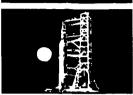
SPACE

















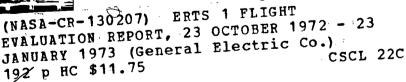


Prepared By
GE ERTS OPERATIONS CONTROL CENTER

For

NATIONAL AERONAUTICS AND SPACE ADMINISTRATION
Goddard Space Flight Center
Greenbelt, Maryland 20771







N73-22818

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GENERAL 🍪 ELECTRIC

ERTS 1 FLIGHT EVALUATION REPORT 23 OCTOBER 1972 TO 23 JANUARY 1973

Prepared By
GE ERTS OPERATIONS CONTROL CENTER

For NATIONAL AERONAUTICS AND SPACE ADMINISTRATION Goddard Space Flight Center Greenbelt, Maryland 20771

Contract NAS5-21808

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INTRODUCTION

This is the third in a series of documents issued periodically to present flight performance analysis of the ERTS-1 Spacecraft. The first, ERTS-1 Launch and Flight Activation Evaluation Report dated 18 October 1972 (72SD4255), gives a summary of each subsystem, the spacecraft configuration, a table of command matrix, telemetry matrix and the launch configuration. The second ERTS-1 Flight Evaluation Report dated 28 November 1972 (72SD4262) covers the period from July 23 to October 23, 1972.

This report contains analyses of performance for the second three months of operation, i.e., orbits 1300 to 2600.

Future ERTS-1 reports are scheduled on a quarterly basis.

SECTION 1

SUMMARY - ORBITS 1300-2600

The ERTS-1 spacecraft was launched from the Western Test Range on 23 July 1972 at 18:06:06.508Z. The launch and orbital injection phase of the space flight were nominal and deployment of the spacecraft followed predictions. Orbital operations of the spacecraft and payload subsystems were satisfactory through Orbit 147 after which a power transient disabled one of the Wideband Video Tape Recorders. Operations resumed until Orbit 196 when the Return Beam Vidicon failed to respond when commanded off. The RBV was commanded off via alternate commands and since that time ERTS-1 has performed its mission with the Multispectral Scanner and the remaining Wideband Video Tape Recorder providing image data.

ORBITAL PARAMETERS

The launch and injection of ERTS-1 required some correction at Orbit 44 and 59 to achieve the desired 18-day repeat cycle. These corrections were made as noted in Section 7. During Orbit 938 it was necessary to execute a 12.8 second burn and in Orbit 2416 a 20.4 second burn of the -X thruster to maintain the ground trace in the desired 18-day repeat pattern of \pm 10 miles.

POWER SUBSYSTEM

The power subsystem performed well throughout this report period. Solar array current has been following close to prediction. Data from this period shows the array degradation to be slightly higher than projected but the power subsystem will meet ERTS-1 power requirements through all of 1973. Battery temperature spread increased but performance of each battery remained good.

ATTITUDE CONTROL SUBSYSTEM

From the initial acquisition, the ACS performance has been excellent. All functions are active and well within specifications. Perturbations due to sun glint in the IR horizon scanners are not disruptive enough to necessitate single scanner mode. The magnetic moment compensating

assembly corrected the + Roll gating to permit flywheel unloading during darkness when payloads are disabled. Gating frequency leveled off during this period and only six percent of the impulse available at launch has been used. The ACS responded well to orbit adjust maneuvers.

COMMAND/CLOCK SUBSYSTEM

All stored commands have executed and all real time commands except the expected one in approximately 10,000 associated with the logic race in the design. No serious problems have resulted from these few commands failing to execute. A minor anomaly has occurred in Comstor B; cell 12 which on thirteen occasions verified with a delta of 256 seconds change to the desired execute time. Each time, a second try verified correctly. No explanation has yet been found for this condition.

TELEMETRY SUBSYSTEM

The telemetry subsystem has consistently performed in an excellent manner. Memory Section 0,0 has been in use since launch and no alternates have been required. All dropouts have been associated with known link or ground problems.

ORBIT ADJUST SUBSYSTEM

The orbit adjust subsystem has been fired five times, all from the -X thruster. The four second burn gave 60 percent of computed thrust but longer burns gave very near computed thrust. Three firings were for initial correction, two for orbit maintenance.

MAGNETIC MOMENT COMPENSATING ASSEMBLY

The Magnetic Moment Compensating Assembly has been operated six times and performance has been reasonably close to nominal. The hysteresis loop associated with the MMCA requires trial and error after the first charge and dump. The attained performance of the unit is considered excellent. It has held the Pole-Cm values commanded in earlier orbits.

UNIFIED 'S' BAND/PRE-MODULATOR PROCESSOR

The Unified 'S' Band Receiver, Transmitter, and Premodulation Processor have continued to operate satisfactorily, even though telemetry indicates the power output of the 'A' transmitter has dropped to 0.6 watts from its launch value of 1.6 watts, the system still exceeds

the link margin requirements. Transfer to the second 'B' transmitter is not expected to be required until March 1973. No adverse effects have been observed on its performance of telemetry reporting, ranging and relay of DCS messages.

ELECTRICAL INTERFACE SUBSYSTEM

The Auxiliary Processing Unit (APU), Interface Switching Module (ISM), and Power Switching Module (PSM) performed normally in this report period.

THERMAL CONTROL SUBSYSTEM

The thermal subsystem performed normally throughout this report period. Temperatures increased slightly due to increasing sun intensity but had no noticeable effect on operation.

NARROW BAND TAPE RECORDERS

The Narrow Band Tape Recorder Subsystem has continued to operate satisfactorily. Each recorder in turn has operated through its modes of record, standby, playback and off for a total ON time of 2281 hours.

WIDE BAND TELEMETRY SUBSYSTEM

The Wide Band Telemetry Subsystem has continued to operate satisfactorily. Wide Band Power Amplifier No. 2 has been the primary instrument used to transmit MSS data to ground stations, but during the period of the Apollo moon operations, Wide Band Power Amplifier No. 1 was substituted because of more compatible frequencies. No affect on performance was observed.

ATTITUDE MEASUREMENT SENSOR

The AMS continues to function in all respects. Derived values are being used in image processing and effort is continuing to improve correlation relationship between spacecraft attitude, the ACS and the AMS.

WIDE BAND VIDEO TAPE RECORDERS

The Wide Band Video Tape Recorder No. 1 has operated satisfactorily since launch. Wide Band Video Tape Recorder No. 2 failed in Orbit 148. MSS video reproduction, MSS Bit Error Rate, search track, control track and spacecraft time are all nominal.

RETURN BEAM VIDICON

The Return Beam Vidicon Subsystem has been idle since Orbit 196, when its input power supply switching system malfunctioned. The RBV had operated satisfactorily up to that point, photographing 1690 scenes of good quality. The failure was not in the RBV itself, nor was the RBV affected by the failure.

MULTISPECTRAL SCANNER SUBSYSTEM

The Multispectral Scanner Subsystem (MSS) has operated satisfactorily. Since launch, the MSS has imaged 35, 331 scenes, an average of 195 per day, covering an area seven times the total land mass of the earth. The steady decrease of the cal wedge level in Bands 1 and 2 experienced through the first 1200 orbits, has been reversed to a slight rise.

DATA COLLECTION SYSTEM

The Data Collection Subsystem (DCS) continued to operate satisfactorily. The DCS experienced several periods of external interference and one 9-day interval of fewer-than-expected messages received, but returned to normal operations after each incident. 129,750 messages have been received of which over 85% were perfect messages. The number of platforms has risen to 218 and the number of users to 30. 83 platforms have been active in a single orbit and messages have been received on a single orbit without discernible mutual interference, only receiver No. 1 has operated to date.

PAYLOAD OPERATION SUMMARY

Launch through Orbit 2600*

	OPERATIONAL SUMMARY	ORBITAL ON-TIME H M S	SUB- SYSTEM
1,6 1 14.7X1	Total scenes photographed Average scenes per day Total area photographed square nautical mile ON-OFF cycles	13:59:09	RBV
	% Real Time scenes % Recorded scenes		
35, 3 1	Total scenes photographed Average scenes per day Total area photographed square	350:21:57	MSS
307.9X1 3,0	nautical mile ON-OFF cycles		
3,1	% Real Time scenes % Recorded scenes		
129,7 10,3 2	Message received at OCC Non perfect messages Ground platforms identified Ground platforms active/orbit Users Average messages per orbit	4467:06:00	DCS
under	% Record Mode % Playback Mode % Rewind Mode % Standby Mode Minor Frame Sync Error Count: Playback	392:20:56	WBVTR-1
	% USAGE SAME AS WBVTR-1 FAILED IN ORBIT 148/9	9:26:33	WBVTR-2
3	% Real Time Mode % Playback Mode Used in Orbits: 5 thru 196 and 1890 thru 2099 ON-OFF cycles	31:55:09	WPA-1
	% Real Time Mode % Playback Mode Used in Orbits: 5 thru 1889 and	235:54:48	WPA-2
1,60	2100 thru 2600 ON-OFF cycles		

^{*}Test time prior to launch contained in Appendix D. Flight Hardware Operating Time Summary

SECTION 2 ORBITAL PARAMETERS

The ERTS 1 launch and injection was satisfactory and required only a minor orbit adjust to achieve nominal parameters. These adjustments were made in orbit 38, 44 and 59. After several repeat cycles orbit maintenance burns were made in Orbit 938 and again in Orbit 2416.

The orbital parameters are given in Table 2-1. Figure 2-1 shows the subsatellite plot and Figure 2-2 shows the longitude error as a function of time and orbit maintenance burns. Figure 2-3 is a summary of ERTS-1 orbital periods.

Table 2-1. Orbital Parameters

	Element		Planned	25 Oct 1 972	25 Jan 1973
(1)	Apogee	KM	917	917.3	922.3
(2)	Perigee	KM	917	898.1	893.1
(3)	Inclination	deg	99.0919	99.103	99.090
(4)	Semimajor Axis	KM	7,294.662	7,285.850	7,285.865
(5)	Eccentricity		0.0001	0.00132	0.00200
(6)	Anomalistic Period	min	103,341	103.152	103.153
(7)	Nodal Period	min		103.268	103.268
(8)	Argument of Perigee	deg	0	93.721	133.693
(9)	18 day repeat cycle	NM	<u>±</u> 5	+1.25	+2.72

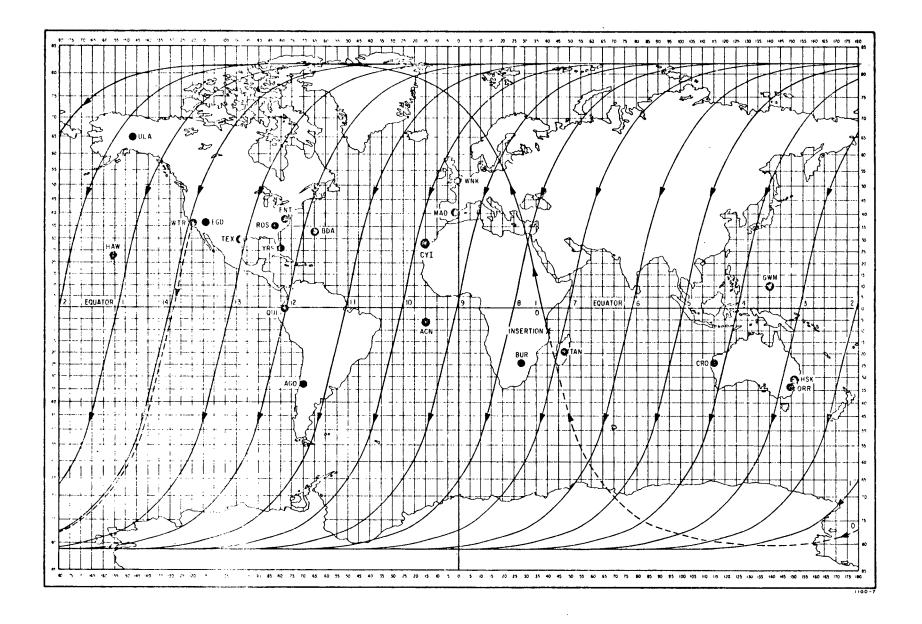
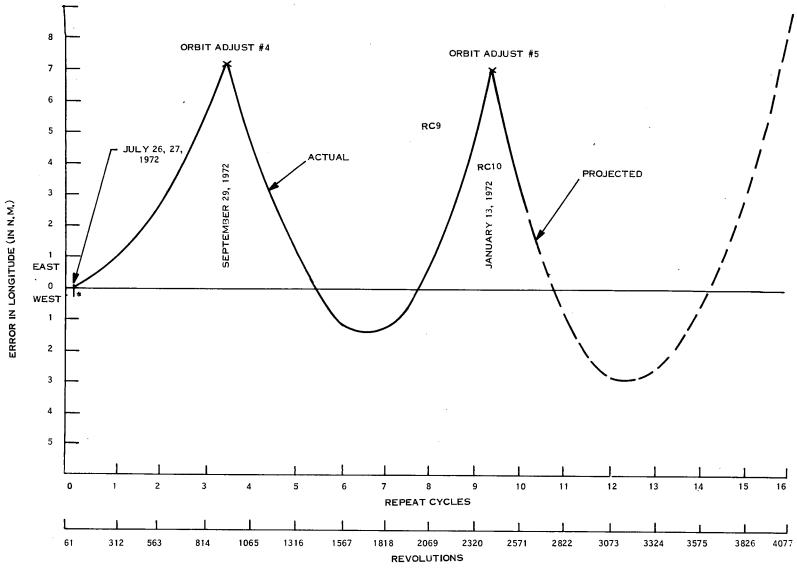


Figure 2-1. Typical Subsatellite Plot of the ERTS-1 Spacecraft



*ORBIT ADJUST NO'S 1, 2, 3 TO ACHIEVE NOMINAL PARAMETERS RC = REPEAT CYCLE

Figure 2-2. Effects of Orbit Adjust on Ground Track

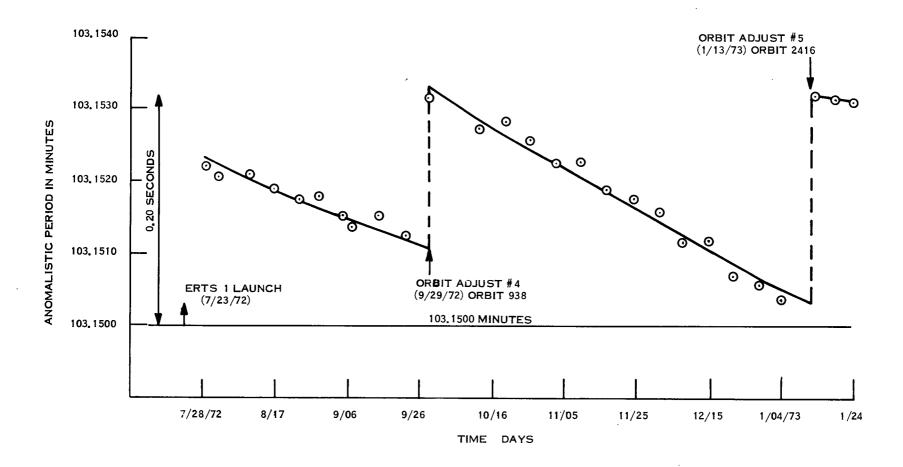


Figure 2-3. ERTS-1 Orbital Period

SECTION 3 POWER SUBSYSTEM (PWR)

The power subsystem continued to perform well.

The solar array provided excess energy for the payload and spacecraft load throughout this report period. Compensation loads and auxiliary loads dissipated the excess power above the battery pack and load requirements using ERTS-1 power management procedures. Midday measured solar array current tracked quite closely to the predicted value and is beginning to decrease as anticipated due to decreasing sun intensity.

Solar Array Degradation is revised (based on data from this report period) to a higher rate of decline and is now predicted to be down 17.1 percent (compared to previous predictions of 13.6 percent) at the end of one year. The power subsystem is predicted to meet the ERTS-1 power requirements through all of 1973. A plot of measured and predicted Midday Solar Current for 1972 and 1973 is shown in Figure 3-1. Figures 3-2 and 3-3 show actual and predicted solar array degradations for 1972 and 1973. Figure 3-4 shows actual and predicted solar paddle sun angle for 1972 and 1973. Figure 3-5 shows seasonal sun intensity variations. In orbits 2298 and 2299, the solar array current dropped to 13.50 and 11.8, respectively from 14.30 amperes near midday as the spacecraft passed through an annular eclipse of the sun.

Battery packs ranged from 9 to 16 percent Depth of Discharge (DOD) with an average of 11 percent over a 24-hour period of normal operation. Temperature spread between battery packs increased to approximately 6.5 °C during this report period due to increasing sun intensity and payload operation. Charge and load sharing were satisfactory. During recovery of normal operation after a station command problem, the batteries discharged to -473 ampere-minutes or 22.5 percent DOD in orbit 1819. The battery voltages were 27.53 volts. Prelaunch battery tests performed on June 24, 1972, show 28.45 volts for 22.5 percent DOD. This decrease in voltage is the combined result of battery degradation and loss of conditioning due to prolonged operation at 9-16 percent DOD. From this data, it is predicted that battery packs will give satisfactory operation through 1973 for the

present MSS payload and WBVTR operation. Table 3-1 shows major power subsystem parameters for typical power management orbits (complete night followed by a complete day).

The power system electronics performed well in this report period with all voltages stable. During orbit 1819, the unregulated bus voltage went to 26.69 volts (lowest flight operation to date); regulator voltages remained stable at their normal values. Table 3-2 shows power subsystem telemetry (average over telemetry period recorded on NBTR) for various orbits. Some parameters in Table 3-2 may be slightly different from Table 3-1 because Table 3-1 uses a time span for power management (night followed by a day) different from the time span used in Table 3-2 which is the playback period from the NBTR. Auxiliary loads are switched each orbit and with the compensation loads dissipate excess array power above that needed by the batteries and loads. Though battery temperature spread is higher, the temperature and battery voltages have been held to satisfactory operating limits. The Shunt Limiter has not operated since orbit 3 because the unregulated voltage has been held below the cut-in voltage by power management.

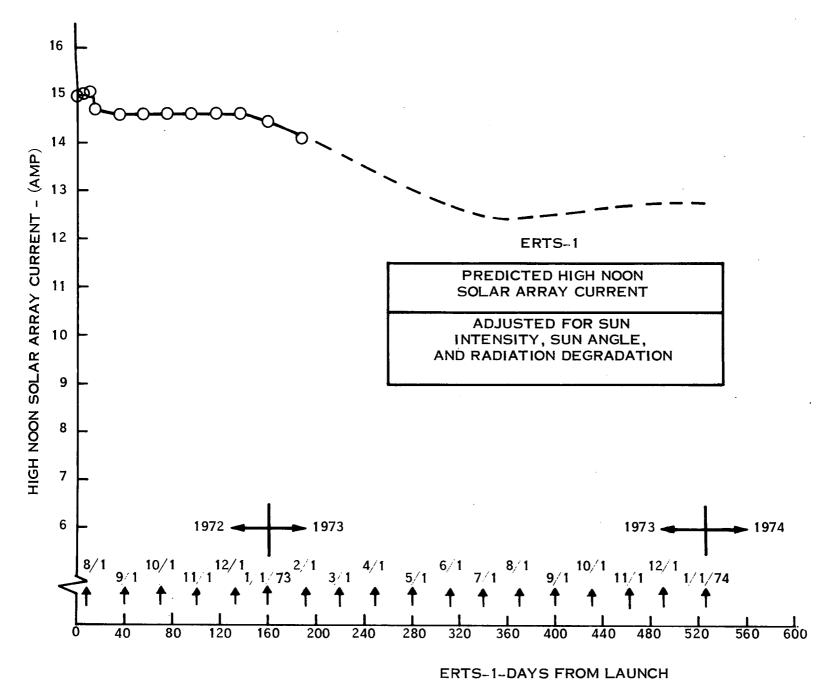


Figure 3-1. Predicted High Noon Solar Array Current

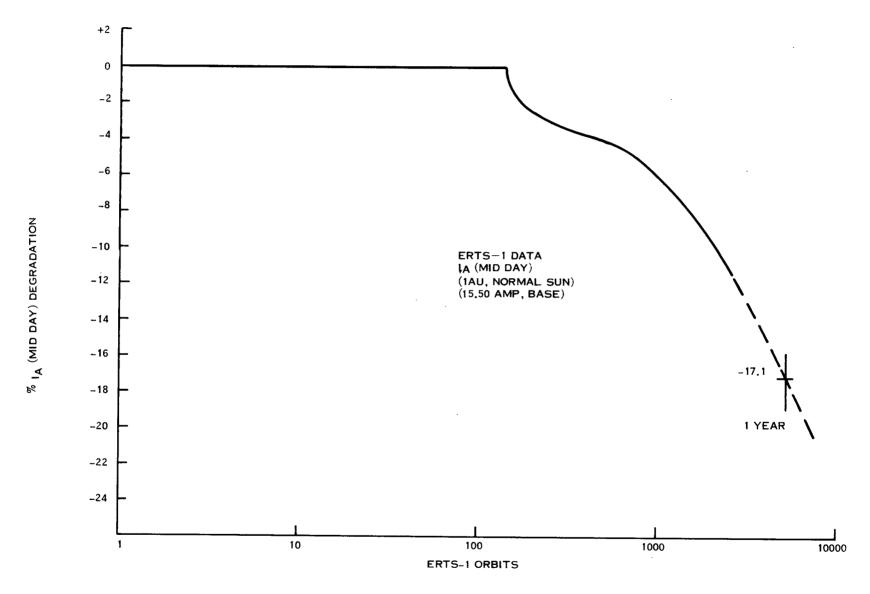


Figure 3-2. I_A (Midday) Degradation vs. Orbits

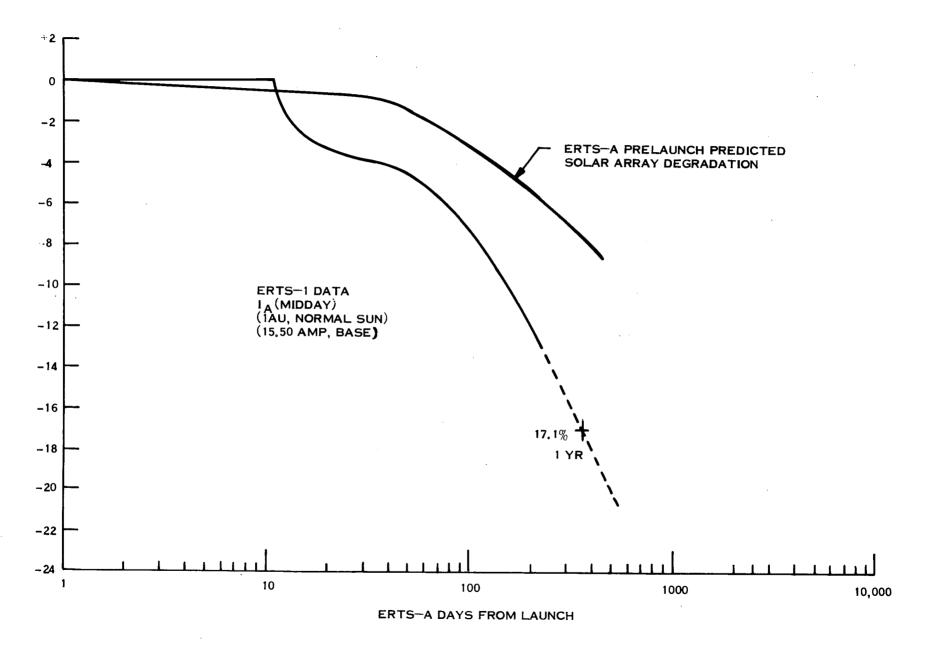


Figure 3-3. I_A (Midday) Degradation vs. Days

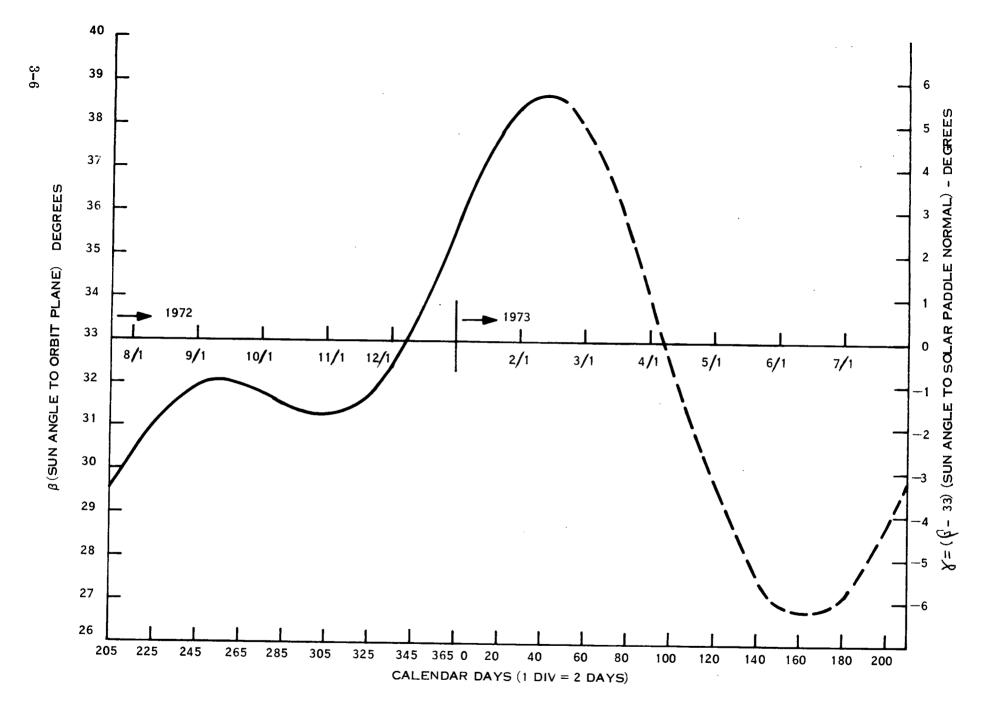


Figure 3-4. Actual and Predicted β and Paddle Sun Angles

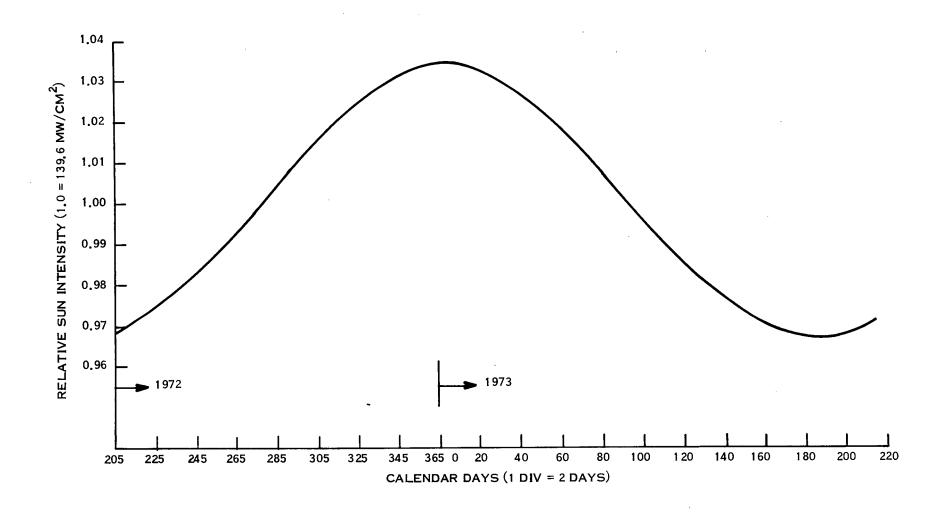


Figure 3-5. Seasonal Solar Intensity Variation

Table 3-1. Major Power Subsystems Parameters

	Orbit No.	7	26	500	899	1291	1799	2198	2600
Batt	1 Max	32.91	32.48	32,99	32, 91	22.00	 		
Date	2 Chge	32.91	32.48	32.99	32.82	32,99	33.08	32.82	32.91
						32,99	33.08	32.82	32.91
		32.91	32, 48	33.08	32.91	32.99	33,16	32.82	32,91
	4	32.91	32.48	33,08	32.91	32.99	33.16	32.82	32.91
	5	32.91	32.48	33.08	32.99	32.08	33.16	32.91	32.99
	6	32.82	32.31	33.08	32.91	32.99	33.16	32.82	32, 91
	7	32.82	32, 22	33.08	32.91	32.99	33.08	32,82	I .
	8	32.82	32.14						32.91
			1	33.08	32.91	32.99	33.16	32.82	32, 91
	Average	32.87	32.38	33.06	32.91	33.00	33.13	32.83	32.92
77-44	1 70.1	00.00					Į		
Batt		29.32	28. 81	29.23	28. 21	28.55	29.32	28.38	28.12
	2 of-	29.32	28.81	29.32	28.30	28.55	29.32	28.38	28.12
	3 Night	29, 23	28. 21	29, 23	28.21	28.55	29.32	28.38	28.04
	4 Volts	29.32	28.89	29.32	28.30	28.55	29.32		1
	5	29.41	28. 29	1				28.38	28.12
				29.32	28.30	28.64	29.41	28.47	28.21
	6	29.23	28. 81	29. 23	28. 21	28.55	29.32	28.38	28.04
	7	29.32	28.89	29, 32	28.30	28.55	29, 32	28.38	28.12
	8	29,23	28.81	29.23	28.21	28.55	29.32	28.38	
	Average		1	1		1	1	1	28.12
	Average	29.30	28.84	29.28	28. 25	28.56	29.33	28.39	28.11
Dott	1 (%	,,,,,						ļ	
Batt		13.51	13.11	13.54	13.12	13.29	13.32	13, 22	13.00
	2 Share	12.80	12.93	12.87	13.17	12.95	13.18	12.94	13.00
	3 (%)	10.82	11.38	11.10	11.55	11.23	11.03	11.28	11.53
	4	12.34	12.39	12.21	1			J.	1
					12.32	12.29	12.20	12.25	12.13
	5	12.36	12.32	12.33	12.25	12.30	12.38	12.21	12.41
1	6	12.77	12.80	12.66	12.64	12.74	12.75	12.70	12.82
	7	13.01	12.62	12.88	12.65	12.83	12.85	12.03	
	8	12.39	12.45	12.41	•			l .	12.66
	•	14.00	12.40	12.41	12.31	12.36	12, 27	12.58	12.45
Batt :	1 Load	12.81	12.71	1,2.55	10.50	10.00	١	1	1
				12.67	12.70	12.68	12.66	12.72	12.61
	2 Share	13.20	12.90	13.47	13.37	13.71	13.78	13.47	13.43
	3 (%)	11.38	11.43	11.84	11.87	12.09	12.08	11.86	12.11
	4	12.75	12.77	12.95	12.71				1
	5					12.89	12.98	12.76	12.88
		12.37	12.54	12.17	12.31	12.32	12.28	12.39	12, 29
	6	12.59	12,53	12.47	12.45	12, 24	12.16	12.36	12.29
,	7	12.84	12.80	12.50	12.41	12.33	12.33	12,53	12.27
	8	12.06	12.32	11.93	12.17	11.74	11.73	11.90	12, 12
							11	11.00	12.12
Batt :	1 Temp	22.15	21.11	24.02	24.19	24.63	04.40	04.04	
							24.46	24.61	25.13
		19.27	18.74	20.53	21.92	21.37	21.35	21.39	22.33
	3 (°C)	19.14	18.77	19.85	20.49	20.36	20.25	20.33	20.72
4	4	22.14	21.57	22.88	22.75	23.41	23, 49	23.23	23.23
	5	22.86	21.02	24.17	24.15			6	
	6					24.67	25.28	25.49	26.77
		22.38	21.21	24.00	24.15	24.98	25, 41	25.70	26.95
	7	22.80	21.41	24.76	24.85	25.64	25, 83	26.07	27.18
8	8	22.99	21.82	24,92	25.11	25.67	25.67	25.96	26.68
1	Average	21.72	20.81	23.14	23.45	23.84	23.97	24.10	24.87
	ĭ				20, 10	20.01	20.51	24.10	24.01
S/ Re	g Ring	167.9	176.8	184.5	170 =	160 0	100 0	150 5	100 0
, 100	'5 ****B	101.9	110.8	104.0	179.5	168.0	163.6	159.7	182.3
Co	I and David Str.		40 -					i	
	Load Part (W)	49.0	49.0	49.0	41.8	41.8	34.8	34.8	34.8
(P/US	C Reg Bus)		i						
	ŀ								
P/L R	eg Bus Pwr (W)	8.1	16, 2	12.0	31.9	19.6	12.2	17.0	36.1
	- ', '					10.0	12.2	11.0	99.1
C/D R	atio	1.41	1.06	1 10	1 40				
O, D 10	4.10	1.41	1.06	1.15	1.10	1.17	1.25	1.07	1.08
m-t-1 1	a		<u></u>						
rotai (Charge (A-M)	327.8	309.2	282.3	343.0	296.8	267.22	285.64	353.85
		l			 				
Total I	Discharge (A-M)	232.6	290.9	245.2	312.9	253.6	214.21	267.40	327.08
					 				
Solar A	Array (A-M)	1058	1044	1034	1040	1033	1034	1038	1028
	,	l						2330	
S.A. P	Peak I (A)	15.8	15.8	15.45	15.45	15.36	15.45	15.36	15.10
		- 1				20.00	10.40	20.00	10.10
Beta L	ogic (DES)	-3.40	-3, 33	-1.17	-1.10	_1 es	_0.65	ne	45 15
	~ ` -/		0,00	4.11	-1.10	-1.65	-0.65	+2.25	+5.15
Max P	Pad Temp (°C)	+65.0	465.0	460 ^	1c0 0				
max K	- au remp (C)	100.0	+65.0	+68.0	+69.0	+71.0	+72.00	+72.00	71.00
M: -	D-150 0- 1					l			
Min R	Pad Temp (°C)	-59.0	-62.0	59.0	-58.0	-58.0	-59.00	-57.00	-56.00
	_	[.			
Max L	Pad Temp (OC)	+56.1	+57.9	+60.5	+61.4	+65.0	+66.00	+67.00	466 00
	• • • • • • • • • • • • • • • • • • • •	· i					.00.00	101,00	+66.00
	^	ı	i		l			i	
Min L	Pad Temp (OC)	-66.0	-67.0	-66.0	-64.0	-64.0	-65.00	-62.00	-60.00

Table 3-2. Power Subsystem Analog Telemetry (Average Value for Frames of Data Received in NBTR Playback)

Participo Description Unit Orbit 2 Orbit 20		· · · · · · · · · · · · · · · · · · ·	т			0.14.500	Orbit 899	Orbit 1291	1799	2201	2600
George G	Function	Description	Unit	Orbit 7	Orbit 26	Orbit 500					1.23
Control Cont	6001		Amp						1		1.29
Google G	1		1 !				· .				1.17
0006)		1								1.23
60015											1.19
0.94	1]]								1.20
00007 00007 0.98 0.91 0.93 0.94 0.90 0.76 0.96 0.96 0.96 0.96 0.96 0.97 0.97 0.96 0.97 0.96 0.97 0.96 0.97 0.96 0.97		i I									1.19
Course		1 1	1				1				1.18
Main			. VIDC							0.54	0.71
0012 2			VDC				,			0.54	0.71
SOLIA SOLI				1						0.48	0.63
0015										0.50	0.66
0015 0016 0017 0018 0017 0018								0.54	0.53	0.51	0.68
0011			-				1	0.55	0.56	0.53	0.70
Boil		1					0.69	0.56	0.55	0.52	0.70
Second Bat Volt VDC 31.61 30.87 31.40 30.94 31.28 31.17 31.23 31.60 31.62 30.87 31.41 30.94 31.28 31.17 31.22 31.60 31.62 30.87 31.41 30.94 31.28 31.17 31.22 31.60 31.60 31.60 30.87 31.41 30.94 31.28 31.17 31.22 31.60 31.60 31.60 30.87 31.41 30.94 31.29 31.17 31.23 31.20 31.25 31.60 31.60 30.86 31.39 30.97 31.36 31.25 31.31 31.25 31.31 31.25 31.30 31.25 31.30 31.25 31.30 31.25 31.30 31.60 30.86 31.30 30.92 31.27 31.15 31.21 31.25 31.30 31.25 31.25			1				0.67	0.54	0.52	0.51	0.69
6022 2 2 3 3.62 30.87 31.41 30.94 31.28 31.17 31.23 3 6024 4 4 30.97 31.32 31.20 31.25 31.17 31.23 3 6025 5 5 31.69 30.90 31.44 30.97 31.32 31.20 31.25 31.31 60.26 6 6 31.69 30.86 31.39 30.92 31.27 31.32 31.20 31.25 6027 7 7 31.62 30.99 31.42 30.96 31.30 31.18 31.25 6028 8 8 7 31.63 30.89 31.42 30.96 31.30 31.18 31.25 6031 Bat 1 Temp DGC 22.49 21.17 22.89 24.18 24.61 24.88 24.44 31.05 31.06 31.30 31.18 31.25 6033 3 3 60.89 31.42 30.96 31.30 31.18 31.25 6033 3 3 60.89 31.42 30.96 31.30 31.18 31.25 6033 3 3 60.89 31.42 30.96 31.30 31.18 31.25 6033 3 3 60.89 31.42 30.96 31.30 31.18 31.25 6033 3 3 60.89 31.42 30.96 31.30 31.18 31.25 6033 3 3 60.89 31.42 30.96 31.30 31.18 31.25 6033 3 60.89 31.42 30.96 31.30 31.18 31.25 6033 3 60.89 31.42 30.96 31.30 31.18 31.25 6033 3 60.89 31.42 30.96 31.30 31.18 31.25 6033 60.89 31.42 30.96 31.30 31.18 31.25 6033 60.89 31.42 30.98 24.18 24.61 24.68 24.44 24.61 24.68 22.45 21.57 22.45 21.57 22.45 21.57 22.77 22.89 24.19 24.46 25.67 20.30 20.37 20.20 30 60.35 6 6 22.55 22.45 21.57 22.77 22.77 22.73 23.41 23.67 23.14 23.34 24.67 24.67 24.67 25.67 25.99 26.08 27.67 25.91 25.60 25.57 25.99 24.14 24.99 25.47 25.70 26.08 27.14 24.67 24.67 24.67 24.67 24.67 25.67 25.91 26.08	1		voc				30.94	31.28	31.17	31.23	30.74
6023 3 31,62 30,87 31,44 30,94 31,29 31,17 31,25 31,60 30,95 31,68 30,95 31,48 31,02 31,36 31,25 31,31 31,26 31,69 30,95 31,48 31,02 31,36 31,25 31,31 31,27 31,15 31,21 31,26 31,60 30,95 31,48 31,02 31,36 31,25 31,31 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,27 31,15 31,21 31,25 31,31 31,27 31,27 31,15 31,21 31,25 31,31 31,27 31,27 31,15 31,21 31,25 31,31 31,27 31,27 31,15 31,21 31,25 31,31 31,27 31,27 31,31 31,27 3	1	1	Ĩ				30.94	31.28	31.17		30.74
6024 4	1					31.41	30.94	31.29	31.17	31.23	30.74
Second Column Second Colum				l .		l	30.97				30.77
6025 6 6 7 7 31.60 30.86 31.39 30.92 31.27 31.15 31.21 5 6028 8 8 31.60 30.89 31.42 30.96 31.30 31.18 31.25 5 6028 8 8 31.30 30.89 31.42 30.96 31.30 31.18 31.25 5 31.62 30.89 31.42 30.96 31.30 31.18 31.25 5 31.62 5 30.89 31.42 30.96 31.30 31.18 31.25 5 31.62 5 30.89 31.42 30.96 31.30 31.18 31.25 5 31.62 5 30.89 31.42 30.96 31.30 31.18 31.25 5 31.62 5 31.62 5 31.62 5 31.62 5 31.62 5 31.42 5 31.6						1	31.02				30.82
Section Sect				1 1		31.39	30.92	31.27	31.15		30.72
Second S	1			1 1		31.42	30.96	31.30	31.18	1	30.76
Bat I Temp DGC 22.49 21.17 23.89 24.18 24.61 24.58 24.44 21.33 3 3 3 3 3 3 3 3 3		!	↓			31.42	30.96	31.30	31.18		30.75
19.54 18.80 20.46 21.91 21.36 21.48 21.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.36 20.37 20.20 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.36 20.37 20.20 20.36 20.37 20.20 20.37 20.2			DGC			23.89	24.18	24.61		ı	25.19
19.36						20.46	21.91			ı	22.44
Color	1		l i		18.76	19.82	20.50	20.36		1	20.80
6035 6 6 22.3 0 9 21.84 24.10 24.09 24.64 25.57 25.39 26.08 6037 7 7 22.3 10 21.43 24.67 24.87 25.67 25.91 26.08 6037 7 7 23.10 21.43 24.67 24.87 25.67 25.91 26.08 6037 8 Pad V N VDC 34.47 33.40 34.12 33.42 33.96 33.84 33.71 6042 R Pad V N VDC 34.48 33.29 33.67 32.89 33.59 33.31 32.60 6046 L Pad V G VDC 34.48 33.29 33.67 32.89 33.59 33.31 32.60 6045 L Pad V G VDC 34.74 33.69 34.41 33.70 34.26 34.18 34.06 6046 L Pad V G VDC 34.74 33.69 34.41 33.70 34.26 34.18 34.06 6050 8/C Rg Bus V VDC 24.54 24.54 24.54 24.54 24.55 24.54 24.55 24.54 24.55 6052 Aux Reg A V VDC 23.41 23.41 23.41 23.50 23.50 23.50 23.50 23.50 23.50 23.50 6056 8/C Rg Bus I Amp 6.86 7.11 6.99 7.17 6.86 6.69 6.54 6.6					21.57	22.77	22.73	23.41		ı	23.20
6036 6 6 7 7 23.10 21.43 24.67 24.87 25.67 25.91 25.00 25.08 8 8 7 23.26 21.86 24.81 25.10 25.66 25.75 25.89 6040 RT Pad Temp DGC 25.94 25.82 27.12 28.00 30.33 24.21 33.69 6041 R Pad V N VDC 34.47 33.40 34.12 33.42 33.96 33.84 33.71 32.60 6041 R Pad V N VDC 34.28 33.29 33.67 32.89 33.59 33.31 32.60 6044 Lt Pad Temp DGC 14.03 14.14 16.10 17.34 19.50 15.11 20.90 34.79 33.68 14.14 16.10 17.34 19.50 15.11 20.90 34.79 33.68 34.45 33.70 34.26 34.18 34.06 6046 L Pad V F VDC 34.74 33.69 34.41 33.70 34.26 34.18 34.10 6055 S/C Rg Bus V VDC 24.54 24.54 24.54 24.54 24.55 24.54 24.55 6052 Aux Reg A V VDC 23.41 23.41 23.50 23.47 23.47 23.49 23.48 6055 S/C Rg Bus I Amp 6.86 7.11 6.99 7.17 6.85 6.69 6.54 6.69 6.	1		l i	I	21.84	24.10	. 24.09	24.64		l .	26.86
Court Cour					21.24	23.93	24.14				26.99
8 6040 RT Pad Temp DGC 25.94 25.82 27.12 28.00 30.33 24.21 33.69 6041 RP Pad V N VDC 34.47 33.40 34.12 33.42 33.96 33.84 33.71 6042 R Pad V M VDC 34.28 33.29 33.67 32.89 33.59 33.31 32.60 14.03 14.14 16.10 17.34 19.50 15.11 20.90 16.045 14.Pad Temp DGC 14.03 14.14 16.10 17.34 19.50 34.26 34.18 34.06 6046 LP Pad V F VDC 34.79 33.68 34.45 33.72 34.27 34.18 34.06 6050 S/C Ur Bus V VDC 34.79 33.68 34.45 33.72 34.27 34.18 34.10 35.60 15.50				3	21.43	24.67	24.87			1	27.20
RT Pad Temp		i	l 👃		21.86	24.81	25.10			1	26.75
R Pad V N VDC 34.47 33.40 34.12 33.42 33.96 33.84 33.71 6042 R Pad V M VDC 34.28 33.29 33.67 32.89 33.59 33.31 32.60 6044 Lt Pad Temp DGC 14.03 14.14 16.10 17.34 19.50 15.11 20.90 6045 L Pad V F VDC 34.74 33.69 34.41 33.70 34.26 34.18 34.06 6046 L Pad V G VDC 34.79 33.68 34.45 33.72 34.27 34.18 34.10 6050 S/C Ur Bus V VDC 32.05 31.24 31.80 31.29 31.69 31.37 31.73 31.73 6051 S/C Rg Bus V VDC 24.54 24.54 24.54 24.55 24.54 24.55 23.47 23.47 23.47 23.48 23.50 23.5		1	DGC		25.82	27.12				i .	27.98
R Pad V M VDC 34, 28 33, 29 33, 67 32, 89 33, 51 32, 00 004 004 004 005 006				34.47	33.40	34.12	33.42			1	33.01
Bod44	1		VDC	34.28	33.29	33.67	32.89			l .	32.43
Control Cont				14.03	14.14	16.10					18.56
G046 L Pad V G VDC 34.79 33.68 34.45 33.72 34.27 34.18 34.10 31.37 31.73 31.73 31.73 31.73 31.69 31.37 31.37 31.73 31.	1		VDC	34.74	33.69	34.41			t .	i	33.71
S/C ur Bus V VDC 32.05 31.24 31.80 31.29 31.69 31.37 31.15 31.69 35.37 31.15 31.69 35.67 31.69 35.67 31.69 35.67 31.69 35.67 31.69 35.67 31.69 35.67 32.45 3			VDC	34.79	33.68	34.45			1	1	33.73
S/C Rg Bus V VDC 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 24.54 23.47 23.47 23.47 23.48 23.48 23.48 23.48 23.48 23.48 23.48 23.48 23.48 23.48 23.48 23.48 23.48 23.48 23.48 23.48 23.47 23.49 23.48 23.48 23.48 23.48 23.47 23.49 23.48 23.48 23.47 23.49 23.48 23.48 23.47 23.49 23.48 23.48 23.48 23.47 23.49 23.48 23.48 23.50		S/C Ur Bus V	VDC	32.05	31.24	31.80		1			31.03
Aux Reg A V VDC 23.41 23.50	3	S/C Rg Bus V	VDC	24.54	24.54		1				24.54
Aux Reg B V VDC 23.50 23.51		Aux Reg A V	VDC	23.41						1	23.46
6054 Solar I Amp 6.86 7.11 6.99 7.17 6.86 6.69 6.54 6.69 6.54 6.6056 S/C Rg Bus I Amp 6.86 7.11 6.98 7.17 6.85 6.69 6.54 6.54 6.0058 PC Mod T1 DGC 21.83 21.82 22.35 23.21 22.81 22.63 22.55 6.0059 PC Mod T2 DGC 21.63 21.68 22.25 22.91 22.74 22.73 22.61 6.0070 P/L Rg Bus V VDC 24.67 24.66 24.68 24.67 24.68 24.66 24.69 24.69 6.0071 P/L Ur Bus V VDC 31.90 31.08 31.05 31.15 31.54 31.22 31.57 6.0072 P/L Rg Bus I Amp 0.33 0.57 0.41 1.13 0.79 0.50 0.69 6.0073 PAux A V VDC 23.50 23.51	6053	Aux Reg B V	VDC	23.50		1	1			1	23.50 13.97
6055	6054	Solar I	Amp	14.77	i		1	1		1	
S/C Rg Bus I Amp 6.86 7.11 6.98 7.17 6.85 6.69 6.54 OSS PC Mod T1 DGC 21.83 21.82 22.35 23.21 22.81 22.63 22.55 OSS PC Mod T2 DGC 21.63 21.68 22.25 22.91 22.74 22.73 22.61 OSS P/L Rg Bus V VDC 24.67 24.66 24.68 24.67 24.68 24.66 24.69 OSS P/L Rg Bus I Amp 0.33 0.57 0.41 1.13 0.79 0.50 0.69 OSS P/L Rg Bus I Amp 0.33 0.57 0.41 1.13 0.79 0.50 0.69 OSS PAUX A V VDC 23.50 23.51 23.51 23.53 23.52 23.51 23.51 OSS PAUX B V VDC 23.50 23.51 23.51 23.53 23.52 23.51 23.51 OSS Pr Mod T1 DGC 21.52 21.50 22.38 24.00 23.15 23.24 23.28 OSS Pr Mod T2 DGC 20.38 20.34 20.88 22.07 21.47 21.62 21.56 OSS Pr Mod T2 DGC 24.56 24.56 24.58		S/C Rg Bus I	Amp						1		7.45 7.46
Company		S/C Rg Bus I			1					I	23.53
6059 P/L Rg Bus V VDC 24.67 24.66 24.68 24.67 24.68 24.66 24.69 P/L Rg Bus V VDC 31.90 31.08 31.65 31.15 31.54 31.22 31.57 31.57 6072 P/L Rg Bus I Amp 0.33 0.57 0.41 1.13 0.79 0.50 0.69 6073 P Aux A V VDC 23.50 23.51 23.51 23.51 23.53 23.52 23.51 23.51 6074 P Aux B V VDC 23.50 23.51 23.51 23.51 23.55 23.51 23.51 6074 P Aux B V VDC 23.50 23.51 23.51 23.51 23.55 23.52 23.51 23.51 6075 Pr Mod T1 DGC 21.52 21.50 22.38 24.00 23.15 23.24 23.28 6076 Pr Mod T2 DGC 20.38 20.34 20.88 22.07 21.47 21.62 21.56 6079 Fuse Blow V VDC 24.56 24.56 24.58	6058	l .		1		1					23.08
6070 P/L Ur Bus V VDC 31.90 31.08 31.65 31.15 31.54 31.22 31.57 6072 P/L Rg Bus I Amp 0.33 0.57 0.41 1.13 0.79 0.50 0.69 6073 P Aux A V VDC 23.50 23.51 23.51 23.51 23.53 23.52 23.51 23.51 6074 P Aux B V VDC 23.50 23.51 23.51 23.51 23.53 23.52 23.51 23.51 6075 Pr Mod Tl DGC 21.52 21.50 22.38 24.00 23.15 23.24 23.24 23.28 6076 Pr Mod T2 DGC 20.38 20.34 20.88 22.07 21.47 21.62 21.56 6079 Fuse Blow V VDC 24.56 24.56 24.58 Fuse Blow V VDC 24.56 24.56 24.58 6083 4 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0	6059	l		1			1		1	1	24.67
6071 P/L Ur Bus V Amp 0.33 0.57 0.41 1.13 0.79 0.50 0.69 6072 P/L Rg Bus I Amp 0.33 0.57 0.41 1.13 0.79 0.50 0.69 6073 P Aux A V VDC 23.50 23.51 23.51 23.53 23.52 23.51 23.51 6074 P Aux B V VDC 23.50 23.51 23.51 23.53 23.52 23.51 23.51 6075 Pr Mod T1 DGC 21.52 21.50 22.38 24.00 23.15 23.24 23.28 6076 Pr Mod T2 DGC 20.38 20.34 20.88 22.07 21.47 21.62 21.56 6079 Fuse Blow V VDC 24.56 24.56 24.58 - - - - 6080 Shunt 1 I Amp 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.00<	6070				1	1)	1	1	30.88
6072 P/L Rg Bus 1 Amp 0.53 23.51 23.51 23.53 23.52 23.51 23.51 23.51 23.51 23.53 23.52 23.51	6071		1	1	ł.				I.	1	1.47
6073 PAIX A V VDC 23.50 23.51 23.51 23.52 23.51 23.51 23.53 23.52 23.51 23.51 23.53 23.53 23.52 23.51 23.51 23.51 23.51 23.51 23.24 23.28 23.24 23.28 23.28 23.24 23.28 23.51 23.24 23.28 23.24 23.28 23.51 23.24 23.28 23.24 23.28 23.51 23.51 23.51 23.51 23.51 23.24 23.28 23.24 23.24 23.28 23.51 23.51 23.51 23.51 23.51 23.51 23.51 23.51 23.24 23.28 23.24 23.28 23.24 23.28 23.24 23.28 23.24 23.28 23.24 23.28 23.24 23.28 23.24 23.28 24.56 24.56 24.56 24.56 24.56 24.56 24.56 24.56 24.56 24.56 24.56 24.56 24.56 24.56 24.56 24.56 <td< td=""><td>6072</td><td></td><td></td><td></td><td></td><td></td><td></td><td></td><td>1</td><td>1</td><td>23.53</td></td<>	6072								1	1	23.53
6074 Pr Mod T1 DGC 21.52 21.50 22.38 24.00 23.15 23.24 23.28 6075 Pr Mod T2 DGC 20.38 20.34 20.88 22.07 21.47 21.62 21.56 6079 Fuse Blow V VDC 24.56 24.56 24.58	6073		1	L					1	1	23.53
6075 Pr Mod T2 DGC 20.38 20.34 20.88 22.07 21.47 21.62 21.56 6079 Fuse Blow V VDC 24.56 24.56 24.58	6074		1		1		1	1	1	1	24.40
6076 Fr Mod 12 Pr Mod 12 Poc 24.56 24.56 24.58	6075			1							22.31
6079 Fuse Blow V Shurt 1 I Amp 0.00 0.00 0.00 0.00 0.00 0.00 0.00 0.	6076						1			1	
6080 Shuff 1 Amp 0.00	6079)	1				1	l .	1		0.00
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	6080		Amp	L	1	1		1	1	I.	0.00
$ \begin{bmatrix} 6082 \\ 6083 \\ 6084 \\ 6085 \end{bmatrix} \begin{bmatrix} 3 \\ 4 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.$	6081			1					I	1	0.00
$\begin{bmatrix} 6083 \\ 6084 \\ 6085 \end{bmatrix} \begin{bmatrix} 4 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix} \begin{bmatrix} 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \\ 0.00 \end{bmatrix}$	l l		1 1			1			I .	1	0.00
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	· ·	h		T .		1	0.00	0.00	0.00	0.00	0.00
6086	6086		1 1		l .	1		1			0.00
6087 8 0.00 0.50 0.41 1.12 0.79 0.49 0.69		1	.▼		1		1			1	1.47
6100 P/L Rg Bus 1 Amp 0.55 0.50 752 394 390 520 610		1		1						1	425
Total No. Major Frames FRM 385 764 783 394 390 320 610	Total No.	Major Frames	rKM	989	104	100		L	<u> </u>		L

SECTION 4

ATTITUDE CONTROL SUBSYSTEM (ACS)

Performance of the Attitude Control Subsystem has been excellent throughout the launch and orbital operations.

Gating for the ACS has been as noted in Figure 4-1 and Tables 4-1 and 4-2. (Figure 4-2, Early Gate History, is repeated for convenience). The small increase in number of gates/orbit has ceased and the slope of the curve seems to be decreasing slightly. There appears to be a long-term correlation with seasons and beta angle and some short-term correlation with payload (especially the Wideband Video Tape Recorder) operations. These phenomenon are continuing to be studied.

Performance dynamics for the ACS during the orbit adjust in orbit 2416 is shown in Section 7.

ACS components have operated in a satisfactory manner throughout this period. Minor variations have been investigated but no specific problems found. An example is the slight increase (from 2% average to 5% average) in the Yaw Motor Drive duty cycle around orbit 1870, which lasted for several days. (See Figure 4-3.) A smaller excursion in the roll drive duty cycle was noted in orbit 1890 but returned to normal after several orbits. Near orbit 2150 the pitch drive duty cycle increased sharply to a peak of 50% duty cycle (see Figure 4-4), but returned to normal after fifteen (15) orbits. These unexplained data are being further investigated.

During preparation for the orbit maintenance burn in orbit 2416 RMP No. 1 was turned on and checked for performance. The identical outputs for RMP No. 1 and RMP No. 2 are shown in Figure 7-1. Figure 4-5 shows the dynamics for the RMP No. 1 coastdown after the unit was commanded off.

Figure 4-6 is included to illustrate the SAD motor winding voltages and sun sensor preamp output from a typical early orbit (241) and a recent orbit (2417). Table 4-3 gives typical ACS telemetry values.

Table 4-1. Impulse Useage ERTS-1

			Orbit	,
Item	Units	0/1	1300	2600
Gas				
Remaining (2) Useable	Lbs	12.02	11.63	11.00
Impulse (3)	Lb-Sec	575 . 2	555.7	524.2
Gates	Total			
-Pitch			0	0
+Pitch			475	1431
-Roll			375	1030
+Roll			150	153 (1)
$W = \frac{PV}{CRT}$				

Where:

W = Weight of Freon-14 in lbs

P — Tank pressure in lbs/ft³

V = Tank volume in ft³ (0.272 for ERTS-1)

C = Compressibility factor for Freon-14

R = Universal gas constant (17.55 for Freon-14)

T = Tank temperature degrees Rankine

- (1) 3 + roll gates during orbit adjust (Orbit 2416)
- (2) 0.516 lbs of Freon not useable due to manifold lock up pressure
- (3) Freon-14 specific impulse = 50 lb-sec/lb

Table 4-2. ACS Gates/Orbit

Orbit	+P	-P	+R	-R	Total
0-73	0.425	0	1.19	0	1.62
74-85(1)	0.182	0	0.816	0	1.00
86-110	0.332	0	0.960	0.042	1.33
111-220(2)	0.330	0	0.092	0.238	0.660
221-1300	0.370	0	0.019	0.323	0.710
1301-1950	0.670	0	0	0.508	1.18
1951-2200	0.805	0	0	0.541	1.34
2201-2400	0.813	0	0	0.487	1.30
2401-2600	0.810	0	0	0.476	1.28

⁽¹⁾ Sample too small for accuracy.

NOTE: Yaw gates observed only during preparation for orbit adjust.

⁽²⁾ MMCA adjustments completed at orbit 220.

Table 4-3. ACS Temperature and Pressure Telemetry Summary

		*T/V		Orb	pit	
Function	Units	20 ⁰ C Plateau	31	1799	2201	2600
1084 RMP 1 Gyro Temperature	DGC	79.,0	44.5	24, 12	24. 48	24, 28
1094 RMP 2 Gyro Temperature	DGC	73. 0	74.3	75. 07	75.08	75.07
1222 SAD RT MTR HSING Temp	DGC	28.0	21.1	23, 12	23, 50	23.07
1242 SAD LT MTR HSING Temp	DGC	27.0	27.0	31,74	32.37	32, 27
1223 SAD RT MTR WNDNG Temp	DGC	29, 0	25, 3	27.67	27.87	27.39
1243 SAD LT MTR WNDNG Temp	DGC	29.0	28.7	34, 54	35, 27	34, 99
1228 SAD RT HSG Pressure	PSI	7.57	7.6	7. 59	7.59	7.53
1248 SAD LT HSG Pressure	PSI	6. 91	7.0	7.10	7.07	7.04
1007 FWD Scanner MTR Temp	DGC	17.00	19.8	21.08	21.63	21.35
1016 Rear Scanner MTR Temp	DGC	25,00	20.5	20.88	21.37	21, 25
1003 FWD Scanner Pressure	PSI	4. 80	4. 6	4, 62	4. 49	4, 52
1012 Rear Scanner Pressure	PSI	5. 16 ⁽¹⁾	7.8	7. 95	8.00	8. 05
1212 Gas Tank Pressure	PSI	1810.	1988.	1908.	1886.	1849.
1210 Gas Tank Temperature	DGC	20.0	22.6	25, 53	26. 19	26.07
1213 Manifold Pressure	PSI	57. 53	56.7	56.75	56, 82	57.16
1211 Manifold Temperature	DGC	24.0	21.9	24.99	25.58	25. 51
1059 CLB Power Supply Card Temp	DGC	36.0	37.1	41.80	42,74	42.22
1260 THO1 EBP	DGC	26.0	25. 4	29. 28	29. 81	29.71
1081 RMP 1 MTR Volts	VDC	-30, 13	Off	Off	Off	Off
1082 RMP 1 MTR Current	Amps	0, 11	Off	Off	Off	Off
1080 RMP 1 Supply Volts	VDC	-23, 88	Off	Off	Off	Off
1091 RMP 2 MTR Volts	VDC	-29, 68	-29.7	-29.64	-29.63	-29.63
1092 RMP 2 MTR Current	Amps	0.10	0.10	0.10	0.10	0.10
1090 RMP 2 Supply Volts	VDC	-23, 46	-23.4	-23, 39	-23, 39	-23,38
1220 SAD RT MTR WNDNG Volts	VDC	-5, 0	-4.8	-4.36	-4, 30	-4, 32
1240 SAD LT MTR WNDNG Volts	VDC	-5.2	-4.8	-4.38	-4, 42	-4.12
1227 SAD RT -15 VDC Conv.	VDC	-14, 88	14.9	15, 13	14, 88	14,90
1247 SAD LT -15 VDC Conv.	VDC	-15,12	15, 2	15 . 1 3	15. 1 3	15.15
1056 CLB <u>+</u> 6 VDC	TMV	2, 33	2.4	2, 35	2.35	2.35
1055 CLB <u>+</u> 10 VDC TMV	TMV	2.73	2,75	2.75	2.75	2,75
1057 CLB Power Supply Volts	TMV	2, 77	2.8	2.78	2.79	2.79
1261 THO2 EBP	DGC	23.0	22.9	26.00	26, 69	26, 42
1262 THO3 EBP	DGC	25.0	23.4	24, 90	25, 39	25.09
1263 THO1 STS	DGC	-8.0	-6.8	3, 49	2.70	0.59
1264 THO2 STS	DGC	-11.0	-14.6	-6. 49	-8, 55	-8. 81
1265 THO3 STS	DGC	-12,0	-3, 1	12.04	11, 92	9, 32
1266 THO4 STS	DGC	4.0	-13, 9	1.70	2.18	-2,55
1267 THO5 STS	DGC	-2, 0	-8, 9	7. 89	6, 20	-0.07
1224 SAD R FSST	DGC	28, 0	39.5	-6, 49	53, 20	52, 87
1244 SAD L FSST	DGC	22.0	27.1	43. 87	44. 23	45,64

⁽¹⁾ Scanner S/N FT-3 in thermo-vacuum scanner - S/N FT-6 in flight * Thermal Vacuum Test Data

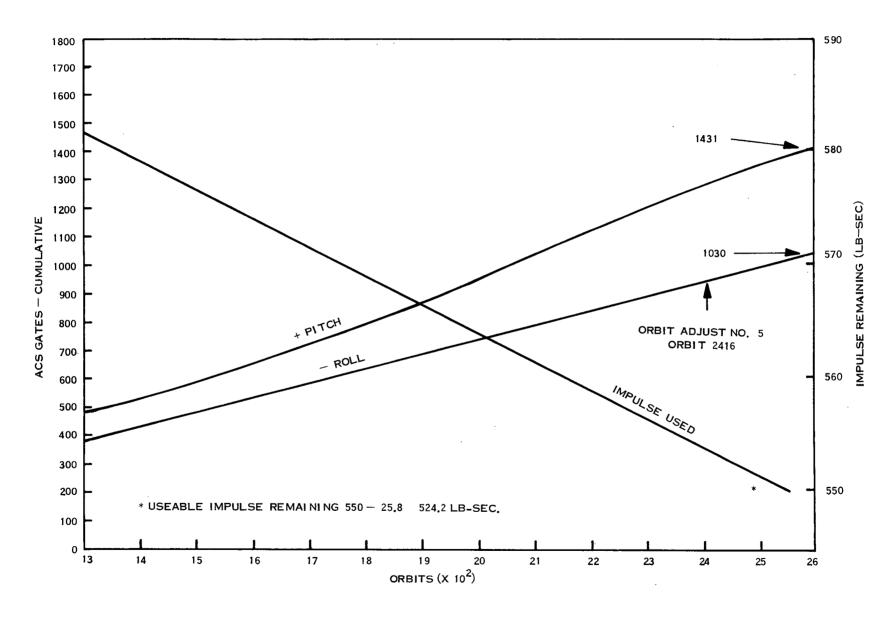


Figure 4-1. Cumulative Gate History ERTS 1

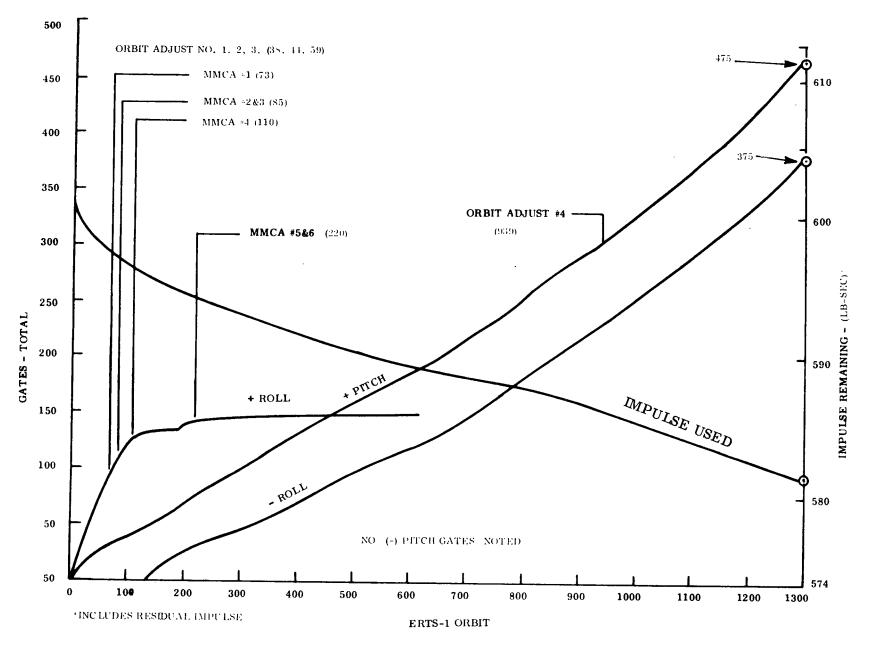


Figure 4-2. Cumulative Gate History ERTS 1

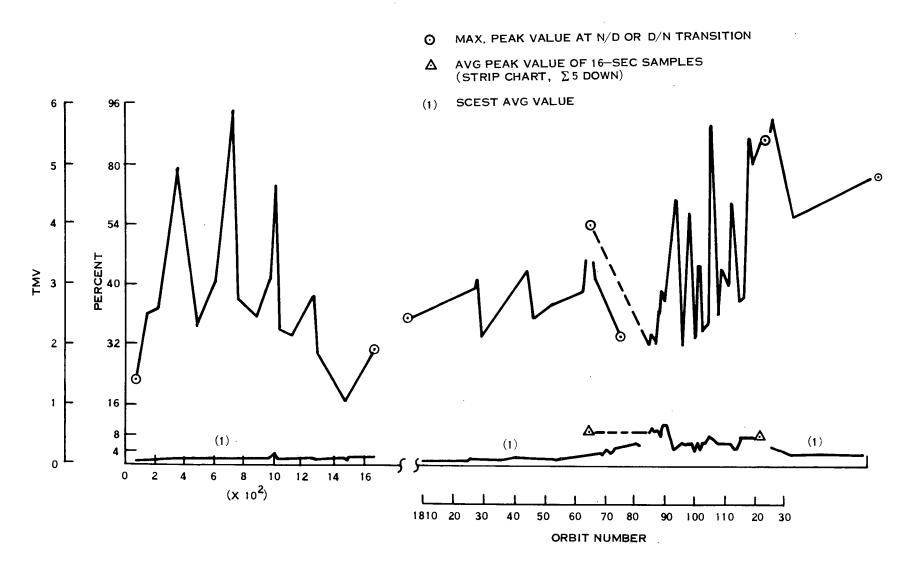


Figure 4-3. Yaw Motor Drive Duty Cycle (Func. 1033/1034)

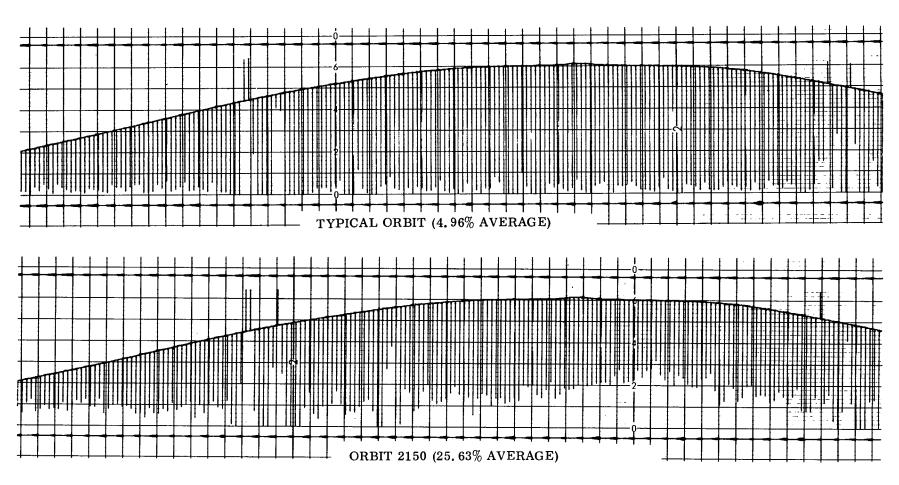


Figure 4-4. Pitch Flywheel Duty Cycle

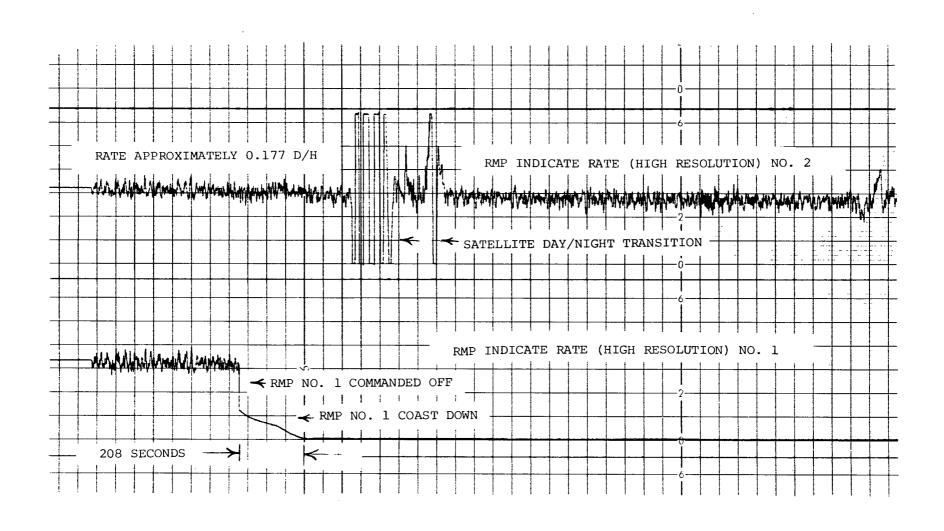


Figure 4-5. RMP No. 1 ("A") Coast Down Test Results (Orbit 2417)

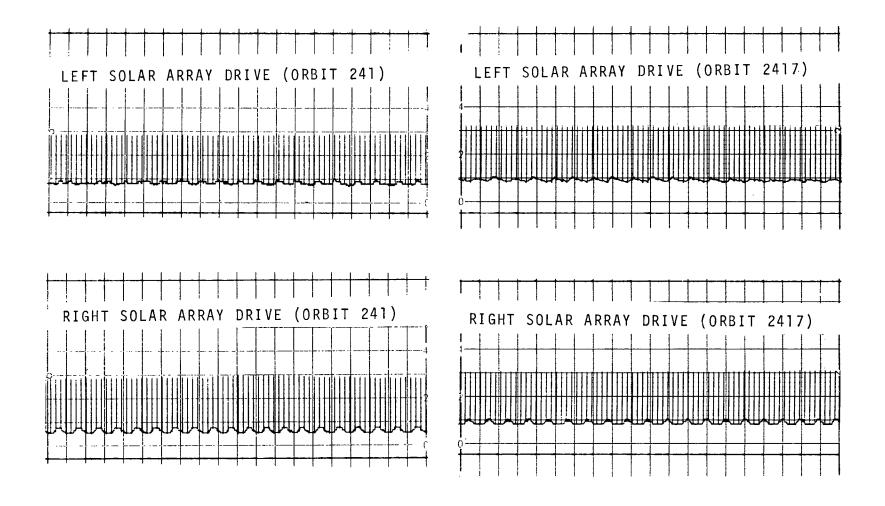


Figure 4-6. SAD Motor Winding Voltages and Sun Sensor Preamp (Typical Early Orbit and Recent Orbit)

COMMAND/CLOCK SUBSYSTEM

Command processing for both real time and stored commands for ERTS-1 has been normal during this period except for one minor problem with one comstor cell which will be noted later.

Commanding difficulties which have been experienced have been isolated to ground transmission problems.

Several commands have been missed which were attributed to the logic race in the command clock design. This is expected for 1 in 10,000 commands. (See Appendix B, PIR 1J83-NE-759.) Six have been noted in approximately 52,000 commands. The time base provided by the S/C clock has been well within specifications during this period. Drift has averaged -1.18 m.s./orbit. The spacecraft clock was reset successfully on 1 January 1973. See Figure 5-1. Spacecraft time code transmitted via MSS and Telemetry has been reliable and accurate. All frequency outputs to other subsystems have been nominal.

There has been no occasion to switch to alternate units from original configuration.

In orbit 583 in the Bermuda pass during an attempted Comstor load cell 12 of Comstor B gave a return that was 256 seconds higher than entered. Cell 12 loaded with 525 "Inv A ON" for 14:57:20; verified as 525 for 15:01:36. The same Δ time was noted in Cell 12. Comstor B as listed in Table 5-1. In three cases noted the Δ time was 256 sec lower than entered. On second try Comstor loaded normally each time. This intermittent problem is under further investigation.

Table 5-2 gives typical telemetry values.

The VHF command Receiver-B has operated flawlessly since launch. Receiver A has not yet been used. Interference has frequently been observed in strip charts and telemetry data, but this has had no impact on the operational functions.

Table 5-1. Summary of Cell 12 Comstor 'B' (Δ Time 256 Sec)

Orbit	Δ Time	Station
583	Н	Bermuda
635	Н	Alaska
891	Н	Greenbelt
1225	Н	Greenbelt
1254	Н	Greenbelt
1538	Н	Greenbelt
1696	L	Alaska
1699	Н	Greenbelt
1719	Н	Alaska
1803	${f L}$	Greenbelt
1852	L	Bermuda
1983	Н	Alaska
2189	Н	Goldstone

H - Δ time 256 seconds higher than entered

L – Δ time 256 seconds lower than entered

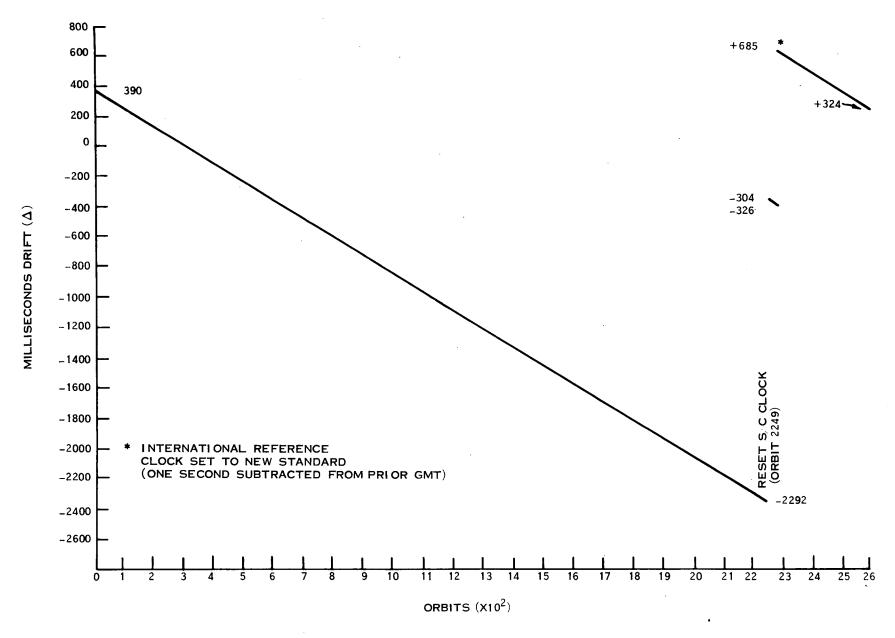


Figure 5-1. Command Clock Drift Summary

Table 5-2. Command/Clock Telemetry Summary

Function No.	Name	Mode	Units 20 ⁰ C	T/V Plateau	Orbit 35	Orbit 1799	Orbit 2201	Orbit 2600
8005	Pri. Power Supply Temp		°c	37.0	37, 31	39, 49	39.04	38, 91
8006	Red. Power Supply Temp	_	°c	41.3	35,73	38, 05	37, 62	37, 56
8007	Pri. Osc. Temp	_	°c	31.1	31.14	32, 09	31.99	31,92
8008	Red. Osc. Temp	_	°c	30.3	30, 47	31, 41	31.40	31, 31
8009	Pri, Osc. Output	_	TMV	1.07	0.95	0.96	0,96	0.96
8010	Red. Osc. Output	_	TMV	0.98	**	**	**	**
8011	100 kHz	Pri Red.	TMV	3,10	3.11	3, 11	3, 11	3.11
8012	10 kHz	Pri Red.	TMV	3.07	3.10	3.08	3, 08	3.08
8013	2.5 kHz	Pri, - Red,	TMV	2,95	2,95	2, 95	2, 95	2, 95
8014	400 Hz	Pri Red.	TMV	4. 40	4, 40	4. 40	4.40	4. 40
8015	Pri. +4V Power Supply	Pri. Clk ON	VDC	4, 10	4, 10	4.10	4, 10	4, 10
8016	Red. +4V Power Supply	Red. Clk ON	VDC	3.98	3, 95	3, 95	3,95	3, 95
8017	Pri. +6V Power Supply	Pri. Clk ON	VDC	6, 07	6.06	6. 07	6.07	6, 08
8018	Red. +6V Power Supply	Red. Clk ON	VDC	5.95	6.00	5, 94	5,94	5.95
8019	Pri, -6V Power Supply	Pri. Clk ON	VDC	-6, 02	-6.02	-6, 03	-6.02	-6.03
8020	Red6V Power Supply	Red. Clk ON	VDC	-6.02	-5, 99	-6.00	-6.00	-6.00
8021	Pri, -23V Power Supply	Pri. Clk ON	VDC	-22.96	-22,88	-22.89	-22,89	-22.90
8022	Red, -23V Power Supply	Red. Clk ON	VDC	-23.0	-22.98	-23,00	-23, 01	-23, 02
8023	Pri29V Power Supply	Pri. Clk ON	VDC	-29.2	-29,13	-29,07	-29.15	-29.14
8024	Red29V Power Supply	Red, Clk ON	VDC	-29, 2	-29,07	-29, 21	-29, 21	-29, 21
8101	CIU A -12V	CIU A ON	VDC	-12.3	-12.33	-12,33	-12,33	-12.33
8102	CIU B -12V	CIU B ON	VDC	-12.2	-12.26	-12, 26	-12,26	-12.26
8103	CIU A -5V	CIU A ON	VDC	-5,34	-5,32	-5, 34	-5.34	-5, 34
8104	CIU B -5V	CIU B ON	VDC	-5.30	-5, 31	-5, 31	-5.31	-5.31
8105	CIU A Temp	CIU A ON	°c	24.3	24. 47	25, 13	24.85	24, 85
8106	CIU B Temp	CIU B ON	°c	24.6	24.96	25. 67	25.36	25. 42
8201	Receiver RF-A Temp	_	°c	29, 0	**	**	**	**
8202	Receiver RF-B Temp	_ [°c	28,5	27.98	28, 53	28.44	28, 46
8203	D MOD A Temp	-	°c	37.5	25, 41	25, 90	25.99	25, 82
8204	D MOD B Temp	-	°c	35, 4	35.03	35. 61	35.75	35, 59
8205	Receiver A AGC	Receiver A ON	DBM	-70.0	**	**	**	**
8206	Receiver B AGC	Receiver B ON	рвм	-57.0	-94.74	-92, 10	-88, 28	-89.91
8207	Amp. A Output	Receiver A ON	RMV	1.50	**	**	**	**
8208	Amp B Output	Receiver B ON	TMV	1,54	2.81	2.96	3.08	2.81
8209	Freq. Shift Key A OUT	Receiver A ON	TMV	1,11	**	**	**	**
8210	Freq. Shift Key B OUT	Receiver B ON	TMV	1,10	1,10	1.10	1.10	1.10
8211	Amp, A Output	Receiver A ON	TMV	1.11	**	**	**	**
8212	Amp. B Output	Receiver B ON	TMV	1.13	1.13	1.13	1,13	1.14
8215	D MOD A -15V	Receiver A ON	TMV	4.98	**	**	**	**
8216	D MOD B ~15V	Receiver B ON	TMV	4.99	5,00	5.00	5, 00	5.00
8217	Regulator A -10V	Receiver A ON	TMV	5.39	**	**	**	**
8218	Regulator B - 10V	Receiver B ON	TMV	5.50	5.50	5. 50	5,50	5.50

^{*} Thermal Vacuum Test Data

 $[\]ensuremath{^{**}}$ A component not used since prelaunch

SECTION 6 TELEMETRY SUBSYSTEM

The telemetry Subsystem was launched in the ON mode and has been operating continuously since then providing data from the spacecraft either to ground stations, the narrow band recorders, or both. Typical telemetry values are given in Table 6-1. Only memory section 0, 0 has been used in the telemetry matrix. Total performance has been excellent.

Table 6-1. TLM Telemetry Summary

Function No.	Function Name	Unit	T/V* 20°C Plateau	Orbit 35	Orbit 1799	Orbit 2201	Orbit 2600
9001	Memory Sequencer A Converter	VDC	6.34	6.35	6.33	6.33	6.34
9002	Memory Sequencer B Converter	VDC	6.44	**	**	**	**
9003	Memory Sequencer Temp	°c	20.1	19.59	21.24	21.69	21.47
9004	Formatter A Converter	VDC	5.99	5,99	5.99	5,99	5.99
9005	Formatter B Converter	VDC	6.02	**	**	**	**
9006	Dig. Mux A Converter	VDC	10.02	10.01	10.04	10.07	10.07
9007	Dig. Mux B Converter	VDC	10.01	**	**	**	**
9008	Formatter/Dig. Mux Temp	°c	22.2	22.50	25.00	26.01	27.34
9009	Analog Mux A Converter	VDC	26.18	26.01	26.18	26. 18	26.18
9010	Analog Mux B Converter	VDC	26.21	**	**	**	**
9011	A/D Converter A Voltage	VDC	10.00	10.00	10.06	10.07	10.07
9012	A/D Converter B Voltage	VDC	10.06	**	**	**	**
9013	Analog Mux. A/D Converter Temp	°c	26.7	25.00	27.27	27.50	27.50
9014	Preregulator A Voltage	VDC	19.91	19.93	19.96	19.99	19.99
9015	Preregulator B Voltage	VDC	19.88	**	**	**	**
9016	Reprogrammer Temp	°c	19.9	22.0	23.59	24.88	25.00
9017	Memory A Converter	VDC	6.00	6.00	6.00	6.00	6.00
9018	Memory A Temp	°c	19.3	17.51	17.52	18.51	19.06
9019	Memory B Converter	VDC	6.03	**	**	**	**
9020	Memory B Temp	°c	17.4	17.68	18. 16	19.04	19.29
9100	Reflected Power (Xmtr A)	dBm	0	11.95	12.46	12.38	12.75
9101	Xmtr A -20 VDC	VDC	-19.76	-19.75	-19.76	-19.76	-19.78
9102	Xmtr B -20 VDC	VDC	-19.79	**	**	**	**
9103	Xmtr A Temp	°c	20.5	20.95	22.00	22,46	24.06
9104	Xmtr B Temp	°c	20.0	21.69	22.77	23.31	25.02
9105	Xmtr A Power Output	dBm	25.48	25, 12	25.36	25,36	25,36
9106	Xmtr B Power Output	dBm	25.84	**	**	**	**

^{*} Thermal Vacuum Test Data

^{**} Units not used since prelaunch

SECTION 7 ORBIT ADJUST SUBSYSTEM (OAS)

A fifth orbit adjust burn was performed during orbit 2416 for the purpose of maintaining a satisfactory ground track. The OAS heaters were turned on during orbit 2415 at 22:22:01 and off prior to the burn. The OAS and the (-)x thruster were turned on at 00:21:31 and off at 00:21:52. All commands were backed up in COMSTOR for a firing period of 20.4 seconds. Figure 7-1 shows performance characteristics. Tracking data for the fifth burn is given in Table 7-1. Table 7-2 is a summary of OAS performance to date and Table 7-3 gives average telemetry values for the off quiescent state.

Table 7-1. ERTS-1 Brouwer Mean Elements

<u>Parameter</u>	<u>Pre-burn</u>	Post-burn
Apogee (Km)	920.597	920.738
Perigee (Km)	894.515	894.686
SMA (Km)	7285.723	7285.8 7 7
Inclination (Deg)	99.093	99.093
Eccentricity	.00179	.00179
Mean Anomaly (Deg)	229.008	39.512
Argument of Perigee (Deg)	109.442	140.302
RAAN (Deg)	77.982	80.002
Nodal Period (Min)	103.266	103.269
Epoch	12 Jan 73	14 Jan 73
	20:57:45.8	21:09:16.6

Table 7-2. Orbit Adjust Performance

Orbit	Burn Time (sec)	Average Sma (2) (KM)	Performance % of Plan	N ₂ H ₄ Used # (3)
(1)	_	7281.461	-	_
38	4.8	7281.484	60.0	0.018
44	251.0	7283.456	103.5	0.934
59	318.0	7285.838	101.5	1.19
938	12.8	7285.877	110.0	0.044
2416	20.4	7285.877	106.0	0.076
	Average Force	e 0.81 LB _f		

- (1) After Injection
- (2) Semi-Major Axis
- (3) Initial fuel load 67.0 pounds

Table 7-3. OAS Telemetry Values

Function			*T/V		Ork	oit	
No.	Name	Units	20 ⁰ C Plateau	35	1799	2 2 01	2600
2001	Prop. Tank Temp.	°C	18.2	22.03	23.81	23.72	23,91
2003	Thrust Chamber No. 1 (-x) Temp.	°C	20.9	29.57	34.22	27.60	28.50
2004	Thrust Chamber No. 2 (+x) Temp.	°C	19.7	38.76	36.93	41.21	37.44
2005	Thrust Chamber No. 3 (-y) Temp.	°C	18.9	34.55	40.63	42.95	46.23
2006	Line Pressure	Psia	4.0	539.29	486.86	487.17	486.87

^{*} Thermal Vacuum Test Data

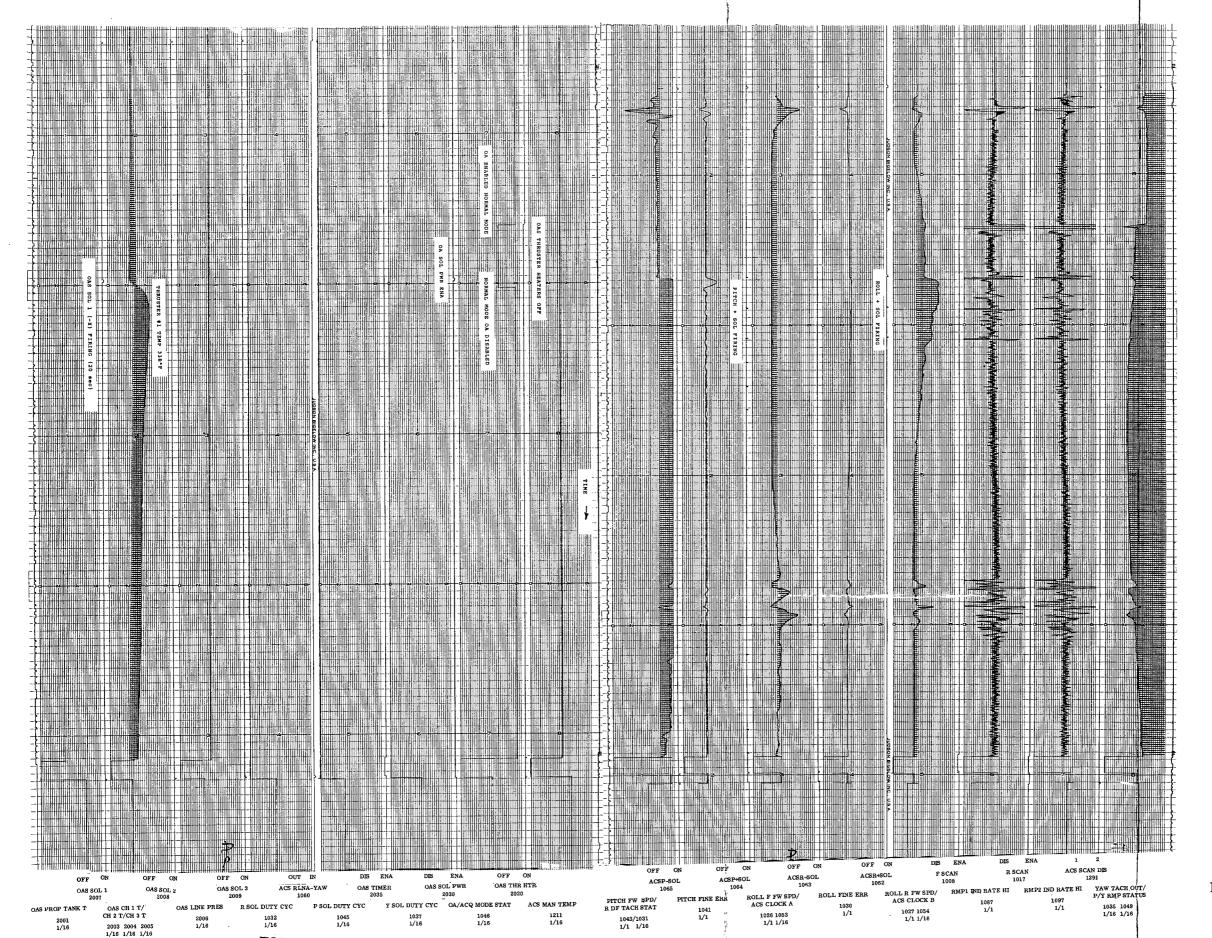


Figure 7-1. Orbit Adjust Subsystem
Performance Characteristics

SECTION 8 MAGNETIC MOMENT COMPENSATING ASSEMBLY (MMCA)

The spacecraft was corrected for unbalanced magnetic moments in orbits 73, 85, 110 and 220. Adjustments were made in the pitch positive. The unit responded well as noted in Table 8-1 and has held its charge. The current dipole values are Pitch + 2950 Pole-Cm, roll zero, yaw zero. These values are unchanged since Orbit 220. Table 8-2 gives typical telemetry for the MMCA.

Table 8-1. MMCA Telemetry Before and After Adjustment

		Orbits								
Function	Units	72	75	83	88	106	115	218	224	
4003	TMV	3.49	3.48	3.48	3.48	3.47	3.49	3.50	3.50	
4004	TMV Pole-Cm	$\begin{vmatrix} 3.11 \\ \approx 0 \end{vmatrix}$	3.11 ≈0							
4005	TMV Pole-Cm	3. 13 ≈0	2.87 1200	2.87 1200	2.77 1800	2.77 1800	2.65 2350	2.65 2350	2.52 2950	
4006	TMV Pole-Cm	3.18 ≈ 0	3.20 ≈0	3.20 ≈0	3.20 ≈0	3.18 ≈0	3.18 ≈0	3. 18 ≈0	3.18 ≈0	

Table 8-2. MMCA Telemetry Summary

			T/V 20°C*	Orbit			
Number	Name	Units	Plateau	35	1799	2201	2600
4001	A1 Board Temp	°C	19.8	19.77	19.54	19.54	19.37
4002	A2 Board Temp	°C	23.6	23.58	23.43	23.38	23, 36
4003	Hall Current	TMV	3,50	3.48	3,49	3, 49	3.49
4004	Yaw Flux Density	TMV	3.07	3.11	3.06	3.06	3.10
4005	Pitch Flux Density	TMV	3.12	3.13	2.51	2,50	2.50
4006	Roll Flux Density	TMV	3.22	3.19	3.17	3,18	3, 20

UNIFIED S-BAND/PREMODULATION PROCESSOR

The Unified S-Band Subsystem (USB) has operated satisfactorily since separation, late in Orbit Zero.

The USB receiver has been ON continuously since launch for a total of 4474 hours, available to any USB ground station for reception of commands and ranging interrogation. Only Receiver A has been used to date.

The USB transmitter has been ON for 592 hours (13% of the time) available on command for transmission of telemetry, DCS information, and ranging data. Only transmitter A has been used to date.

Table 9-1 lists telemetry values for orbits in this reporting period. All functions have maintained their original value except for transmitter power output, which has decreased from a value of 1.60 watts at launch to a value of 0.60 watts at orbit 2600. Figure 9-1 shows the power output history with its abrupt step-downs in orbits 808, 988, 1256, 2083, and 2526.

For a nominal 1 watt power output for the USB, the margins for the worst case have been computed to be:

Carrier	24 dB drop
1 kilobit modulation	17 dB drop
24 kilobit modulation	13 dB drop
DCS modulation	6 dB drop

The DCS margin is considered soft, however, and could be as much as 10 dB. The 6 dB decline equates to a power output of 0.25 watts, and the 10 dB decline equates to a power

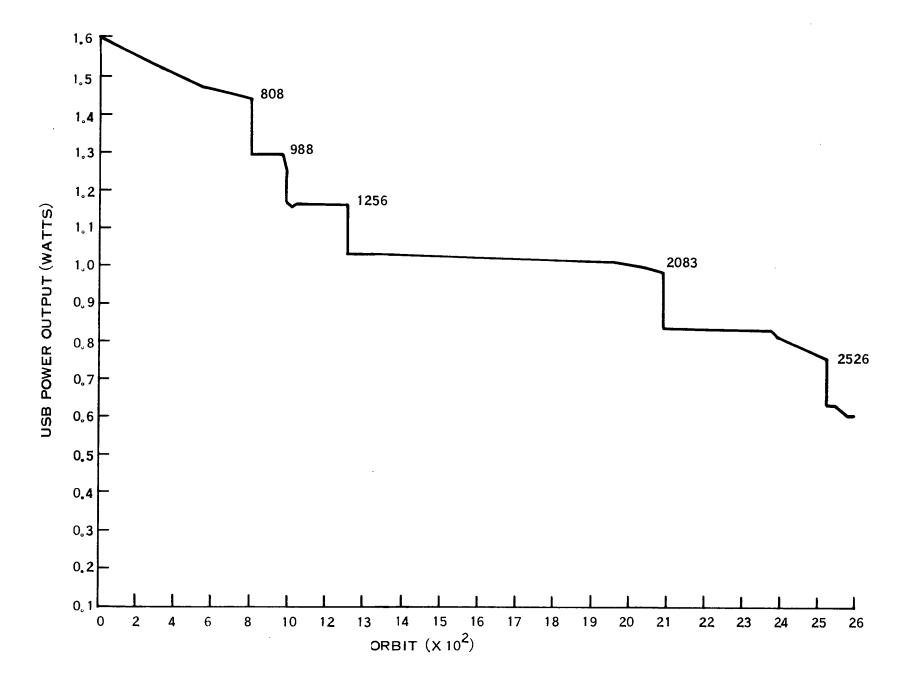


Figure 9-1. USB Power Output

output of 0.1 watt. A power output of 0.20 watts may then be used as the value requiring consideration of corrective action.

The average power decrease per 100 orbits has been 38.5 milliwatts. A continuation of this average rate of decline would reduce the power output to 0.20 watts in another thousand orbits—early April 1973. The rate of power decline since orbit 2400 has been 120 milliwatts per hundred orbits. If this rate of decline is continued, the output could decrease to 0.20 watts in 400 orbits—late February 1973. It appears likely, therefore, that DCS quality will reach marginal values between late February and early April 1973 and will require a shift to the B transmitter of the USB unit.

Table 9-1. USB/PMP Telemetry Values

	Function		Telemetry Value					
No.	Name		*TV	35	1699	2139	2566	
11001	USB Revr. AGC	DBM	-127.24	-122.78	-127.58	-125.89	-126.18	
11002	USB Trans. Pwr	WTS	1.60	1.60	1.03	0.84	0.62	
11003	Receiver Error	KHZ	-24.33	-21.79	-21.28	-23.01	-20.87	
11004	Transp. Temp.	DGC	20.37	22.92	23.31	24.34	25.30	
11005	Transp. Pressure	PSI	15.68	15,91	15.96	16.02	16.09	
11007	Trans A-15VDC	VDC	-15.16	-15,20	-15.20	-15.20	-15.20	
11009	Ranging -15VDC	VDC	-14.76	-14.76	-14.76	-14.76	-14.76	
11101	PMP A Volt	VDC	-15,21	-15. 12	-15.23	-15.11	-15.18	
11103	PMP A Temp.	DGC	23.14	30.44	31.10	32.80	33.70	

^{*}Thermal Vacuum Test Data; from EAB-FT-1 (unit changed to EAB-FT-2 for flight).

NOTE: Only "A" Unit has been turned on.

During Orbit 2083, the USB power output stepped down during a transmission period for the first time, so that the playback telemetry shows the step-down on the strip chart. See Figure 9-2.

Table 9-2 is a section of the computer printout--Data Listing Program (DLP)--from telemetry showing the time bracket of the power step-down in Orbit 2526. The data was played back in Orbit 2527 as can be seen from the header. The left hand column gives the time of the data: Julian day 20 (20 January 1973) plus hours, minutes and seconds. The next column gives the major frame and minor frame numbers (reference the header) in the telemetry matrix. The third column gives telemetry values for the USB transmitter power output function 11002 which is in column 18 row 64 of the telemetry matrix. The values are indicated "low" by the "L" entry from an arbitrary value inserted before launch in the DLP software program. The values are printed out only when they change; and associated with the print-out after the slash mark is the number of major frames of the prior reading before the change. The last column is the static phase error values. The corrected value of the power output is circled just below the value printed out from the original calibration curve. It can be seen from the data that between 21:19:35 and 21:23:51 the power output declined from 0.77 to 0.75 watts where it rem ained until after 21:55:11. Between 21:25:11 and 21:25:27 the power output dropped to 0.65 watts, the step-down shown in Figure 9-1. The plotted values shown in Figure 9-1 are average values for the orbit, and hence do not reveal the detail of the DLP, nor can correspondence in value be made directly.

Figure 9-3 is a strip chart of the AGC reading at Alaska during the step-down in Orbit 2526. As can be seen, the AGC reading decreased from 8.0 to 7.8, equivalent to a dbm reading of -79 to -80, which is about equal to the power drop of 0.8 db from 0.77 to 0.65 watts. As the spacecraft receded from the ground station, the AGC level decreased as can be seen. Minor effects of antenna pattern may also be seen.

Figure 9-4 shows the original and revised calibration curve for the USB Power output.

These curves are useful in correcting the computer programs which still use the original calibration curve.

Figure 9-5 shows the AGC levels as recorded at Alaska (ULA), Goldstone (GDS) and Greenbelt (ENT). Alaska uses an 85-foot antenna and cooled receivers. This yields a net advantage to Alaska of about 8 db. Goldstone reports slightly higher AGC readings than does Greenbelt, for reasons not yet determined. Of interest is a fourth trace on Figure 9-5 showing the AGC readings at Alaska for Orbits 2500 to 2600 only. This trace is about 2 db below the average AGC readings for Orbits 1300 to 2600, reflecting the successive power drops.

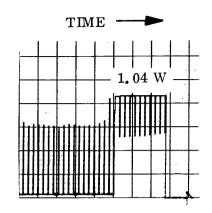
The pressure/temperature ratio of the USB unit has remained practically constant as shown by Figure 9-6, dropping from 0.0549 in Orbit 35 to 0.0545 in Orbit 2600.

Table 9-2. Data Listing Program

DATA LISTING PRGRM ERTS+A FLT GRBIT NO. 0025271A SOURCE DATA GRIGIN-20-JAN. 73 FROM 21/19/35 (OC1) TO 23/01/43 (384)

TIME DDD/HH/MM/SS	MAJOR:	- XMTR PWR	RCVR ERR KHZ	, 0	23,01,40	(001)	
· .	•	18/64 11002	1/74 11003				
020/21/19/35	1= 1	•67L/	0 =17.66 /	0			
020/21/19/51	2- 1	0.79	- 19.26 /	1			
020/21/20/07	3- 1		+22.47 /	1			
020/21/20/23	4- 1	•	- 20.87 /	1			
020/21/20/39	5- 1		-22.47 /	1			
020/21/20/55	6- 1		-19.26 /	1			
020/21/21/11	7- 1		*20·87 /	1			
020/21/21/27	8- 1		7				
020/21/21/43	9 - 1	0.77	- 19•26 /	2			
020/21/22/15	11- 1	•	*17.66 /	2			
020/21/22/31	12- 1		-22.47 /	1			
020/21/23/03	14- 1		≈20•87 /	5			
020/21/23/19	15- 1		-22.47 /	1			
020/21/23/35	16- 1		-20.87 /	1			
020/21/23/51	17- 1	•65L/	9 =24.07 /	1			
020/21/24/07	18- 1		*16.05 /	1			
020/21/24/23	19* 1	0.75	÷24.07 /	1		garage and the second s	
C20/21/24/55	21- 1		-22.47 /	2		FOLDOUT FRAME	1
020/21/25/11	22- 1		•19·26 /	1		-	1
C20/21/25/27	23- 1	•55L/	6 +24.07 /	1			
020/21/25/43	24- 1	0.65	+20.87 /	1			
020/21/26/15	26- 1		-22.47./	. S			
020/21/26/31	27- 1		+24.07 /	1			
020/21/26/47	28= 1	•55L/	5 =19.26 /	1			
020/21/27/03	29- 1	0.65	- 22.47 /	1			
020/21/27/19	30# 1		-19.26 /	1			
020/21/27/51	32- 1	•	#20.87 /	5		•	
020/21/28/07	33- 1	•	- 24.07 /	1			
020/21/28/23	34# 1		*17.66 /	1			
020/21/28/39	35- 1		- 19.26 /	1			
020/21/28/55	36- 1		+16+05 /	1			
020/21/29/11	37# 1	L	-20.87 /	1			
020/21/29/27	38= 1		= 17.66 /	1			
020/21/29/43	39= 1	•02L/	11 -20 -87 /	1			
020/21/29/59		•02 /	1 =24.07 /	1			
020/21/30/15			•20·87 /	1			
020/21/30/31			=22.47 /	1		FOLDOUT FRAME	2
020/21/30/47			÷24.07 /			- CLEVEL FRAME	
020/21/31/03			*22.47 /	1			
020/21/31/35	46- 1	l	=17.66 /	5			

ORBIT 2082 LEAVES ORBIT
WITH USB POWER
4.35 TMV = 1.04 WATTS

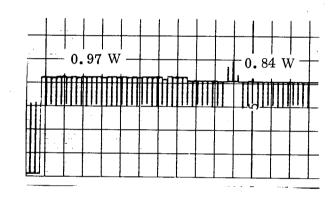


ORBIT 2083

POWER STEP-DOWN IN ORBIT

FROM 4.25 TMV = 0.97 WATTS TO

4.08 TMV = 0.84 WATTS



ORBIT 2084
ENTERS ORBIT WITH USB POWER
= 4.08 TMV = 0.84 WATTS

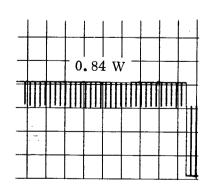


Figure 9-2. USB Power Output

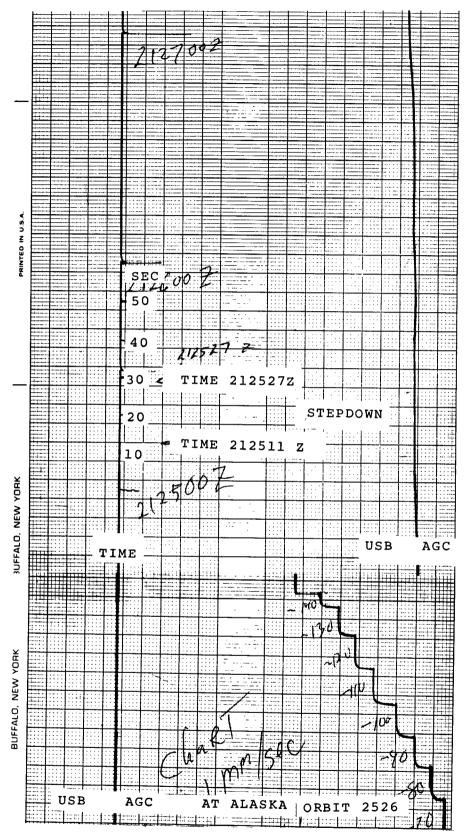


Figure 9-3. Strip Chart of AGC Power from Alaska Site

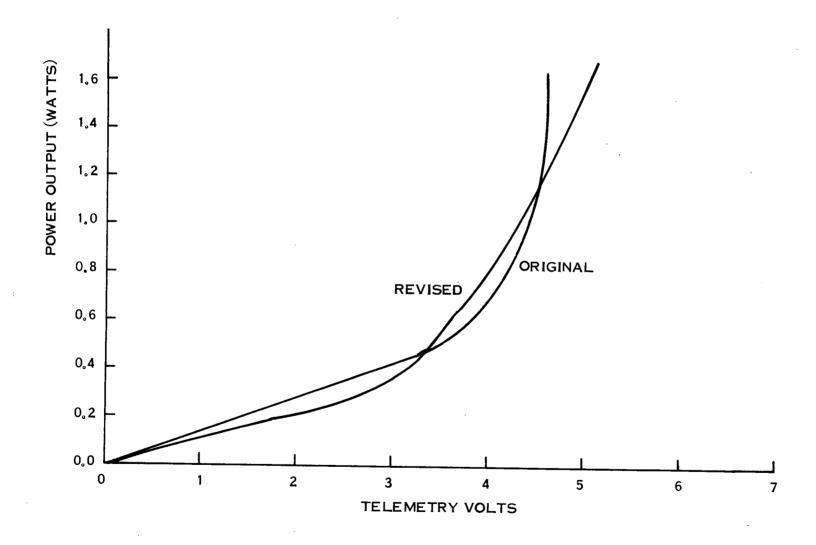


Figure 9-4. USB Calibration Curves - Original and Revised

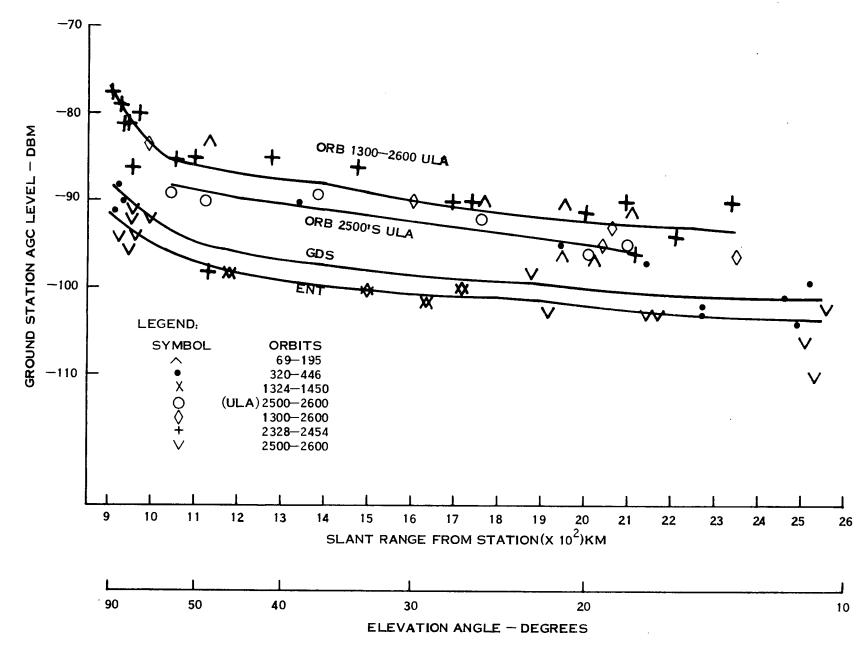


Figure 9-5. Maximum AGC Levels During Orbit as Recorded in Ground Station

Figure 9-6. USB Pressure/Temperature Ratio

ELECTRICAL INTERFACE SUBSYSTEM

Auxiliary Processing Unit (APU) consists of Search Track Data, Time Code Data, and Back-up Timers which operated satisfactorily throughout this report period. Telemetry for the APU is shown in Table 10-1. The APU is in Normal mode.

Table 10-1. APU Telemetry Functions

Functions	Description	Unit	Orbit 7	Orbit 500	Orbit 899	Orbit 1291	Orbit 1799	Orbit 2201	Orbit 2600
13200 13201 13202	APU, -24. 5 VDC APU, -12 volts APU Temp.	VDC VDC DGC	24.90 12.08 25.49	24. 91 12. 08 26. 30	12.08	12.08	24. 91 12. 08 27. 72	24.91 12.08 27.68	24.90 12.08 28.50

The Power Switching Module (PSM) contains the switching relays for power to Orbit Adjust, MSS, WBVTR No. 1 and No. 2. RBV and PRM. The Orbit Adjust power circuit was powered for the duration of the Orbit Adjust maneuver in orbit 2416. The MSS and WBVTR No. 1 power circuits have been operated on a regular basis throughout this report period. The power relay for the RBV remained in a closed condition since orbit 196. but the RBV remained off by relays in the individual cameras and camera electronics. The WBVTR No. 2 remained off due to the failure occurring in orbit 148. Appendix B contains the anomaly bench simulator test reports.

The Interface Switching Module (ISM) performed all switching normally during this report period. Orbit Adjust Heater on and off, and Compensation Loads changes were exercised in this report period.

THERMAL CONTROL SUBSYSTEM

The thermal subsystem has maintained spacecraft temperature control over a satisfactory range during this report period. Table 11-1 shows average analog telemetry values from data recorded on the NBTR. During this report period, the sun intensity reached a maximum which was +6.5% above the sun intensity at launch or +3.3% increase above the end of the last report period. This caused a gradual rise in average temperatures of about 0.5° to 2° C around the spacecraft as seen in Figure 11-1.

On orbit 1409 compensation load #7 was turned off leaving compensation loads 1, 2, 4, 5 and 8 on to use excess array power and to help balance temperatures around the sensory ring. Load #7 provided heating to the Wide Band Recorder Electronics #2 and is no longer required. Compensation load history is shown in Table 11-2.

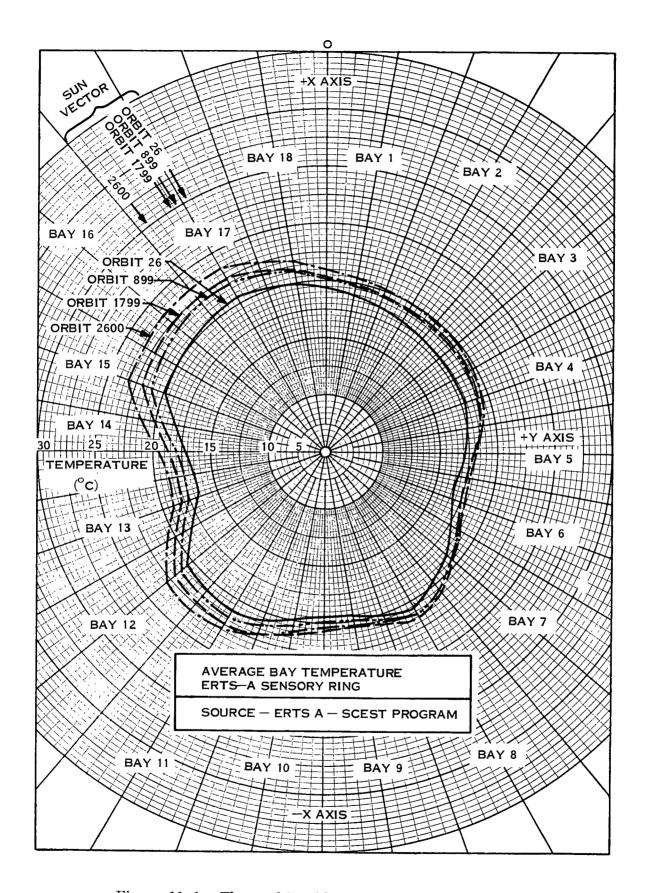


Figure 11-1. Thermal Profile Orbits 26, 899, 1799, 2600

Table 11-1. Thermal Subsystem Analog Telemetry (Average Value for Frames of Data Received in NBTR Playback)

Function	Description	Unit	7	26	500	899	1291	1799	2201	2600
7001	THM TH01 STI	DGC	19, 31	19,52	20.91	21.59	21.47	20.93	21,77	22, 18
7002	THM TH02 SBO	DGC	18.48	18.60	19.28	20.24	20.01	19.70	20.37	20.55
7003	THM TH03 STI	DGC	18, 24	18.48	19,59	21.23	20.28	20.29	20.65	21.79
7004	THM TH03 SBI	DGC	19.24	19.47	19.85	20.12	20.46	21.11	20.53	21.11
7005	THM TH04 STI	DGC	18.25	18.39	19.18	20.73	19, 81	20.08	20.07	21.17
7006	THM TH05 SBO	DGC	17.69	17.57	18.04	18, 83	18.53	18.45	18.51	19.04
7007	OA -X THRUSTER	DGC	21.73	21.95	22,30	22.54	23.04	23.36	22.42	22.38
7008	THM TH07-STO	DGC	15.89	15.95	16.44	17.01	16.87	16.82	16.74	17.09
7009	THM TH06 SBI	DGC	19. 41	19.38	20,07	20.73	20, 62	20.62	20.61	21.05
7010	THM TH07 STI	DGC	18, 36	18.61	19.17	19, 61	19.71	19.79	19.68	19.79
7011	THM TH08 STO	DGC	21.60	21.78	22, 22	22.52	22,87	23.24	22,38	22.52
7012	THM TH09 SBI	DGC	21.62	21.81	22.37	22.62	23.07	23,38	23.04	23.10
7013	THM TH10 SBO	DGC	18.76	18.73	19.19	19,37	19.82	20.37	19.37	19.87
7014	THM TH11 STI	DGC	22, 09	22.37	23.02	23, 32	23.62	24.18	24.01	24.52
7015 7016	THM TH12 SBO THM TH13 STI	DGC	22, 03	22.37	22.74	23.27	23.37	24. 46	23,68	25.36
7016	RBV BEAM CTR LN	DGC	20.75	20.95	21.80	22.22	22.68	23.12	23.21	24. 5
7018	THM TH14 STO	DGC DGC	21. 25	21.53	22.19	22.47	22, 85	23.23	23.17	23.30
7018		1	20, 52	20, 38	21.56	21.85	22.10	22.57	23.35	24.77
7019	NBR RAD OUTBD B4 THM TH15 SBI	DGC	4. 88	5, 09	5, 51	5.96	6.08	6.23	6.03	6.00
7020	THM THIS SEI	DGC	21.39	21.14	22, 87	23.33	23.78	24.23	25.02	26. 21
7021	THM THIO SII	DGC	20, 87	20.73	22.65	23.23	23, 68	23.83	24.54	25. 44
		1	20.70	20, 22	22,39	23.06	23.46	23.38	24.31	25.18
7023 7030	THM TH18 SBO THM TH03 BUR	DGC	22, 39	21, 90	23.87	24.40	24.86	24.16	25.98	25.79
7030	THM THOS BUR THM THO6 BUR	DGC	16, 01	16.05	16,50	17.82	17.09	17.11	17.17	17.89
7031	THM THOS BUR	DGC	13, 54 19, 77	13.59	13.98	14.42	14.39	14.32	14.16	14.49
7032	THM TH12 BUR	DGC	21. 25	19.92 21.51	20, 26	20.44	20.89	21.29	20, 48	20.61
7034	THM THIS BUR	DGC	19.92	21.51 19.70	21.94	22.42	22.49	23,68	22.62	24.59
7034	THM THIS BUR	DGC	19.92	20.11	21.40	21.85 21.91	22.44	22.09	24,17	24.36
7040	THM THIS BOX	DGC	18. 97	20.11 19.27	21.46 20.16	20.93	22.12 20.80	20,95	23.15	22.4
7041	THM THOI TEB	DGC	17. 93	17.99	18.80	20.93 19.76	19.34	20.39 19.16	21.34 19.51	21.58 20.00
7042	тим тноз тсв	DGC	18.22	18.34	19.00	21.32	19.72	20.28	20.00	20.00
7043	тнм тно4 тсв	DGC	19.03	18.95	19.42	20.46	19.93	20.28	20.00	20.7
7044	тнм тно5 тсв	DGC	16.38	16.27	16.79	17.33	17.13	17.08	17.11	17.4
7045	тнм тнот тсв	DGC	18.23	18, 41	18.89	19,23	19.37	19.46	19.28	19.30
7046	тнм тноэ тсв	DGC	19.64	19. 38	20.04	20.15	20.60	20.86	20.39	20.52
7048	тим тил тсв	DGC	21.77	21.98	22.51	22, 85	23.16	23.93	23, 42	24.32
7049	ТНМ ТН12 ТСВ	DGC	21.60	21.92	22.15	22.69	22.58	23, 61	23.19	25.10
7050	тнм тн13 тсв	DGC	21.10	21, 21	22,00	22.35	22,51	23.38	23.44	25.22
7051	THM TH14 TCB	DGC	21.94	21.38	23.02	23.23	23.65	24.18	24.77	26.19
7052	- THM-TH16 TCB	DGC -	21.71	21.30	23.59	24, 53	25.11	•	25.80	26.6
7053	тнм тн17 тсв	DGC	22, 43	21.73	23.91	24, 28	24.81	24.39	25. 48	25.74
7054	тнм тн18 тсв	DGC	20.54	20.02	21.83	22,22	22, 51	22.06	22.91	22.99
7060	THM SHUTTER BY 1	DEG	23, 56	25.85	31.62	37.08	36, 21	34.83	39.66	43.64
7061	THM SHUTTER BY 2	DEG	0.00	6. 62	12.69	13.07	16.89	18.28	13.91	13.88
7062	THM SHUTTER BY 3	DEG	6.09	10.96	18.70	33.53	25.96	25.91	24.39	38.14
7063	THM SHUTTER BY 4	DEG	26.32	30, 60	33,35	38.24	36, 27	36.10	37.09	38.29
7064	THM SHUTTER BY 5	DEG	15.00	15, 03	10.46	12.26	14.42	16.88	16.87	16.24
7065	THM SHUTTER BY 7	DEG	10.66	17.14	17.30	18,21	20.98	22, 43	22.44	21.92
7067	THM SHUTTER BY 9	DEG	33, 31	33, 26	34.40	37.97	39.15	39.26	38.84	38.49
7068	THM SHUTTER BY 10	DEG	19.76	24.68	26.03	27.32	29.54	31.63	32.08	33, 69
7069	THM SHUTTER BY 11	DEG	38, 13	39, 66	44.55	46.04	48, 48	51.47	52.98	55.79
7070	THM SHUTTER BY 12	DEG	43. 46	43, 81	44, 91	47.64	47.05	50.71	50.68	55. 84
7071	THM SHUTTER BY 13	DEG	39.75	40, 39	47.54	47,88	47.96	48.75	49.99	59.02
7072	THM SHUTTER BY 14	DEG	35, 29	34. 20	38, 50	41.42	42.85	47.50	51.14	62.55
7073	THM SHUTTER BY 15	DEG	47. 45	45, 40	55. 67	59.35	63.42	65.59	70.71	75.54
7074	THM SHUTTER BY 16	DEG	31.69	24.50	39, 62	47.22	51.25	53.07	55.30	59. 81
7075	THM SHUTTER BY 17	DEG	43.96	39.06	54, 02	56.48	60.34	59.02	63.72	66.93
7076	THM SHUTTER BY 18	DEG	33.88	29.70	39.90	41.98	43.14	42.93	45.56	48.5
7080	THM Q1 T ZENER V	VDC	8.19	8.19	8, 19	8, 19	8.19	8.19	8, 19	8.19
7081 7082	THM Q2 T ZENER V THM Q3 T ZENER V	VDC VDC	8. 40	8, 40	8, 40	8, 40	8.40	8.40	8.40	8.40
7082	THM Q3 T ZENER V THM Q1 S ZENER V	VDC	8, 31	8.31	8,31	8, 32	8.32	8.32	8.32	8.32
7083	THM QI S ZENER V THM Q2 S ZENER V	VDC	8, 31 8, 10	8, 31 8 10	8,33	8,35 8,30	8.35	8,33	8.35	8.35
7084	THM Q2 S ZENER V THM Q3 S ZENER V	VDC	8. 19 8. 15	8.19	8.19	8.20	8.20	8.20	8.20	8.2
7085	THM Q3 5 ZENER V THM PSM MOUNT	DGC	8, 15	8.15 21.60	8.15	8.15	8.15	8,15	8.15	8.10
7090	THM PSM MOUNT THM IND ATTITUDE	DGC	20, 82 19, 15	21.60 19.40	22, 25 20, 05	22.84 20.71	23.14	23.45	23,64	23.7
7091	THM RBV RADIATOR	DGC	19. 15 15. 33	19. 40 15. 65	20.05 16.42	20.71 16.78	20.69 17.31	20.86 17.99	20, 87	21.0
-7 092	THM RBV RADIATOR THM RBVC CTR BM	—ĐG€	15.33 19.84	15, 65 20, 30	16.42 21.06	16.78 21.36	17.31 -21.81	22.29	17.46	17.89
7094	THM WBVTR ROOT	DGC	12.85	12.96	14.44	15.51	15.64	15.50	16.85	17.1
-		DGC	4. 82	4. 81	6.14	7.08	7.50	6.98	9.31	8.6
7095	THM WBVTR RAD CT		16. 46	16. 62	18.18	19.54	19.39	19.12	20.45	21.0
7095 7096	THM WBVTR RAD CT THM WBVTR STRAP	DGC	10.10		22, 69	22.90	21.59	19.42	21.30	22.3
1		DGC DGC	19, 41	20, 56						
7096	THM WBVTR STRAP			20, 56 20, 22	22.30	22, 42	21.93	19.21	20.59	21.0
7096 7097	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3	DGC	19. 41					19.21 20.58	20.59 21.18	
7096 7097 7098	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1	DGC DGC	19. 41 19. 21	20. 22	22,30	22.42	21.93	1		22.32
7096 7097 7098 7099 7100 7101	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3	DGC DGC DGC DGC	19. 41 19. 21 18. 40	20.22 18.60	22.30 19.88	22, 42 21, 53	21.93 20.69	20.58	21.18	22.32 26.1
7096 7097 7098 7099 7100	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17	DGC DGC DGC DGC	19. 41 19. 21 18. 40 21. 43	20.22 18.60 21.31	22,30 19,88 23,35	22.42 21.53 24.38	21.93 20.69 24.41	20.58 24.15	21.18 25.12	22.32 26.13 25.95
7096 7097 7098 7099 7100 7101	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17 THM WBVTR 1 DENT	DGC DGC DGC DGC	19. 41 19. 21 18. 40 21. 43 21. 26	20.22 18.60 21.31 21.49	22.30 19.88 23.35 23.16	22.42 21.53 24.38 24.67	21.93 20.69 24.41 24.19	20.58 24.15 23.75	21.18 25.12 24.85	22.32 26.13 25.93 20.0
7096 7097 7098 7099 7100 7101 7102	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17 THM WBVTR 1 DENT THM WBVTR 2 BAY	DGC DGC DGC DGC DGC	19. 41 19. 21 18. 40 21. 43 21. 26 17. 35	20. 22 18. 60 21. 31 21. 49 17. 46	22.30 19.88 23.35 23.16 18.34	22. 42 21. 53 24. 38 24. 67 19. 51	21.93 20.69 24.41 24.19 19.07	20.58 24.15 23.75 19.24	21.18 25.12 24.85 19.45	22. 32 26. 14 25. 99 20. 04 25. 69
7096 7097 7098 7099 7100 7101 7102 7103	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17 THM WBVTR 1 DENT THM WBVTR 2 BAY THM WBVTR 2 BY 15	DGC DGC DGC DGC DGC DGC	19. 41 19. 21 18. 40 21. 43 21. 26 17. 35 21. 08	20. 22 18. 60 21. 31 21. 49 17. 46 21. 00	22, 30 19, 88 23, 35 23, 16 18, 34 22, 80	22, 42 21, 53 24, 38 24, 67 19, 51 23, 43	21.93 20.69 24.41 24.19 19.07 23.75	20.58 24.15 23.75 19.24 24.05	21.18 25.12 24.85 19.45 24.71	22. 32 26. 19 25. 99 20. 04 25. 69 23. 50
7096 7097 7098 7099 7100 7101 7102 7103 7104	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17 THM WBVTR 1 DENT THM WBVTR 2 BAY THM WBVTR 2 BY 15 THM WBVTR 2 CTR	DGC DGC DGC DGC DGC DGC DGC	19. 41 19. 21 18. 40 21. 43 21. 26 17. 35 21. 08 19. 05	20. 22 18. 60 21. 31 21. 49 17. 46 21. 00 19. 35	22.30 19.88 23.35 23.16 18.34 22.80 20.88 18.85	22, 42 21, 53 24, 38 24, 67 19, 51 23, 43 21, 94 19, 69	21, 93 20, 69 24, 41 24, 19 19, 07 23, 75 21, 86 19, 71	20.58 24.15 23.75 19.24 24.05 21.97 19.87	21.18 25.12 24.85 19.45 24.71 22.73 20.10	22, 32 26, 15 25, 95 20, 04 25, 65 23, 56 20, 17
7096 7097 7098 7099 7100 7101 7102 7103 7104 7105	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17 THM WBVTR 1 DENT THM WBVTR 2 BAY THM WBVTR 2 BY 15 THM WBVTR 2 CTR THM NBTR B SEP 6	DGC DGC DGC DGC DGC DGC DGC DGC DGC	19. 41 19. 21 18. 40 21. 43 21. 26 17. 35 21. 08 19. 05 17. 90 20. 75	20. 22 18. 60 21. 31 21. 49 17. 46 21. 00 19. 35 18. 06 20. 82	22.30 19.88 23.35 23.16 18.34 22.80 20.88 18.85 22.16	22, 42 21, 53 24, 38 24, 67 19, 51 23, 43 21, 94 19, 69 22, 59	21.93 20.69 24.41 24.19 19.07 23.75 21.86 19.71 22.89	20, 58 24, 15 23, 75 19, 24 24, 05 21, 97 19, 87 23, 43	21.18 25.12 24.85 19.45 24.71 22.73 20.10 23.86	22. 32 26. 15 25. 95 20. 04 25. 65 23. 50 20. 17 24. 88
7096 7097 7098 7099 7100 7101 7102 7103 7104 7105 7106 7107	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17 THM WBVTR 1 DENT THM WBVTR 2 BAY THM WBVTR 2 BY 15 THM WBVTR 2 CTR THM WBVTR B SEP 6 THM NBTR B SEP 1 THM NBTR BM CTR	DGC	19. 41 19. 21 18. 40 21. 43 21. 26 17. 35 21. 08 19. 05 17. 90 20. 75 18. 95	20. 22 18. 60 21. 31 21. 49 17. 46 21. 00 19. 35 18. 06 20. 82 19. 37	22, 30 19, 88 23, 35 23, 16 18, 34 22, 80 20, 88 18, 85 22, 16 20, 48	22, 42 21, 53 24, 38 24, 67 19, 51 23, 43 21, 94 19, 69 22, 59 21, 12	21. 93 20. 69 24. 41 24. 19 19. 07 23. 75 21. 86 19. 71 22. 89 21. 34	20.58 24.15 23.75 19.24 24.05 21.97 19.87 23.43 21.72	21.18 25.12 24.85 19.45 24.71 22.73 20.10 23.86 22.06	22. 32 26. 15 25. 95 20. 04 25. 65 23. 56 20. 17 24. 86 22. 44
7096 7097 7098 7099 7100 7101 7102 7103 7104 7105 7106 7107 7108	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17 THM WBVTR 1 DENT THM WBVTR 2 BAY THM WBVTR 2 BY 15 THM WBVTR 2 CTR THM WBVTR 2 CTR THM NBTR B SEP 6 THM NBTR B SEP 1 THM NBTR BM CTR THM MSS MOUNT 14	DGC	19. 41 19. 21 18. 40 21. 43 21. 26 17. 35 21. 08 19. 05 17. 90 20. 75 18. 95 19. 21	20. 22 18. 60 21. 31 21. 49 17. 46 21. 00 19. 35 18. 06 20. 82 19. 37 19. 18	22, 30 19, 88 23, 35 23, 16 18, 34 22, 80 20, 88 18, 85 22, 16 20, 48 20, 77	22. 42 21. 53 24. 38 24. 67 19. 51 23. 43 21. 94 19. 69 22. 59 21. 12 21. 26	21. 93 20. 69 24. 41 24. 19 19. 07 23. 75 21. 86 19. 71 22. 89 21. 34 21. 59	20.58 24.15 23.75 19.24 24.05 21.97 19.87 23.43 21.72 22.27	21.18 25.12 24.85 19.45 24.71 22.73 20.10 23.86 22.06	22. 32 26. 15 25. 95 20. 04 25. 65 23. 50 20. 17 24. 88 22. 44 23. 89
7096 7097 7098 7099 7100 7101 7102 7103 7104 7105 7106 7107 7108 7109	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17 THM WBVTR 1 DENT THM WBVTR 2 BAY THM WBVTR 2 BY 15 THM WBVTR 2 CTR THM WBVTR 2 CTR THM NBTR B SEP 6 THM NBTR B SEP 1 THM NBTR BM CTR THM MSS MOUNT 14 THM OA -Y THRUSTER	DGC	19. 41 19. 21 18. 40 21. 43 21. 26 17. 35 21. 08 19. 05 17. 90 20. 75 18. 95 19. 21 22. 27	20. 22 18. 60 21. 31 21. 49 17. 46 21. 00 19. 35 18. 06 20. 82 19. 37 19. 18 22. 21	22, 30 19, 88 23, 35 23, 16 18, 34 22, 80 20, 88 18, 85 22, 16 20, 48 20, 77 24, 00	22. 42 21. 53 24. 38 24. 67 19. 51 23. 43 21. 94 19. 69 22. 59 21. 12 21. 26 24. 43	21. 93 20. 69 24. 41 24. 19 19. 07 23. 75 21. 86 19. 71 22. 89 21. 34 21. 59 24. 85	20.58 24.15 23.75 19.24 24.05 21.97 19.87 23.43 21.72 22.27 25.53	21.18 25.12 24.85 19.45 24.71 22.73 20.10 23.86 22.06 22.75 26.63	22. 32 26. 18 25. 98 20. 04 25. 68 23. 50 20. 17 24. 88 22. 44 23. 89 28. 11
7096 7097 7098 7099 7100 7101 7102 7103 7104 7105 7106 7107 7108	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17 THM WBVTR 1 DENT THM WBVTR 2 BAY THM WBVTR 2 BY 15 THM WBVTR 2 CTR THM WBVTR 2 CTR THM NBTR B SEP 6 THM NBTR B SEP 1 THM NBTR BM CTR THM MSS MOUNT 14	DGC	19. 41 19. 21 18. 40 21. 43 21. 26 17. 35 21. 08 19. 05 17. 90 20. 75 18. 95 19. 21	20. 22 18. 60 21. 31 21. 49 17. 46 21. 00 19. 35 18. 06 20. 82 19. 37 19. 18 22. 21 18. 14	22.30 19.88 23.35 23.16 18.34 22.80 20.88 18.85 22.16 20.48 20.77 24.00 19.30	22. 42 21. 53 24. 38 24. 67 19. 51 23. 43 21. 94 19. 69 22. 59 21. 12 21. 26 24. 43 20. 17	21. 93 20. 69 24. 41 24. 19 19. 07 23. 75 21. 86 19. 71 22. 89 21. 34 21. 59 24. 85 20. 27	20.58 24.15 23.75 19.24 24.05 21.97 19.87 23.43 21.72 22.27 25.53 20.60	21.18 25.12 24.85 19.45 24.71 22.73 20.10 23.86 22.06 22.75 26.63 21.05	22, 32 26, 15 25, 95 20, 04 25, 65 23, 50 20, 17 24, 88 22, 44 23, 89 28, 11 21, 29
7096 7097 7098 7099 7100 7101 7102 7103 7104 7105 7106 7107 7108 7109 7110	THM WBVTR STRAP THM WB MT BAY 1 THM WB MAT BAY 1 THM WB WAT BAY 1 THM WBVTR SEP 3 THM WBVTR SEP 17 THM WBVTR 1 DENT THM WBVTR 2 BAY THM WBVTR 2 BY 15 THM WBVTR 2 CTR THM NBTR B SEP 6 THM NBTR B SEP 1 THM NBTR BM CTR THM MSS MOUNT 14 THM OA -Y THRUSTER THM MSS WBVTR BM	DGC	19. 41 19. 21 18. 40 21. 43 21. 26 17. 35 21. 08 19. 05 17. 90 20. 75 18. 95 19. 21 22. 27 17. 94	20. 22 18. 60 21. 31 21. 49 17. 46 21. 00 19. 35 18. 06 20. 82 19. 37 19. 18 22. 21	22, 30 19, 88 23, 35 23, 16 18, 34 22, 80 20, 88 18, 85 22, 16 20, 48 20, 77 24, 00	22. 42 21. 53 24. 38 24. 67 19. 51 23. 43 21. 94 19. 69 22. 59 21. 12 21. 26 24. 43	21. 93 20. 69 24. 41 24. 19 19. 07 23. 75 21. 86 19. 71 22. 89 21. 34 21. 59 24. 85	20.58 24.15 23.75 19.24 24.05 21.97 19.87 23.43 21.72 22.27 25.53	21.18 25.12 24.85 19.45 24.71 22.73 20.10 23.86 22.06 22.75 26.63	21. 05 22. 32 26. 15 25. 95 20. 04 25. 65 23. 50 20. 17 24. 88 22. 44 23. 89 28. 11 21. 29 23. 43 11. 23

Table 11-2. Compensation Load History

COMPENSATION LOADS

Launch 1	. 0	0						8
1		U	0	0	0	0	0	0
1 2 1	0	0	0	0	0	0	0	0
2	0	0	χ	Х	Х	0	Χ	Х
5	0	0	Х	χ	Х	0	Χ	Χ
6	Х	Х	Χ	Х	Х	0	Х	Χ
117	Χ	Χ	χ	Х	Χ	0	Х	Х
118	0	0	0	0	0	0	0	0
155	0	0	0	0	0	0	0	0
156	X	Χ	χ	χ	χ	0	Х	Х
193	Х	Χ	Х	Χ	Χ	0	χ	Х
194	0	0	0	0	0	. 0	0	0
196	0	0	0	0	0	0	0	0
197	Х	Х	Х	X	X	. 0	Х	Χ
700	,Χ	Χ	Χ	Х	Χ	0	Х	Χ
701	Х	Х	0	Х	Х	0	Х	Χ
1409	X	Х	0	Х	Х	0	Х	Х
1410	Х	Χ	0	Х	Х	0	0	Х
2600	Х	Х	0	Х	Χ	0	. 0	Х

NARROWBAND TAPE RECORDERS

The Narrowband Tape Recorder Subsystem continued to operate in a completely satisfactory manner. Since Orbit 1, the two Recorders A and B have alternated in Record and Playback Modes with a nominal one minute overlap.

Table 12-1 lists the telemetry values for Thermo-Vacuum Testing, for the initial orbits and for late orbits. The values vary slightly from orbit to orbit, but are substantially unchanged. The specific differences are shown for Orbit 1950 in Table 12-2. These are typical variations, that rise and subside, and show no trend.

Since launch, each recorder has had an on time of 2281 hours. Each recorder was in the Playback mode for 95 hours and 48 minutes, in the Record mode for 2185 hours and 12 minutes, and in the OFF mode for 2281 hours.

Table 12-3 is a 5% random sample (5 orbits from each week) showing the performance of the NBTR Subsystem in its entirety, including the radio downlink and the ground station processing. At the end of the table, there is a listing of values from early orbits for comparison.

The first two columns show the percentage of bad data and missing data at the end of processing. As can be seen, both are usually zero. Higher values are attributed to noise on the radio downlink.

The third column shows the data rate, nominally 24 kilobits, reflecting the speed of the motor during playback. The true value varies from 23.83 to 23.87 averaging 23.85 showing that the playback motor speed is slightly less than planned. This has no effect on the fidelity of the playback, but only increases the playback time by less than 1%.

The last column shows the extent of the "wow" and "flutter" effects in a major frame. It is characteristically 2 or 3 hundredths of 1%, a completely satisfactory value. The occasional high values are attributed to noise effects.

Since the complete subsystem shows satisfactory performance, each of its component parts are therefore satisfactory, including the Narrowband Tape Recorders.

In Table 12-3 it will be noticed that for those orbits with a high percentage of bad or missing data, or high standard deviation of the data rate, the A recorder was in use for 72% of the orbits. This is not considered significant however, due to the sampling technique and the fact that the B recorder was also significantly involved—in fact, the highest percent missing data, and the highest deviation of the data rate was with the B recorder. Although the study is continuing, it is concluded from present data that the abnormalities are due to noise, and not recorder malfunction.

Table 12-1. Narrowband Tape Recorder Telemetry Values

			Typical Tele	emetry Values			
	Function	Thermal Vac	Orbital Values				
Number	Name	Values	6	1959	1951		
10001	A - Motor Cur. (ma)						
	Record P/B	198 185	190.10 180.00	189.47 177.63	189.47 -		
10101	B - Motor Cur. (ma)				·		
	Record P/B	194 185	193.26 188.18	192.79 -	192.63 189.47		
10002	A - Pwr Sup. Cur. (ma)						
	Record P/B	315 540	320.56 535.78	339.81 563.11	339.81		
10102	B - Pwr Sup. Cur. (ma)						
	Record P/B	313 535	317.62 570.78	333 . 75	333.75 567.50		
10003	A - Rec. Temp. (DGC)	25.4	25.47	26.25	26.25		
10103	B - Rec. Temp. (DGC)	23.8	24.58	25.38	25. 38		
10004	A - Supply (VDC)	-24.55	-24.47	-24.50	-24.50		
10104	B - Supply (VDC)	-24.49	-24.44	-24.57	-24.57		

Table 12-2. Narrowband Tape Recorder Telemetry Changes

	Orbit 1950							
	Rec % Chang	ord	Playback % Change from					
	Thermal Vac	Early Orbit	Thermo Vac	Early Orbit				
10001 A Motor Cur. 10101	-4.3	-0.3	-4.0	-1, 3				
B Motor Cur.	-0.7	-0,3	+2.3	+0.7				
10002 A Pwr Sup Cur.	+7.9	+6.0	+4.3	+5, 1				
10102 B Pwr Sup Cur.	+6.6	+5,1	+6.1	-0.6				

FOLDOUT FRAME 2

Table 12-3. Narrowband Recorder Subsystem Performance

	% DATA			DATA R	ATE	
ľ	ORBIT	BAD	MISSING	MEAN	STD. DEV.	NBTR*
	1320 1337	0.01	0.00	-23.85 -23.85	0.03 0.03	
	1356 1375	0.00 0.50	0.00	-23.85 -23.83	0.03 0.86	A
	1394 1407	0.00	0.00	-23.82 -23.84	0.02 0.03	
	1439 1459	0.25 0.01	0.78 0.00	-23.85 -23.83	0.98 0.02	В
	1473 1495	0.00	0.00	-23.83 -23.83	0.02 0.02	. ,
	1506 15 1 8	0.00	0.22 0.13	-23.85 -23.87	0.03 0.03	A
١	1536 1557	0.00	0.00	-23.85 -23.83	0.03 0.13	
	1588 1616	0.00	0.26 0.13	-23.87 -23.87	0.03 0.03	A
	1640 1650	0.00 0.08	0.00	-23.84 -23.83	0.03 2.80	В
	1678 1691	0.00	0.00	-23.84 -23.84	0.02	
	1706 1724	0.10	0.00	-23.86 -23.84	0.68	A
	1732 1765	0.00	0.13	-23.87 -23.83	0.03	
	1790 1813	0.01 0.00	0.00	-23.84 -23.84	0.03	
	1820 1840	0.00	0.00	-23.84 -23.85	0.03	
	1873 1897	0.00 0.31	0.30	-23.83 -23.84	0.02	B A
	1926 1941	0.24	0.00	-23.86 -23.85	0.67	A A
.	1960 1980	0.00	0.00	-23.85 -23.84	0.03	B
	1999 2013	0.00	0.00 0.54 0.00	-23.84 -23.84 -23.85	0.03 0.03 0.03	A
	2041 2065 2076	0.01 0.01 0.00	0.00	-23.86 -23.85	0.02	
	2076 2091 2113	0.00	0.23	-23.85 -23.84	0.57	A A
	2148 2169	0.00	0.00	-23.85 -23.83	0.03	В
	2179 2179 2192	0.10	0.00	-23.83 -23.85	0.02	Ā
	2192 2221 2231	0.00	0.00	-23.85 -23.85	0.03	
	2250 2265	0.00	0.30	-23.83 -23.85	0.02	A
	2287 2337	0.19	0.00	-23.85 -23.85	0.54	A
	2351 2371	0.00	0.00	-23.85 -23.85	0.03	A
	2388 2396	0.03 0.01	0.00 0.24	-23.85 -23.85	0.03 0.04	A
	2417 2438	0.00	0.00 0.28	-23.83 -23.85	0.02 0.03	A
	2453 2474	0.00 0.00	0.13 0.25	-23.85 -23.85	0.03 0.03	A
	2496 2510	0.00	0.00	-23.85 -23.85	0.60	<u>А</u>
	2523 2554	0.00	0.14	-23.85 -23.85	0.03 0.02 0.02	
	2571 2599	0.00	0.00	-23.83 -23.85	0.02	
	SAMPLE	FROM EAR	LY ORBITS		T	1
	925 927	0.03 0.01	0.00	-23.85 -23.85	0.03	
	950 951	0.68	0.00	-23.86 -23.83	1.01	В
	953	0.00	0.00	-23.82	0.02	<u> </u>

^{*}The NBTR in use is identified for only those orbits with high % of bad or missing data or high standard deviation of the data rate.

WIDEBAND TELEMETRY SUBSYSTEM

The Wideband Telemetry Subsystem has operated satisfactorily since launch, including both its Wideband Power Amplifiers (WPA No. 1 and WPA No. 2).

WPA No. 1, normally associated with RBV, was not used after orbit 196 because the RBV was off due to a failure in the power input circuit (see Section 14). Between Orbits 1891 and 2100, however, WPA No. 1 was substituted for WPA No. 2 to operate with the MSS because its frequency was less likely to cause interference with frequencies being used for the flight of Apollo 17 which occurred at that time.

WPA No. 1 has had a cumulative ON time of 31 hours 55 minutes and 9 seconds, operating nearly equally in the real-time and the playback modes.

WPA No. 2 has had a cumulative ON time of 235 hours, 54 minutes and 48 seconds, with practically equal operating times in real-time and playback modes.

Table 13-1 lists the telemetry values for the Wideband Telemetry Subsystem. All values are normal.

It is interesting to note that WPA No. 1 after being idle from orbit 196 on 6 August until orbit 1890 on 6 December (four months) came back on the air with a power output lowered by 0.3 dB. The output power, after dropping slightly, finally increased so that after 200 orbits it had regained its post launch value. WPA No. 2 has remained practically constant since it was put in the 20 watt mode in orbit 30.

Figures 13-1 and 13-2 show the ground station (Goldstone) AGC readings as a function of slant range. Superimposed on these plots are a few points from the earliest orbits, and a few from the latest orbits, in order to show there is no significant trend upward or downward with passing time, confirming the power output measurement reported by telemetry.

Table 13-1. Wideband Modulator Telemetry Values

			T	T				
WBPA-	<u>1</u>							
	Function							
	runction		T/ V*					
Number	Name		Values	26	1849	1944	2095	
						1		
12001	Temp TWT Coll.	(DgC)	38.7	35.7	39.20	39.90	39.90	
12002	Helix Current	(M a)	6.47	6.08	6.49	6.58	6.78	
12003	TWT Cath. Cur.	(Ma)	45.4	45.89	43.54	43.48	45.01	
12004	Forward Pwr	(DBM)	43.2	43.18	42.88	42.61	43.15	
12005	Reflected Pwr	(DBM)	32.4	34.95	34.99	34.80	35.21	
12227	Loop Str. AFC ConVolt	(MHZ)	(1)	-0.39	-1.26	-0.86	-0.67	
12229	Mod Temp VCO	(DgC)	24.4	21.93	20.31	20.88	20.39	
12232	+15VDC A ⁽³⁾ Pwr Sup (3)	(TMV)	2.69	2.69	2.69	2.65	2.62	
12234	-15 VDC Pwr Sup A	(TMV)	5.91	5.98	5.96	5.73	5.78	
12236	+5 VDC Pwr Sup A	(TMV)	4.01	3.94	3.94	3.94	3.95	
12238	-5 VDC Pwr Sup A	(TMV)	5.26	5.28	5.26	5.1 8	5. 1 2	
12240	-24 VDC Unreg Volt A	(TMV)	5.42	5.56	5.51	5.42	5.49	
12242	Inv. Temp	(DgC)	24.5	20.60	23.43	24.71	24.04	
WBPA-	2				L	<u> </u>	<u> </u>	
	Function		T/ V*	Orbits				
Number	Name		Values (2)	22				
Transcr	Traine	· · · · · · · · · · · · · · · · · · ·	values	33	1555	2128	2595	
12101	Temp TWT Coll.	(DgC)	31.5	35.38	37.11	36.54	34.80	
12102	Helix Current	(Ma)	5.26	7.32	7.37	7.57	7.46	
12103	TWT Cath. Cur.	(Ma)	33.5	44.30	42.50	42.65	42.52	
12104	Forward Pwr	(DBM)	41.2	43.57	43.44	43.54	43.35	
12105	Reflected Pwr	(DBM)	30.6	31.59	32.37	32.59	32.11	
12228	Loop Str HFC ConVolt	(MHZ)	(1)	1.11	-0.30	-0.43	-1.01	
12229	Mod Temp VCO	(DgC)	24.4	21.70	24.57	22.87	24.04	
12232	+15 VDC A(3) Pwr Sup	(TMV)	2.67	2.68	2.68	2.69	ł.	
12234	-15 VDC Pwr Sup A	(TMV)	5.95	5.90	5.88	5.91	2.58 5.71	
12236	+5 VDC Pwr Sup A	(TMV)	4.01	3.97	3.97		5.71 3.91	
12238	-5 VDC Pwr Sup A	(TMV)	5.26	5.24		4.02 5.25		
12240	-24.5 VDC Unreg Volt A	(TMV)	5.42	5.43	5.25 5.20	5.25 5.42	5.05	
12242	Inv. Temp	(DgC)	24.5	23.03	5.39 23.88	5.42 24.69	5.33 22.95	
L	_	\ 3-7			20,00	27.00	<i>22.00</i>	

^{*}Thermal Vacuum Test Data

⁽¹⁾ Satisfactory if not zero or -7.5.

⁽²⁾ Tested T/V in 10-watt mode; put in 20-watt mode in Orbit 30 and used in that mode since. Thermal vacuum values not representative for orbital operation, therefore.

⁽³⁾ B Power Supply not used in orbit.

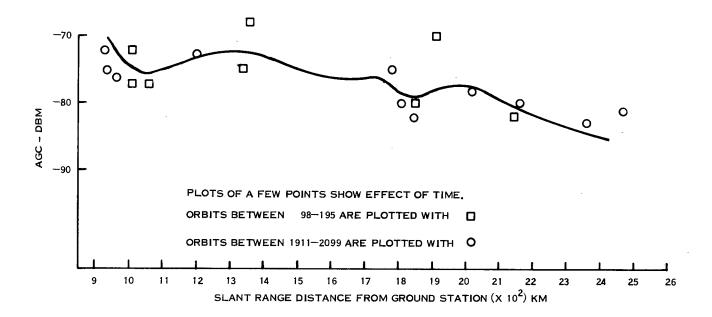


Figure 13-1. WPA-1 Ground Station AGC Readings

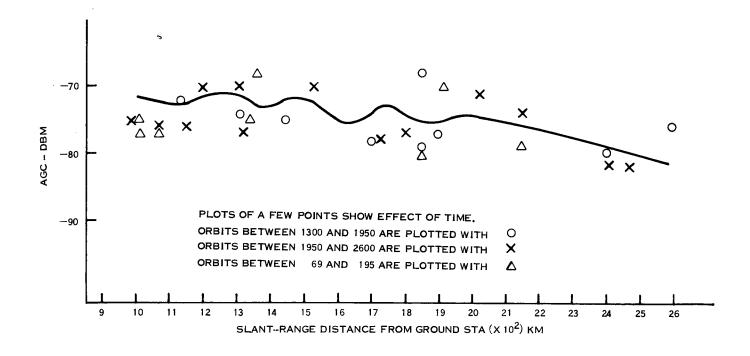


Figure 13-2. WPA-2 Ground Station AGC Readings

SECTION 14 ATTITUDE MEASUREMENT SENSOR

The AMS has consistently produced attitude values which seem reasonable. Since no direct precise correlation can be made with the Attitude Control System the AMS values are accepted. Effort is continuing to refine techniques to evaluate AMS performance. Occasionally the AMS error exceeds one degree in -roll during satellite day. The highest error noted was 1.2° as illustrated in Figure 14-1, at this time, the ACS fine error in roll indicated 0.92° -roll. This excursion beyond one degree error is caused by inhibiting the ACS gating during satellite day and permitting gates only during night. The AMS sensor is functioning properly. The wheel speed at this error was 1250 RPM. Gating, if permitted, would occur at 925 RPM.

Table 14-1 gives typical AMS telemetry values.

Table 14-1. AMS Temperature Telemetry Summary

Function			*T/V 20°C	Orbit				
No.	Name	Units	Plateau	35	1799	2201	2600	
3004	Case - Temp 1	°C	19.1	18.92	19.92	20.18	20, 05	
3005	Assembly - Temp 2	°C	18.9	19.15	20, 25	20.18	20.27	

^{*}Thermal Vacuum Test Data

1024/1020

Figure 14-1. Attitude Measurement Sensor Performance Characteristics Type

FOLDOUT FRAME

WIDEBAND VIDEO TAPE RECORDERS (WBVTR-1 AND WBVTR-2)

The Wideband Video Tape Recorder Subsystem consists of two components, WBVTR-1 and WBVTR-2.

WBVTR-2 failed in orbit 148 (see Appendix B) after nine hours, 26 minutes and 33 seconds of satisfactory performance.

WBVTR-1 has operated satisfactorily since being put into operational use in Orbit 26, for a cumulative ON time of 392 hours, 20 minutes and 56 seconds. Of this time, the video head was in contact with the moving tape for 310 hours. During the pre-launch testing, there were 126 hours of such contact as of 23 July 1972. (Launch was 23 July 1972.) It is estimated that 500 hours—the specified minimum performance time—of such contact will be reached about Orbit 3200 in early March 1973.

Table 15-1 lists typical telemetry values for WBVTR-1 for the orbits of this report period. All values are normal. The values for WBVTR-2 were also included for completeness and convenience.

Table 15-2 shows the telemetry values for the indicated functions for each operational mode in Orbit 2379, which included Standby, Record, Rewind and Playback.

As a measure of the fidelity of the Wideband Video Tape Recorder, the minor frame sync error (MFSE) count experienced by the Multispectral Scanner Subsystem (MSS) was observed. During real-time transmissions of MSS data, the MFSE count is invariably zero; during playback of MSS data recorded on the WBVTR the MFSE count can then be used to measure the degradation contributed by the WBVTR. Counts during 10-second intervals are made. Figure 15-1 shows a plot of typical values of these 10-second count averages. There is no discernible trend upward or downward in the MFSE count.

Table 15-1. WBVTR Telemetry Values

WBV	TR-1 Functions		T	1		ry Values	
Number	Name		In T/ V*	15	1347	Orbits 2073	2599
			·				
13022	Pressure Trans	(PSI)	16.3	16.12	16.43	16.46	16.38
13023	Temp Trans	(DgC)	22.0	19.50	25.53	26.55	25.05
13024	Temp Elec	(DgC)	28.7	22.78	29.44	30.39	25.34
13026	Capstan Speed	(%)	98.0	100.51	96.63	95.44	98.25
13027	Headwheel Speed	(%)	99.6	95.16	97.99	97.97	96.84
13028	Capstan Mot I	(Amp)	0.24	0.25	0.27	0.24	0.26
13029	Input P/B Volt.	(VVP)	20.76	0.72	0.44	0.44	0.41
13030	Headwheel Mot I	(Amp)	0.55	0.55	0.53	0.53	0.55
13031	Rec Input I	(Amp)	3.55	3.15	3.53	3.50	3.31
13032	Lim Volt Out	(VPP)	1.48	1.44	1.45	1.47	1.42
13033	Servo Volt	(%)	50.0	50.03	50.07	50.38	50.23
13034	+5.6 VDC Conv	(VDC)	5.66	5.66	5.72	5.66	5.71
13200	-24.5 VDC	(VDC)	1	-24.91	-24.91	-24.90	-24.90
13201	-12 VDC	(VDC)	1	-12.08	-12.08	-12.08	-12.08
13202	Temp APU	(DgC)		25.79	27.12	27.95	28.24
			•				
WBV	TR-2 Functions						
			In		Orbit N	lumber	
Number	Name		T/ V *	15	64	103	147
13122	Pressure, Trans	(PSI)	3	15.99	16.25	16.25	16.11
13123	Temp Trans	(DgC)		18.46	19.19	20.72	21.09
13124	Temp Elec	(DgC)		21.50	22.00	24.00	21.92
13126	Capstan Speed	(%)		99.91	100.53	100.80	99.38
13127	Headwheel Speed	(%)		94.16	95.48	97.64	98.78
13128	Capstan Mot I	(Amp)		0.17	0.24	0.24	0.28
13129	Input P/B Volt.	(VPP)		0.66	0.63	0.62	0.61
13130	Headwheel Mot I	(Amp)		0.55	0.59	0.52	0.53
13131	Rec Input I	(Amp)		3.70	3.53	3.07	3.43
13132	Lim Volt. Out	(VPP)		1.34	1.41	1.41	1.39
13133	Servo Volt	(%)	İ	49.47	49.60	49.80	49.48
13134	+5.6 VDC	(VDC)		5.47	5.64	5.58	5.59
13200	-24.5 VDC	(VDC)	ļ	-24.91	-24.90	-24.90	-24.90
13201	-12 VDC	(VDC)		-12.08	-12.08	-12.08	-12.09
13202	Temp APU	(DgC)		25.79	26.31	27.64	26.19
ı .	-	\ 0 -/			-0.01		1 -0.10

^{*}Thermal Vacuum Test Data

¹ Thermal VacValues not given

² After Orbit 196 WBVTR-1 configured to MSS: Thermo Vac Value then 0.40.

³ Thermal Vacuum Data are not available for WBVTR-2.

Table 15-2. Function Values by Mode in Orbit 2379

Function	Pla	yback	Sta	ndby	Re	wind	Rec	ord
	T/V	2379	T/V	2379	T/V	2379	T/V	2379
13034	5 . 66	5. 44	5.86	5.89	5.86	5, 89	5.63	5.71
13029	0.37	0, 45	0	0	0	0	0	0
13028	0.25	0.25	0	0	0.18	0.20	0.28	0.24
13030	0.56	0, 55	0.45	0.44	0.50	0.44	0.55	0.55
13031	3.27	3, 89	2.04	2.08	2.16	2.18	3.55	3, 63
13022	16.3	16.4	16.3	16.4	16.3	16.4	16.3	16. 4
13032	1.48	1.48	0	0	0	0	0	0
13033	50.0	50.37	0	0	0	0	0	0
13026	98.0	97.2	0	0	102.20	101.1	99.60	96. 7
13027	99.7	97.8	103.10	102.8	101.90	100.7	99.60	100.1
13023	22.0	25.5	22.0	26.0	22.0	26.0	22.0	27.5
13024	28.7	28, 5	28.7	29.5	28.7	29.0	28.7	31.6

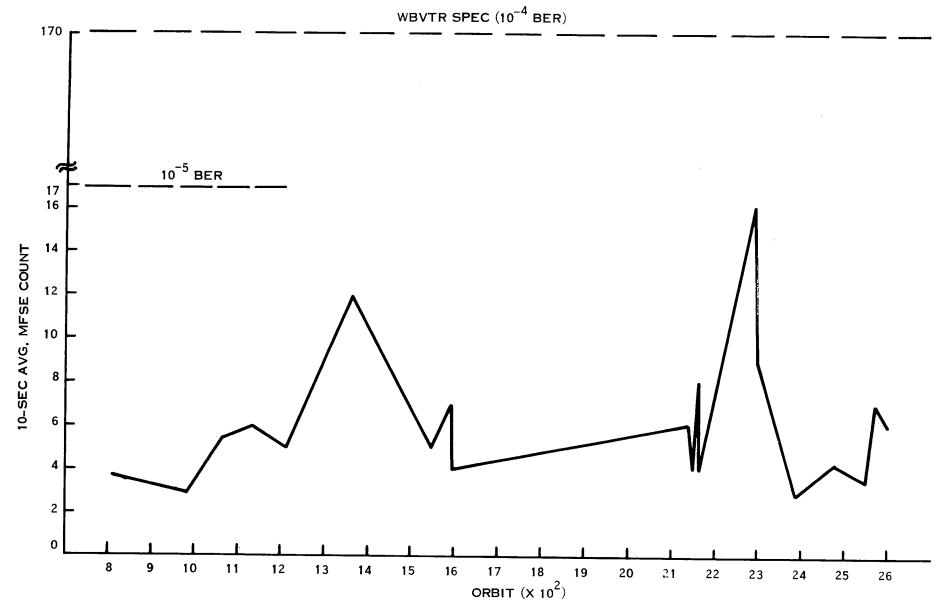


Figure 15-1. Typical Average Values of MSS Minor Frame Sync Error (MFSE) Counts Over 10-Sec Intervals for WBVTR-1 Playback

RETURN BEAM VIDICON

The Return Beam Vidicon (RBV) Subsystem operated normally from turn-on in Orbit 19 to Orbit 196 when it failed to respond to an off command. The RBV itself was not the cause of the failure, nor was it affected by the failure. The complete bench test report of this study is given in Appendix B. The RBV has not been reactivated since Orbit 196.

An assessment of the RBV performance was given in ERTS-1 Flight Evaluation Report 23 July to 23 October, 1972. For completeness and convenience, the telemetry values are repeated in Table 16-1.

Table 16-1. RBV Telemetry Values

	FUNCT ION		ORB	ITS		· · · · · · · · · · · · · · · · · · ·
	•	T/V				
NO.	NAME	VALUE	26	85	149	196
		:				
14001	CCC Board Temp. (DgC)	(1)	18.61	20.04	19.30	19.53
14002	CCC Pwr. Sup. Temp (DgC)	(1)	19.93	21.58	20.70	21.21
14003	<u>+</u> 15 VDC Sup. (TMV)	3.95	3.69	3.95	3.78	3.95
14004	+6V-5.25 VDC Sup. (TMV)	3.05	2.84	2.93	2.98	3.05
14100	VID OUT CAM 1 (TMV)	1.06	1.04	1.15	1.13	1.12
14200	VID OUT CAM 2 (TMV)	1.09	1.05	1.26	1.23	1.24
14300	VID OUT CAM 3 (TMV)	1.05	1.03	1.21	1.19	1.20
14102	Comb. Align I Com 1 (TMV)	3.95	3.67	3.94	3.87	3.94
14202	Comb. Align I Com 2 (TMV)	3.92	3.90	3.91	3.89	3.91
14302	Comb. Align I Com 3 (TMV)	4.04	3.75	4.03	3.80	4.03
14103	Cam l Elec Temp. (DgC)	(1)	20.84	23.37	22.64	25.38
14203	Cam 2 Elec Temp. (DgC)	(1)	18.64	21.06	20.62	22.87
14303	Cam 3 Elec Temp. (DgC)	(1)	21.05	23.61	23.23	25.57
14104	Cam 1 LV Pwr Sup T. (DgC)	(1)	21.71	23.94	23.49	25.92
14204	Cam 2 LV Pwr Sup T. (DgC)	(1)	18.38	20.63	19.40	23.30
14304	Cam 3 LV Pwr Sup T. (DgC)	(1)	20.75	23.02	22.73	25.6
14105	Cam 1 Def. + 10 VDC (TMV)	4.01	3.73	4.00	3.77	4.00
14205	Cam 2 Def. + 10 VDC (TMV)	4.00	3.71	3.98	3.77	3.98
14305	Cam 3 Def. + 10 VDC (TMV)	3.97	3.95	3.95	4.02	3.99
14106	Cam 1 + 6V - 6.3 VDC (TMV)	3.71	3.45	3.70	3.61	3.70
14206	Cam 2 + 6V - 6.3 VDC (TMV)	3.69	3.42	3.67	3.49	3.6
14306	Cam 3 +6V -6.3 VDC (TMV)	3.73	3.47	3.72	3.47	3.72
14107	Cam l Telec I (TMV)	2.62	2.50	2.54	2.55	2.64
14207	Cam 2 Telec I (TMV)	2.65	2.53	2.56	2.41	2.64
14307	Cam 3 Telec I (TMV)	2.64	2.54	2.51	2.45	2.6
14108	Cam l Vid Fil I (TMV)	2.47	2.30	2.36	2.38	2.46
14208	Cam 2 Vid Fil I (TMV)	2.54	2.37	2.52	2.39	2.5
14308	Cam 3 Vid Fil I (TMV)	2.61	2.44	2.60	2.53	2.60
14110	Cam l TARVOLT (TMV)	3.43	3.42	3.42	3.45	3.43
14210	Cam 2 TARVOLT (TMV)	3.36	3.13	3.22	3.26	3.3
14310	Cam 3 TARVOLT (TMV)	3.47	3.23	3.46	3.45	3.4
14113	Cam l Vert Def V (TMV)	2.96	2.75	2.90	2.85	2.9
14213	Cam 2 Vert Def V (TMV)	3.00	2.86	2.98	2.86	3.0
14313	Cam 3 Vert Def V (TMV)	3.45	3.45	3.47	3.37	3.4
14114	Cam l Vid FPT (DgC)	(1)	18.15	20.77	17.91	20.9
14214	Cam 2 Vid FPT (DgC)	(1)	20.62	20.11	20.52	20.6
14314	Cam 3 Vid FPT (DgC)	(1)	18.54	20.88	19.08	20.20
14115	Gam 1 Foc Coil T (DgC)	(1)	17.71	21.67	18.74	19.70
14215	Gim 2 Foc Coil T (DgC)	(1)	17.70	21.60	19.25	19.97
14315	Cam 3 Foc Coil T (DgC)	(1)	18.03	22.09	1988	20.56

⁽¹⁾ Thermo-Vacuum temperatures for these functions were not reported.

MULTISPECTRAL SCANNER SUBSYSTEM

The Multispectral Scanner Subsystem (MSS) continued to operate satisfactorily. Since launch the MSS has had 3073 on-off cycles, imaging 35, 331 scenes covering 307.9 x 10⁶ square nautical miles of earth surface, amounting to over seven times the total earth land masses. The operating time was 350 hours, 21 minutes and 57 seconds, operating 44% in the real time mode and 56% in the record mode. The average number of scenes imaged per day since launch was 195 neglecting scheduled off-days in the flight activation period and in the period following Orbits 148 and 196 when studies were being made of the WBVTR-1 and RBV operational anomalies.

There has been no command anomalies associated with the MSS since launch.

Telemetry values have been normal since launch as is shown in the typical readings in Table 17-1.

Figure 17-1 shows the history of the line length variations. Past Orbit 400, the maximum-to-minimum spread is less than 3 words.

The calibration wedges, which showed a decreasing quantum level for the first 1200 orbits in bands 1 and 2, levelled off, and now show a tendency to rise. Figure 17-2 is a typical plot of this aspect.

The mux transfer function was checked by switching from compressed to linear mode in sequence during the same operating period of Orbit 2375. The sequence was reversed in a subsequent Orbit (2389). Evaluation of the resulting data shows there has been no significant changes in this transfer function.

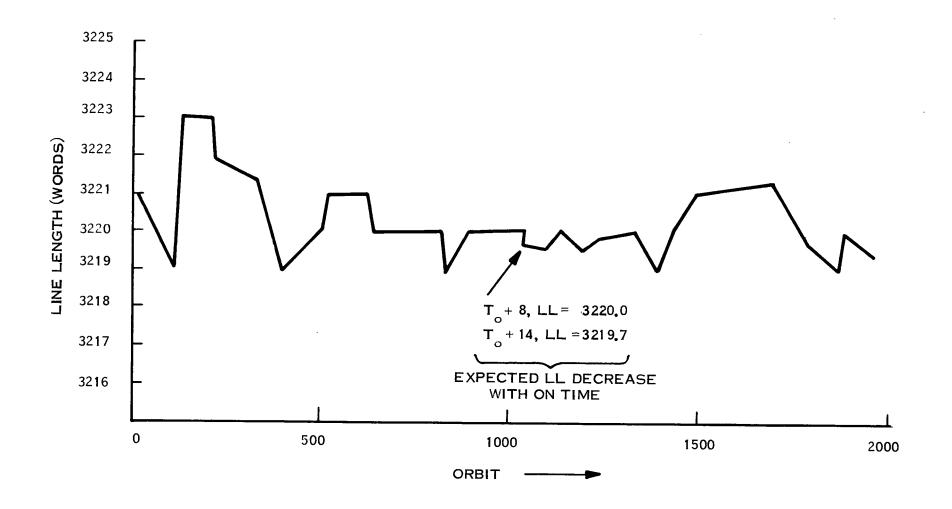


Figure 17-1. Line Length vs Orbit

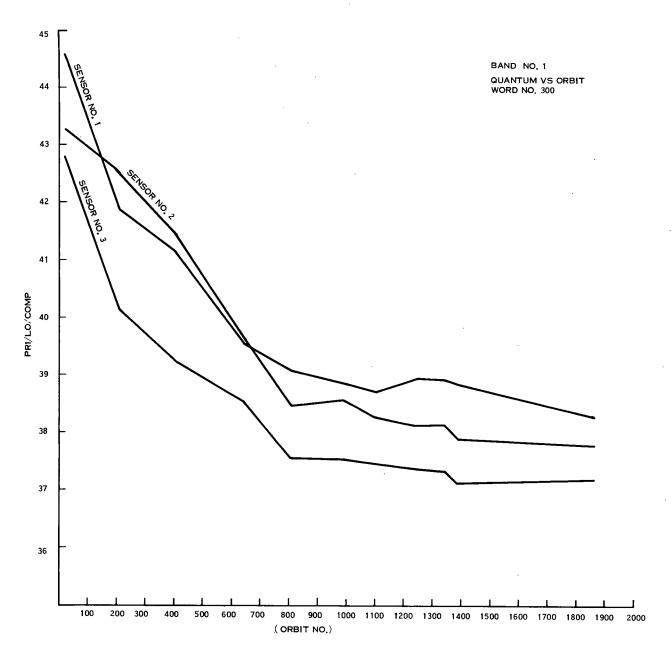


Figure 17-2. Cal Wedge Quantum vs Orbit

Table 17-1. MSS Telemetry Values

		1		T	<u> </u>		<u> </u>
Function No.	Name		T/V Val *	20	1581	1961	2599
15044	FOPT 2 T	(DGC)	20.5	17.46	19.85	20.83	21.03
15046	ELEC CVR T	(DGC)	21.5	19.37	21.89	23.27	23.53
15048	SCAN MIR REG T	(DGC)	22.8	16.35	20.39	22.28	22.84
15050	SCAN MIR DR. COIL T	(DGC)	22.4	15.94	19.68	21.58	21.97
15052	ROT SHUT HSG T	(DGC)	20.8	16.91	19.41	20.62	20.88
15043	FOPT 1 T	(DGC)	20.6	17.67	20.02	20.98	21.17
15045	MUX PWR CASE T	(DGC)	22.4	21.19	23.62	25.72	26.84
15047	PWR SUP T	(DGC)	21.6	17.41	20.28	21.64	21.95
15049	SCAN MIR DR. ELC T	(DGC)	22.8	16.12	20.07	22.20	22.76
15051	SCAN MIR HSG T	(DGC)	21.1	15.60	19.42	21.02	21.46
15040	MUX -6 VDC	(TMV)	3.95	4.03	4.03	3.89	4.03
15042	AVG DENS DATA	(TMV)	1.76	1.67	2.10	2.13	2.52
15054	CAL LAMP CUR A	(TMV)	1.06	1.08	1.10	1.09	1.10
15056	BAND 2 ± 15 VDC	(TMV)	5.05	5,10	5.10	4.93	5.10
15058	BAND 4 ± 15 VDC	(TMV)	5.00	5,10	5.10	4.93	5,10
15060	+12 - 6 VDC REG	(TMV)	4.90	4.82	5,02	4.91	4.92
15062	+19 VDC REC OUT	(TMV)	4.81	4.80	5.01	4.89	4.90
15064	BAND 1 HV A	(TMV)	5.21	5.10	5.13	5.01	5.12
15066	BAND 2 HV A	(TMV)	4.46	4.50	4.52	4.42	4.52
15068	BAND 3 HV A	(TMV)	4.58	4.60	4.62	4.52	4.63
15070	SHUT MOT CON OUT	(TMV)	2.46	2.43	2.51	2.44	2.46
15041	A/D CONV REF V	(TMV)	5,82	5.93	5.93	5. 80	5.82
15053	SCAN MIR REG V	(TMV)	4.44	4.42	4.63	4.53	4.53
15055	BAND 1 ± 15V	(TMV)	4.94	4.97	4.97	4.86	4.97
15057	BAND 3 ± 15V	(TMV)	4.94	5.00	5.00	4.82	5.00
15059	-15 VDC TEL.	(TMV)	5.02	5,02	5,02	5 . 0 2	5.02
15061	±5 VDC LOGIC REG	(TMV)	4.80	4.82	4.77	4.80	4.80
15063	-19 VDC REG OUT	(TMV)	3.42	3,43	3.50	3.46	3.50
15071	SCAN MIR DR. CLK	(TMV)	1.94	1.93	2.00	1.96	1.97

^{*} THERMAL VACUUM TEST DATA

(HV SUPPLY B NOT USED YET IN ORBIT)

Signal-to-Noise ratios (S/N) for the MSS sensors are derived from calibration wedge data. A typical plot is shown in Figure 17-3. Evaluation of all the sample data shows there has been no major S/N degradations for the MSS sensors. Attempts to derive S/N figures by sun calibration input pulse data were successful in the last three bands.

The MSS sun calibration orbits are listed in Table 17-2.

Mid-scan symmetry is evaluated by commanding mid-scan code on, processing the resultant data to 70 mm film, and measuring the position of the mid-scan along the base line assuming 3220 elements per line. This method was adopted as it yields a measure of Error Bit Rate variations during film processing. The data shows no significant change in scan symmetry (up to orbit 327. A later orbit is presently being evaluated.)

Table 17-2. MSS Sun Calibration Orbits

21	1303
47	1400
89	1497
103	1595
131	1692
214	1790
326	1887
423	1985
521	2082
619	2180
730	2278
814	2375
915	2389
1012	2473
1207	2585

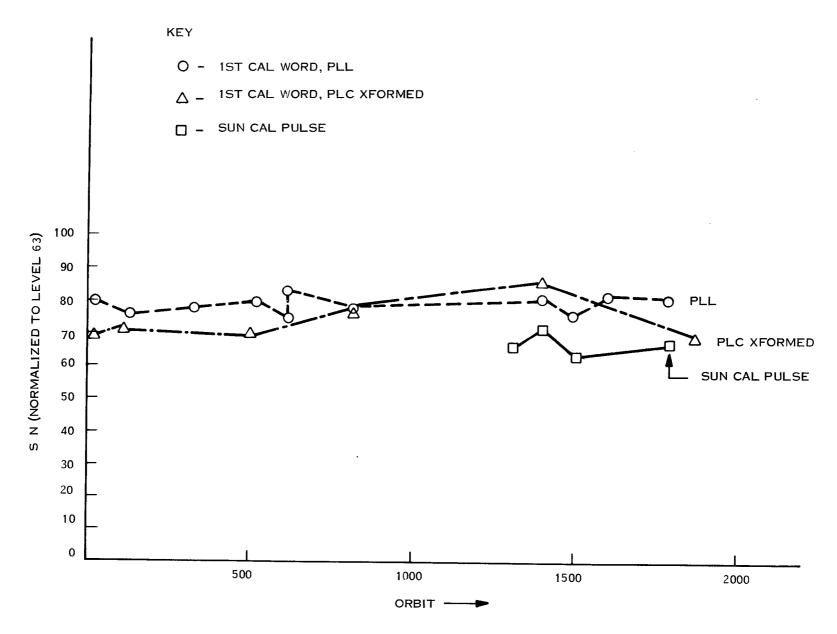


Figure 17-3. CWI, S/N and Sun Calibration S/N

DATA COLLECTION SUBSYSTEM

The Data Collection Subsystem has operated satisfactorily since launch. Periods of interference have been experienced, and one period of not fully explained decreased activity was observed, but normal operation has followed all such incidents.

All telemetry functions have been normal as shown in the typical values of Table 18-1.

			T/V* 20°C		Value	in Orbit	s
Number	Name	Units	Plateau	16	1581	2035	2599
16001	Revr l Sig Str	(DBM)	-119	-124.09	-123.68	-124.47	-124.39
16002	Revr l Temp	(DGC)	23.0	22.72	23.67	25.49	24.07
16003	Revr l Inp Volt	(VDC)	12.02	12.02	12.02	12.01	12.01

Table 18-1. DCS Telemetry Values

Receiver 2 has not yet been used in orbit.

Cumulatively from launch for this subsystem, 129,750 messages were received of which 119,364 (84.5%) were perfect. Considerable interference, externally generated, was experienced during this reporting period causing the large number of non-perfect messages. In periods without obvious interference, perfect messages exceed 95%. 218 ground platforms have been active, with a maximum of 83 active during one orbit. The maximum number of messages received in one orbit was 384 in Orbit 2523.

Messages are received from 7 or 8 orbits per day at two ground stations, Greenbelt and Goldstone. The average number of messages per orbit has been 100.

Thirty users from the United States and Canada include federal, states, universities and private investigators. Appendix C lists the names, affiliations, and locations of users and platforms.

^{*}Thermal Vacuum Test Data

The DCS Subsystem has been ON since launch for a cumulative total of 4467 hours and 6 minutes.

Reception probability has remained at 99% except for an unusual 9-day period when the probability dropped to 71% after which it rose again to the 99% level.

In the first Quarterly Report (23 July to 23 October 1972) reception from DCS platform 6115 was analyzed for orbits in the third, fourth and fifth 18-day cycles. Table 18-2 compares the messages received from Platform 6115 in this reporting period with those of the same orbital trace received during the prior reporting period. It is seen there was equal probability of reception.

Table 18-3 shows a similar comparison for orbits in the unusual 9-day cycle. It is seen the probability of reception dropped to 71%.

Table 18-2. Comparison of Reception Probability for Platform 6115.

3rd and 4th Cycle Orbits	Mes. Rec.	Mes. Rec.	7th and 9th Cycle Orbits
710	3	3	1714
717	2	3	1721
7 23	2	2	1727
724	3	3	1728
730	4	4	1734
731	3	2	1735
737	3	3	1741
738	4	3	1742
744	3	4	1748
1002	3	2	2257
1003	2	3	2258
1009	4	4	2264
1010	2	2	2265
1016	2	4	2271
1017	3	4	2272
1022	3	1	2277
1023	4	4	2278
Total	50	51	

Table 18-3. Reception Probability in Unusual 9-Day Period for Platform 6115

3rd, 4th and 5th Cycle Orbits	Mes. Rec.	Mes. Rec.	7th and 8th Cycle Orbits
841	3	3	1845
	l t	2	1846
842	$\frac{1}{2}$		1853
849	3	3	
850	2	2	1854
855	4	3 .	1859
856	2	4	1860
862	2	1	1866
863	3	3	1867
864	2	1	1868
869	3	2	1873
870	2	4	1874
876	2	2	1880
877	3	2	1881
1143	2	1	1896
1148	3	2	1901
1149	3	-	1902
695	3	2	1950
696	4	0	1951
697	1	0	1952
702	3	2	1957
703	3	1	1958
711	1	ō	1966
725	1 1	0	1980
120			1000
Total	56	40	

Figure 18-1 shows the history of messages received in a time span including the unusual 9-day period. The trend is shown, the percentage of bad messages are plotted, and the unusual 9-day period is identified.

Figures 18-2 and 18-3 show, for Greenbelt and Goldstone respectively, the messages received for each pass in this unusual 9-day period. Passes 1 through 4 are night-time passes and Passes 5 through 8 are day-time passes. The Greenbelt performance appears to have been most affected. Two contributions to the poor performance can be seen: a

missed ETC orbit in Day 342; and the confluence of at least two 18-day cyclic effects—the orbital drift out of range of Passes 4 and 7 and the orbital drift to marginal ranges of Passes 1, 2 and 6. Still under investigation are the lower-than-expected number of messages received on all passes. See Table 18-3.

Table 18-4 summarizes the DCS performance to date.

Table 18-4. DCS Performance to Date

Reception probability (norm)	99%
Reception probability (unusual 9-day period)	71.0%
Invalid messages (including long periods of known interference)	15.5%
System threshold	3400 km
Grazing angle effects	None observed
Adjacent DCP performance	No adverse effect
Ground Transmission System	Satisfactory
Data processing system performance (msg. received/msg. delivered)	0.656

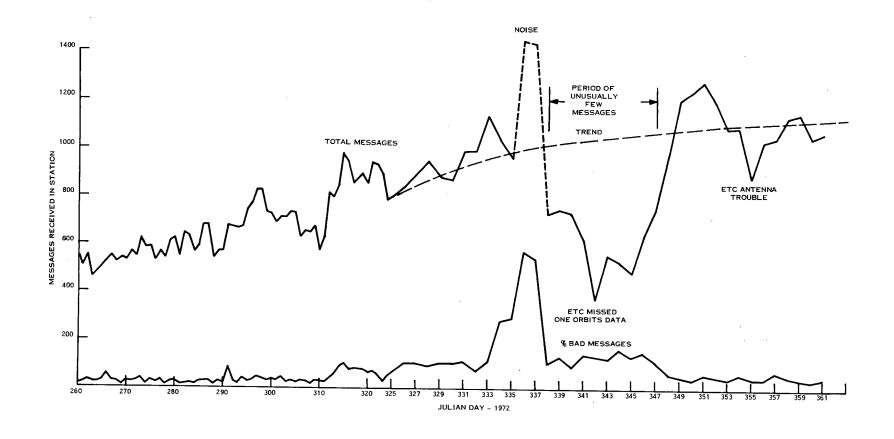


Figure 18-1. DCS Message Receipt History

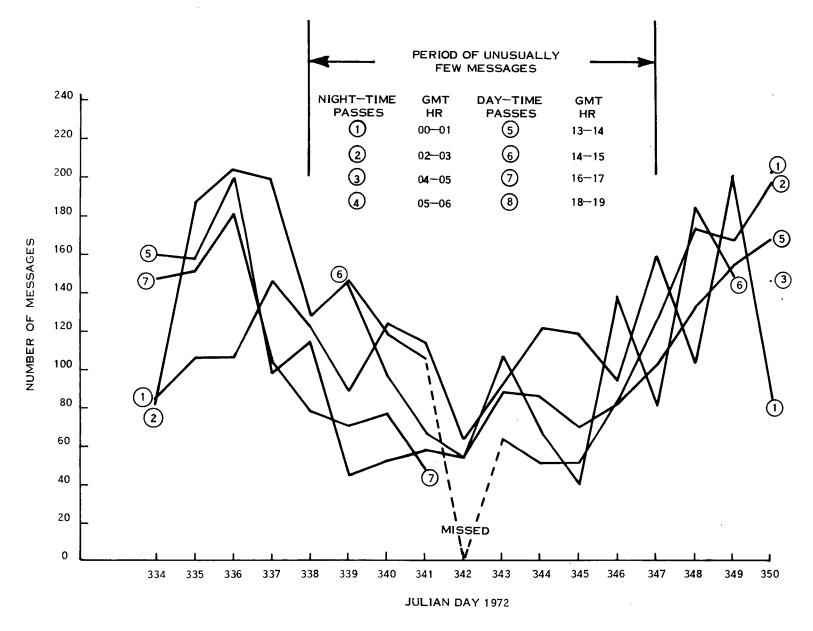


Figure 18-2. ETC DCS Message Reception

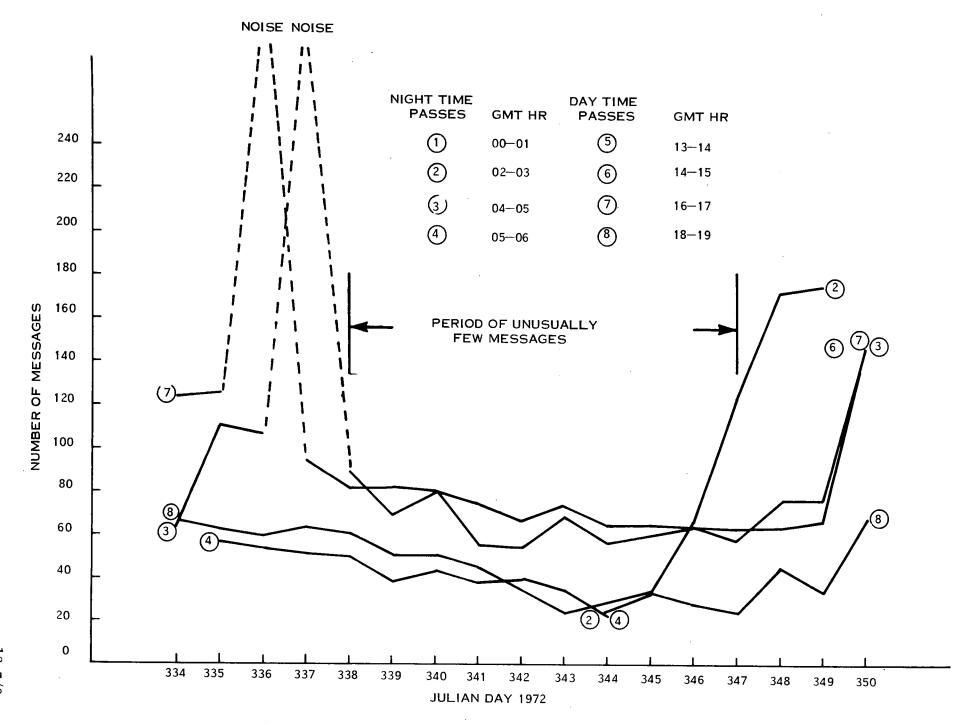


Figure 18-3. GDS DCS Message Reception

APPENDIX A

ERTS-1 ISSUED DOCUMENTS

DOCUMENT NO.	TITLE
72SD4255	ERTS-1 Launch and Flight Activation Report dated 18 October 1972.
72SD4262	ERTS-1 Flight Evaluation Report 23 July to 23 October 1972 dated 28 November 1972.
1TH4-ERTS-72	Solar Flare Activity between 8/2/72 to 8/7/72 dated 11/13/72
1TH4-ERTS-73	Interference to DCS dated 12/7/72
DOSR	ERTS-l Daily Operation Summary Reports (DOSR) dated (daily)
1TH05-ERTS-2006	MNFS Error WBVTR No. 2 Assessment for Orbits 849 thru 1519 dated 11/16/72
1TH05-ERTS-40S	Cal Wedge Evaluation thru Orbit 1337 from the MSS Peg Performance Program dated 11/28/72
1TH05-ERTS-410	Band 1 cal wedge, Scope Pix Evaluation for Orbit 2076 dated 12/27/72
1TH05-ERTS-416	Cal Wedge Evaluation thru Orbit 1965 from the Peg Performance Program dated 1/26/73
1TH05-ERTS-412	Re-examination of Sun Cal Results, RSE Reporting, and Tape Screening dated 1/3/73
1TH05-ERTS-414	Attempt at Evaluation of The Mux Transfer Function from linear and Compressed Mode Orbits dated 1/23/73
1TH05-ERTS-417	Sun Cal Program Data Collection dated 1/26/73
1HO5-ERTS-418	Evaluation of The Mux Lin/Comp Transfer Functions from Sun Cal Orbits 2375 and 2389 dated 2/1/73

1HO5-ERTS-404	Attempt at Calculation of The S/N Parameters for the ERTS A, MSS from the Sun Cal Pulse Input dated 11/16/72
1HO5-ERTS-407	S/N Parameters for the ERTS A MSS from the Modified Sun Cal Pulse Width Sampling Inputs dated 12/11/72
1HO5-ERTS-411	ERTS A MSS Sensor Noise and Baseline Shifts Reported by ULA and Goldstone Receiving Sites, Examination dated 12/27/72
1HO5-ERTS-415	S/N Calculated from the Sun Cal Pulse Input and the Cal Wedge Histograms dated 1/25/73
1TH05-ERTS-406	MSS Analog Telemetry through Orbit 1681 dated 11/28/72

APPENDIX B

ERTS-1 ANOMALY LIST/REPORTS

ERTS-1 ANOMALY LIST

Since launch, July 23, 1972, the ERTS-1 Spacecraft has exhibited the following problems which are being investigated to establish impact on the ERTS-1 Mission.

Item

1. Thermal Anomaly of right forward sun sensor (orbit 4)

Power Transient associated with WBVTR No. 2 (orbits 148, 149)

3. Failure of RBV power circuit to respond to off Command (Orbit 196)

- 4. Intermittant addition of 256 sec., to execute time of Cell 12 in Comstor B
- Power step-downs in USB transmitter power output.

Refer to:

Appendix E ERTS-1 Launch and Activation Report dated 18 October 1972 (72SD4255)

Section 15
Appendix B, Page B-2 thru B-5
ERTS-1 Flight Evaluation Report
23 July to 23 October 1972.
dated 28 November 1972
(72SD4262)
Section 15 and Appendix B herein

Section 10
Section 16
Appendix B, Page B-6 thru B-14
ERTS-1 Flight Evaluation Report
23 July to 23 October 1972.
dated 28 November 1972
(72SD4262)
Section 10, 16 and Appendix B
herein

Section 5
ERTS-1 Flight Evaluation Report
23 July to 23 October 1972
dated 28 November 1972
(72SD4262)
Section 5 herein

Section 9
ERTS-1 Flight Evaluation Report
23 July to 23 October 1972
dated 28 November 1972
(72SD4262)
Section 9 herein

ERTS 1 SPACECRAFT WBVTR ANOMALY BENCH SIMULATION TEST REPORT

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INTRODUCTION

The investigation of the ERTS 1 Orbit 149 anomaly associated with WBVTR No. 2 was based on four minutes of spacecraft telemetry and RBV video data.

The investigation began by connecting the engineering model WBVTR into Position No. 1 on the BIT board and inserting sufficient noise on the payload bus ground line at the WBVTR No. 2 position to upset the ACS.

The ensuing simulation testing was associated with the WBVTR dc-dc converter, because the noise frequencies determined during the ACS testing were within the bandwidth of the converters' oscillator.

The results of the testing pinpointed the failure as a short between the converters' T2 transformer 8Vdc and 22Vdc taps. The path of the short was through a mounting nut to the recorders' tinned copper ground plane.

SECTION 2 NOISE INJECTION TESTS

2.1 NOISE INJECTION AT THE PRM, VIP AND GROUNDS

Initial tests of this type included injection of noise in series with the PRM-24V output to the WBVTR, in series with the PRM return to the WBVTR, between the PRM return and space-craft unipoint return, and several locations associated with the spacecraft VIP. In all of the tests discussed herein, the VTR was simulated by a resistive load (unless otherwise noted).

2.1.1 NOISE ON PRM OUTPUT

A sinewave generator was used with the circuit (see Figure 2-1) to induce noise into the system. The signal measured from the PRM bus to its return was stepped between 22 and 200 kHz and at each frequency from zero up to 600 mV. The resulting data did not match that of the flight anomaly.

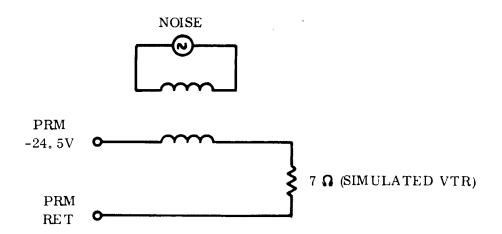


Figure 2-1. Circuit Schematic

2.1.2 NOISE ON PRM RETURN

This test was identical to prior test, except that the noise was coupled into the return side of the simulated WBVTR load. As previously, none of the spacecraft subsystems were affected.

2.1.3 NOISE BETWEEN RETURNS

The data from this series of tests more closely duplicated that of the flight anomaly. The ACS scanners indicated "upside down" as observed in the flight anomaly. Preliminary conclusions were that the ACS scanners were most sensitive to noise that changed frequency rapidly from 24 kHz to 12 kHz. The test setup is shown in Figure 2-2.

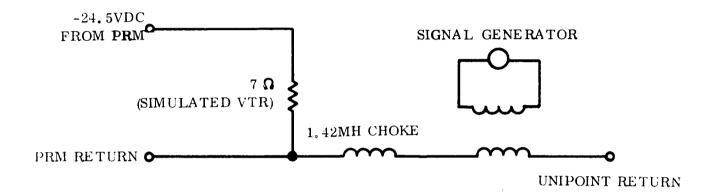


Figure 2-2. Test Setup

The first test was performed using a 22 kHz sine wave for the noise input. The major observation was that ACS data became noisey for most noise levels and that several pitch and roll errors occurred. ACS stimulators were not installed.

The following tables are noise levels measured between the spacecraft bus and the spacecraft bus return, payload bus and payload bus return, and noise between payload return and unipoint return.

S/ C (Volts)	P/ L (Volts)	P/ L to Unipoint (Volts)	Remarks
0.080	0.040	0	Baseline
0.350	0.600	-	Pitch and Roll errors; Very noisy TLM
_	0.500	_	Same as above
0.120	0.200	1.5	Some noisey TLM
0.170	0.300	2.4	Noiser than above
0.210	0.400	3.0	Slight increase in noise
0.275	0.500	4.2	Very noisy
0.250	0.450	4.7	Appears to be threshold

All tests after the first were run with scanners and the scanner go/no-go heater stimulators. With this setup, the rear scanner gave upside down indications when the noise between returns was 6.5 V or greater. Again the noise stimulus was a 22 kHz sine wave.

S/ C (Volts)	P/ L (Volts)	P/ L to Unipoint (Volts)	Remarks
0.160	0.600	6.5	Rear scanner upside down
0.210	0.800	8.2	No change
0.225	0.900	10.0	No change
0.250	1.200	13.0	No change
_	0.400	_	Rear scanner normal

The next test was run with a 10 kps generator for the noise input. In this setup both scanners indicated upside down. However, as can be seen in the following table, the forward scanner results were somewhat inconclusive.

S/ C (Volts)	P/ L (Volts	P/ L to Unipoint (Volts)	Remarks
0.110	0.380	3.5	Rear scanner upside down
0.180	0.600	5.0	Both scanners upside down
0.110	0.300	3.0	Forward scanner back to normal
-	1.2	-	Forward scanner still normal

The next test showed that the scanners were not only sensitive to noise at a given amplitude and frequency, but also to a rapid shift in frequency from approximately 24 kHz to 12 kHz. Noise input was a sine wave.

Frequency (kHz)	S/ C (Volts)	P/ L (Volts)	P/L to Unipoint (Volts)	Remarks
200	0.120	0.300	3.0	No problem
100	0.150	0.500	4.0	Noisy data
100	0.180	0.600	5.25	Noisy data
100	0.180	0.700	7.0	Noisy data
40	0.600	1.0	10.0	Noisy data
20	0.200	0.800	8.0	Some scanner noise
15	-	-	-	Almost full earth on both scanners
40	0.400	1.5	-	Both scanners normal
24	-	-	-	Rapid freq change - no problem
12	0.170	0.700	7.0	Rapid freq change - upside down on both scanners

The next test was run to determine at what noise level both scanners would indicate upside down if the frequency was quickly changed from 24 kHz to 12 kHz. In summary, the results showed that for both scanners to saturate, at least 300 mV of noise was required on the payload bus when the frequency shift occurred. Simply raising the noise level to 300 mV after a frequency shift would not cause both scanners to see full earth. The threshold for the rear scanner only was measured to be about 175 mV.

2.1.4 NOISE ON VIP

Noise was introduced into the VIP subsystem in three phases as follows:

- 1. To both signal and signal return (common mode rejection)
- 2. Between signal return and unipoint
- 3. In series with signal

2.1.4.1 Common Mode Rejection

Several WBVTR telemetry signals were simulated by a 3 Vdc battery. Sinusoidal noise was then injected into both the signal line and the signal return. The simulated WBVTR input current telemetry, which is sampled once a second, was used to determine noise effects. Since the frequencies generated were extremely high in relation to VIP sampling, only maximum and minimum points were used in the analysis. From the data, it appears that the noise was merely added to the dc signal input. The results also indicate that common mode injection was best at frequencies below 20 kHz and at 300 kHz. It seemed not to exist at all at 100 and 200 kHz. The results are tabulated in Table 2-1.

2.1.4.2 Ground Noise

In this test, some of the WBVTR No. 2 telemetry points were connected through a 1.5 V battery to the PCM return, simulating full-time telemetry points. The analog mux return was connected as in the first test. The results were similar to those of the first test for both groups of telemetry. See Table 2-2.

Table 2-1. Common Mode Rejection (All values are TMV unless specified)

Frequency	Amp		/el*			
(kHz)	(V _{P-P})	Maximum	Minimum	+ Δ	-Δ	± Δ
10	1.0	3.30	3.05	0,13	0.12	0.25
10	2.0	3.60	2,77	0.43	0.40	0.83
10	3.0	3.70	2.67	0.53	0.50	1.03
20	1.0	3.50	2.87	0.33	0.30	0.63
20	2.0	3.50	2.57	0.33	0.60	0.93
20	3.0	3.50	2.57	0.33	0.60	0.93
40	1.0	3.60	2,72	0.43	0.45	0.88
40	2.0	4.00	2.37	0.83	0.75	1.58
40	3.0	4.12	2.25	0.95	0.87	1.82
100	1.0	3.70	2.65	0.53	0.48	1.01
100	2.0	4.25	2.15	1.08	1.02	2.10
100	3.0	4.87	1.55	1.70	1.62	3.32
200	1.0	3.70	2.67	0.53	0.50	1.03
200	2.0	4.20	2.20	1.03	0.97	2.00
200	3.0	4.90	1.80	1.73	1.37	3.10
200	1.0	0.05	0.00	2 22		
300	1.0	3.37	3.00	0.20	0.17	0.37
300	2.0	4.00	2.82	0.83	0.35	1.18
300	3.0	4.02	2.37	0.85	0.80	1.65

^{*}Normal steady state T/M level was 3.17 TMV

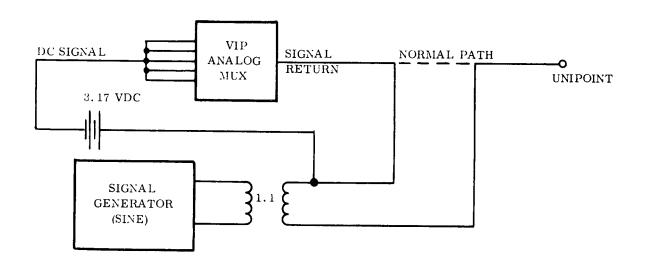
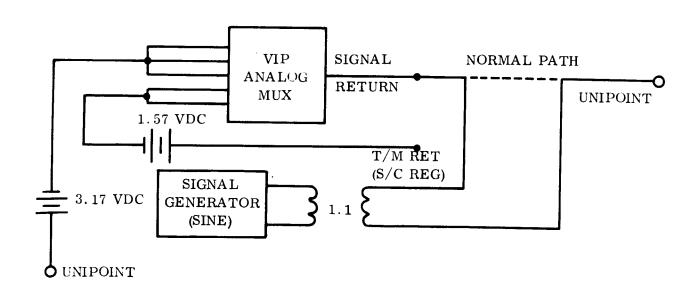


Table 2-2. Noise in Ground (All values are TMV unless specified)

Frequency Amp (V _{P-P})	Amp Level*	/el*		1	1	(Normal 1.57)					
	(v _{P-P})	Maximum	Minimum	+Δ	-Δ	± Δ	Maximum	Minimum	+4	-Δ	± Δ
10	1.0	3.60	2,77	0.42	0.40	0.82	2.00	1.17	0.52	0.40	0.92
10	2.0	4.02	2.35	0.85	0.82	1.67	2.05	1.17	0.57	0.40	0.92
20	1.0	3.50	2.87	0.32	0.30	0.63	1.77	1.42	0.20	0.15	0.35
20	2.0	3.80	2.82	0.62	0.35	0.97	2.42	0.75	0.85	0.13	1.67
20	3.0	4.80	1.57	1.62	1.60	3.22	3.20	0.70	1.62	0.87	2.50
40	1.0	3.65	2.72	0.47	0.45	0.92	2.00	1.12	0,42	0.45	0.87
40	2.0	4.10	2.27	0.92	0.90	1.82	2.05	0.92	0.47	0.65	1.12
40	3.0	4.12	2.25	0.95	0.92	1.87	2.25	1.12	0.87	0.45	1.32
100	1.0	3.70	2.65	0.52	0.52	1.05	2.10	1.05	0.52	0.52	1.05
100	2.0	4.20	2.20	1.02	0.97	2.00	2.60	0.60	1.02	0.97	3.00
100	3.0	4.80	1.62	1.62	1.55	.3.17	3.25	0.00	1.67	1.57+	3.25+
200	1.0	3.65	2.72	0.47	0.45	0.92	1.12	2.05	0.47	0.45	0.92
200	2.0	4.20	2.25	1.02	0.92	1.95	2.60	0.62	1.02	0.95	1.97
200	3.0	4.80	1.87	1.62	1.30	2.92	3.20	0.27	1.62	1.30	2.92
300	1.0	3.40	2.97	0.22	0.20	0.42	1.62	1.37	0.05	0.20	0.25
300	2.0	4.00	2.37	0.82	0.80	1.62	2.90	0.77	0.82	0.80	1.62
300	3.0	4.40	2.37	1.22	0.80	2.02	3.00	0.57	1.42	1.00	2.42

^{*}Normal steady state T/M level was 3.17 TMV.



2.1.4.3 Signal Noise

The setup for this test was the same as for the second test, except noise was injected only at the return of the 3 V group. The results showed noise rejection increasing with frequency for both groups, and coupled noise in the 1.5 V group a factor of 10 below that of the stimulated group (see Table 2-3).

2.2 BIAS AND NOISE

The purpose of this test was to determine the effect on the system of bias and noise between Payload Return and unipoint, and between WBVTR chassis and unipoint.

The test was run twice; first, on September 16, 1972, and then on September 26, 1972.

Figure 2-3 shows the test circuit used to introduce the bias and noise between P/L return and WBVTR unipoint. The engineering model was connected into the No. 1 position on the BIT Board and the bias and noise were introduced at the WBVTR No. 2 power interface.

Voltage measurements were (ac and dc) made from S/C regulator return (A) and WBVTR No. 2 signal return (B) to unipoint.

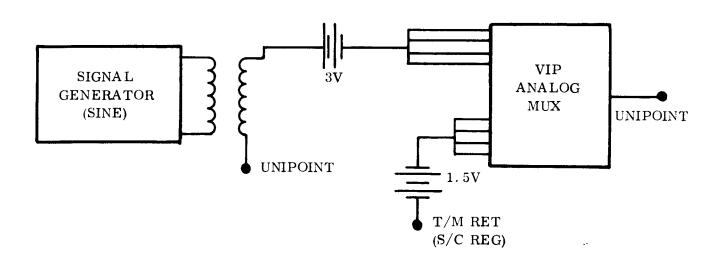
To introduce the bias and noise between chassis and unipoint, Point A on Figure 2-3 was disconnected from P/L return (P5W48-A, B, P & R), and connected to the BIT Board chassis return.

The same procedure was followed in both the September 16 test and the September 26 test. The (RBV) was commanded on and the WBVTR No. 2 power relay in the PSM was commanded on. The dc supply was adjusted to produce approximately 1/2 V of dc offset between the WBVTR No. 2 signal ground and unipoint. The ac signal was increased in steps until the telemetry indicated that the scanners were indicating upside down. This was done at two frequencies: 12 kHz and 22 kHz.

Table 2-3. Noise in Signal (All values are TMV unless specified)

Frequency Amp				1		Į	(Norma	d 1.57)		1	
(kHz) (V _{P-P})	Maximum	Minimum	+Δ	-Δ	±Δ	Maximum	Minimum	+Δ	-Δ	+ A	
10	1.0	3.60	2.77	0.43	0.39	0.82	1.60	1.55	0.02	0.02	0.05
10	2.0	4.02	2.35	0.85	0.82	1.67	1.60	1.55	0.02	0.02	0.05
10	3.0	4.12	2.25	0.95	0.92	1.87	1.65	1.52	0.07	0.05	0.12
20	1.0	3.50	2.87	0.33	0.30	0.63	1.62	1.55	0.05	0.02	0.07
20	2.0	3.50	2.87	0.33	0.30	0.63	1.65	1.52	0.07	0.05	0.12
20	3.0	3.80	2.57	0.63	0.60	1.23	1.67	1.47	0.10	0.10	0.20
40	1.0	3.32	3.05	0.15	0.12	0.27	1.60	1.55	0,02	0.02	0.05
40	2.0	3.65	2.72	0.48	0.45	0.93	1.65	1.52	0.07	0.05	0.12
40	3.0	4.00	. 2.37	0.83	0.80	1.63	1.65	1.52	0.07	0.05	0.12
100	1.0	3.30	3.07	0.13	0.10	0.23	1.60	1.55	0.02	0.02	0.05
100	2.0	3.42	2.95	0.25	0.22	0.47	1.62	1.52	0.05	0.05	0.10
100	3.0	3.55	2.85	0.38	0.32	0.70	1.65	1.52	0.07	0.05	0.12
200	1.0	3.22	3.15	0.05	0.02	0.07	1.57	1.57	0	0	0
200	2.0	3.25	3.10	0.08	0.07	0.09	1.60	1.55	0.02	0.02	0.05
200	3.0	3,30	3.05	0.13	0.12	0.25	1.60	1.55	0.02	0.02	0.05
300	1.0	3.20	3.15	0.03	0.02	0.05	1.57	1.57	0	0	0
300	2.0	3.22	3.12	0.05	0.05	0.10	1.60	1.57	0.02	0	0.02
300	2.0	3.25	3.12	0.08	0.05	0.13	1.60	1.57	0.02	ő	0.02

^{*}Normal steady state T/M level was 3.17 TMV.



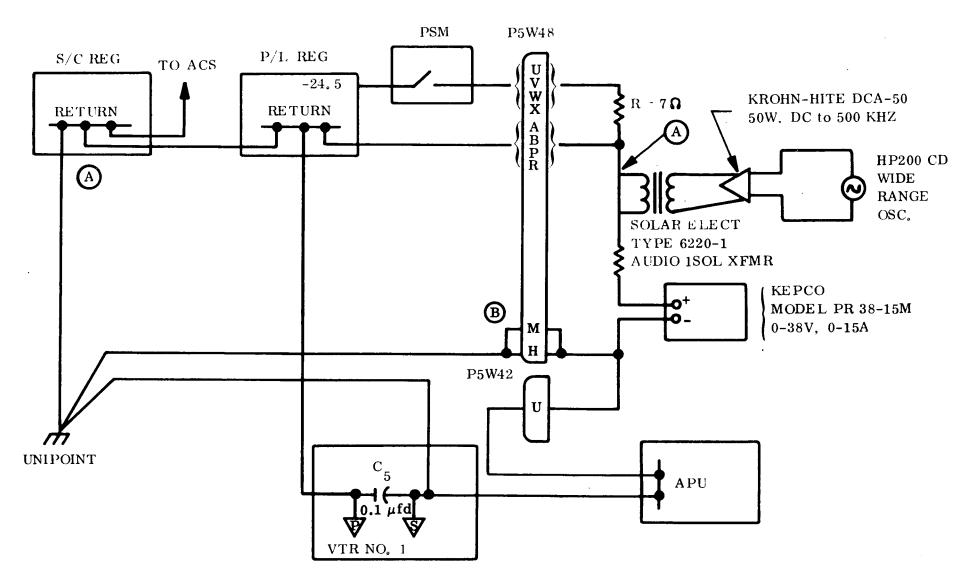


Figure 2-3. BIT Board Test Setup Used to Introduce Bias and Noise Between Payload Bus Return and Unipoint

In both tests, the results show that the ACS scanners indicated upside down when the noise reached a level of 350 mV peak-to-peak at 12 kHz from S/C return to unipoint. When the frequency was raised to 22 kHz the noise required was 750 mV peak-to-peak. The values were repeated a number of times during each day's test.

After the level required to upset the ACS was determined (350 mV at 12 kHz and 750 mV at 22 kHz). WBVTR No. 1 was commanded on and placed in RBV record. A recording of RBV data was made while the required noise was being induced in the system, and the ACS was indicating upside down. During this time, the output of the RBV was monitored on a scope, and no noise was observed. At the end of the record period, the noise was removed and the WBVTR played back. The RBV playback data from WBVTR No. 1 was observed in the same manner as had the real-time RBV data at the time of recording. This play-back data very clearly exhibited the noise being induced in the system.

All of the aforementioned testing was performed with the noise being introduced between P/L return and unipoint. When the noise and bias were introduced between chassis and unipoint, it was found that higher driving levels of noise were required to produce significant noise between return and unipoint. In fact, with the noise generating equipment available it was not possible to produce sufficient noise between return and unipoint to cause the ACS to indicate upside down.

This difference in affect between P/L return and chassis can be more clearly seen by an analysis of the two test configurations. Figures 2-4 and 2-5 are simplified schematics of the P/L return to unipoint and the chassis to unipoint circuits. All resistances shown are wire resistances and are in the low milliohm range. The capacitor is C5 of the WBVTR dc/dc converter (from primary to secondary return) and is 0.1 μ fd (approximately 80 Ω at 20 kHz).

Note that in the P/L return to unipoint case (see Figure 2-4) all the noise current flows between S/C return and unipoint, except that which flows through C5 (a very small percentage of the total current). In the chassis to unipoint case (see Figure 2-5), however, the only portion of the noise current that flows between return and unipoint is that which does flow through C5.

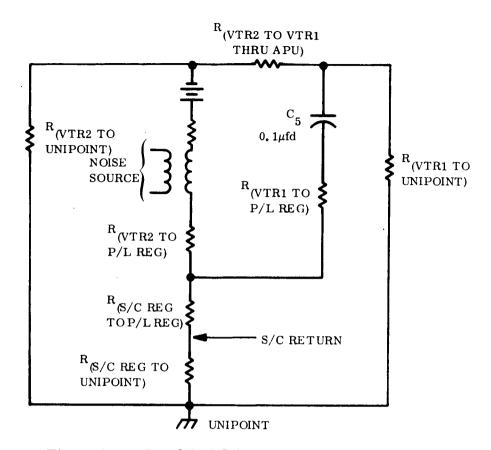


Figure 2-4. Simplified Schematic of Return to Unipoint

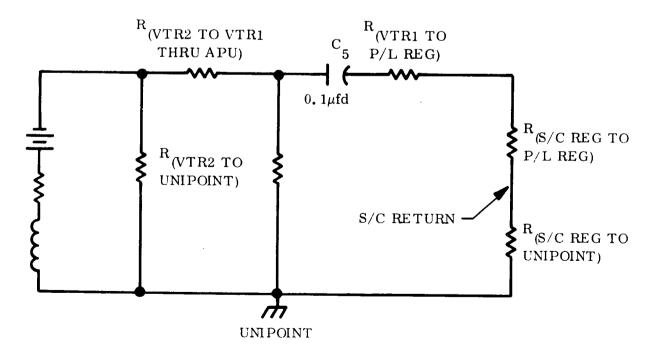


Figure 2-5. Simplified Schematic of Chassis to Unipoint

WBVTR ANOMALY SIMULATION

The investigation of the WBVTR No. ERTS 1 anomaly in Orbit 149 was based on four minutes of spacecraft data telemetered during the period that the anomalous behavior existed, five minutes of RBV video data for the same period, and the fact that the problem began with turn-on of WBVTR No. 2 in Orbit 149.

The investigation began by connecting the engineering model WBVTR into recorder Position No. 1 on the BIT board and inserting sufficient noise on the payload bus ground line at the Recorder No. 2 position to upset the ACS. The results showed that the amplitude required was a function of frequency as measured from spacecraft ground to unipoint.

The simulation testing was associated with the WBVTR dc-dc converter because the noise frequencies determined during the ACS testing were within the bandwidth of converter's oscillator. A schematic of the dc-dc converter is shown in Figure 3-1.

3.1 WBVTR COMPONENT TESTING

Testing of the recorder began by shorting Capacitor C3. This test developed the required frequency (20 kHz), but produced insufficient voltage (1.3 $V_{\rm P-P}$). Capacitors C3 and C5 were then shorted with the signal ground open. The same results were obtained.

A -24.5 Vdc payload regulated bus voltage was shorted through 5 Ω to signal ground with signal ground to unipoint open. A 0.7 Volt dc recorder telemetry signal offset was the result.

The +8 Vdc at the junction of Diodes CR-3 and CR-7 was shorted to chassis ground through resistances ranging from 2.5 to 0.4 Ω . This short produced a slight dc recorder telemetry offset with noise initially at 40 kHz and changing to 20 kHz after 3 minutes. Shorting +5.6 Vdc in the same manner yielded the same results. The minimum resistance for the short that would still permit the recorder to function was 0.19 Ω . Using the same approach, +22 Vdc was shorted to chassis ground through resistances down to 2.0 Ω , the minimum that

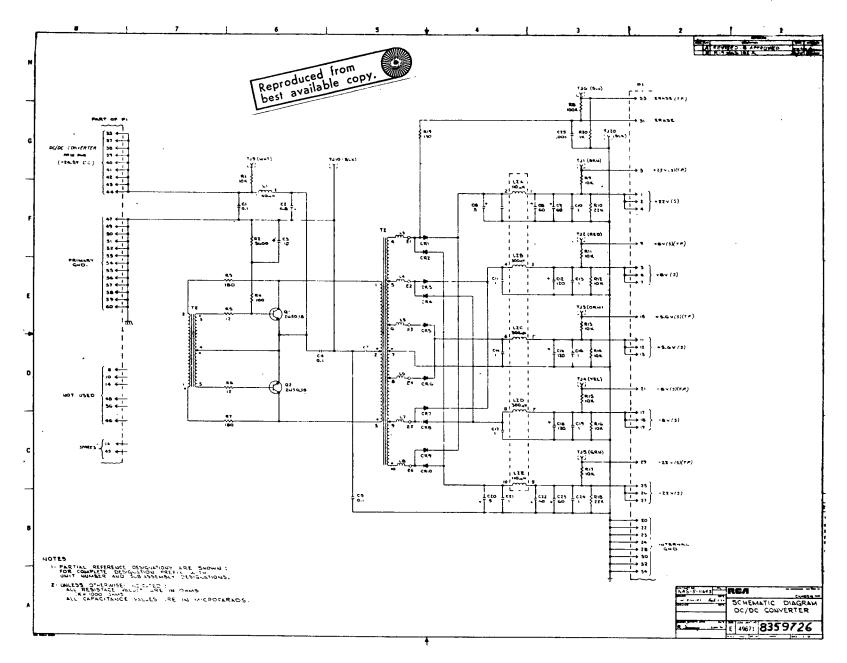


Figure 3-1. WBVTR DC-DC Converter Schematic

would permit the recorder to operate. This test eliminated a short of the + 22 Vdc as the cause of the problem because it produced very little noise and only a slight recorder dc telemetry offset.

3.2 WBVTR SYSTEM TESTING

All affected subsystems were integrated onto the BIT board to obtain subsystem reactions to the simulation testing.

RBV video was recorded on Recorder No. 1 while the +8 Vdc of Recorder No. 2 was shorted to payload ground through 0.25 Ω . RBV video showed very little noise content; a 0.25 Vdc Recorder No. 2 telemetry offset was apparent. This test was repeated with signal ground shorted to unipoint through 0.7 Ω . This test resulted in a 2.5 Vdc offset in Recorder No. 2 telemetry with only slightly perceptible video noise.

The two previous tests were combined by concurrently shorting the +8 Vdc to payload ground through 0.13 Ω and signal ground to unipoint through 0.17 Ω . This test induced 0.15 V_{P-P} noise on the RBV video recorded on Recorder No. 1 and a 2.35 Vdc offset in Recorder No. 2 telemetry signal levels.

Using minimum resistances necessary to sustain recorder operation, the +5.6 Vdc, +8 Vdc, and +22 Vdc lines on the load side of the inductors were shorted to payload ground. This reduced the noise level at the spacecraft ground to unipoint by 5 to 1 in all cases, thereby eliminating the possibility of a short on the load side of the dc-dc converter.

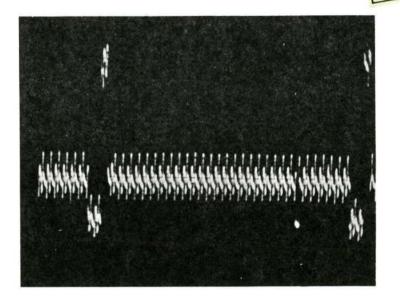
The + 8 Vdc was then shorted through 0.27 Ω total to chassis ground and allowed to run for 4 minutes after which the noise level in the RBV video recorded on Recorder No. 1 reached 0.2 V_{P-P} . Shorting the + 8 Vdc through 0.37 Ω to payload ground for 4 minutes produced video noise amplitude of 0.4 V_{P-P} .

The testing thus far failed to affect the Recorder No. 2 + 5.6 Vdc and servo voltage telemetry signals, to upset the ACS and to cause appreciable offsets in the Recorder No. 1 telemetry signals.

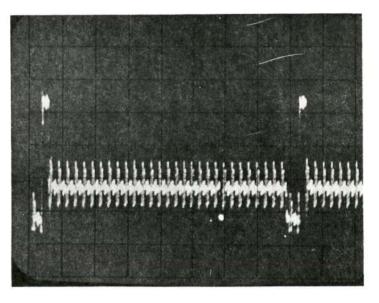
In the final tests, the secondary winding of the dc-dc converter transformer T-2 was shorted to payload ground through a 0.1 to 0.25 Ω resistance. Shorting the 8 V tap produced 20 kHz to 40 kHz noise depending on the resistance of the short. At an amplitude of 15 V_{P-P} from payload bus return to unipoint and 0.7 V_{P-P} from spacecraft bus return to unipoint. The ACS was upset, but insufficient noise was generated to cause the V pass to differentiate the video (see Figure 3-3). Figure 3-4 shows a correlation of WBVTR, Power and ACS brush telemetry signatures obtained during the Orbit 149 anomaly and during the 22 Vdc tap BIT board short simulation.

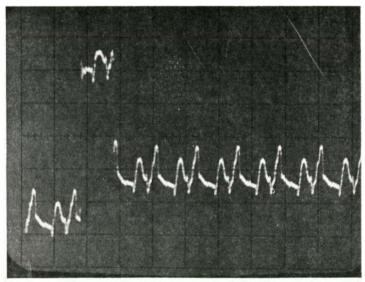
The results of shorting the T-2 transformer 22 Vdc and 8 Vdc taps led to the conclusion that the short was between these two taps. Figure 3-5 illustrates the mechanism by which the short occurred.





 $100 \,\mu\text{S/CM}$





 $20 \mu S/CM$

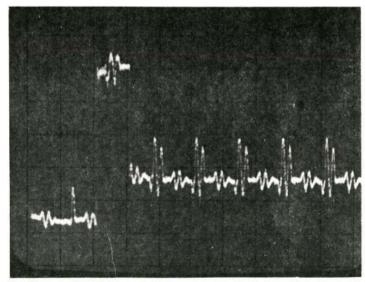
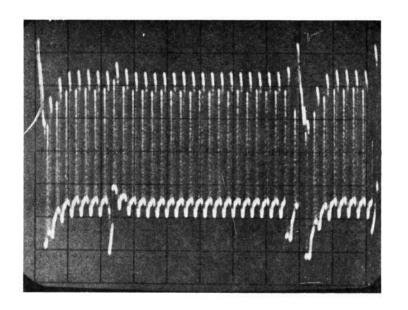
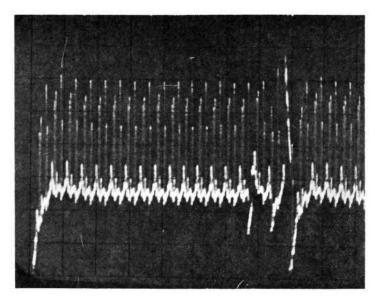


Figure 3-2. Photographs Showing Correlation or Orbit 149 RBV Video and That Recorded During BIT Board 8 Vdc Tap Short Simulation



 $100 \, \mu \mathrm{S/CM}$



 $20~\mu\mathrm{S/CM}$

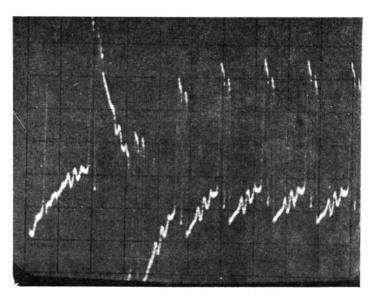


Figure 3-3. Photographs Showing Correlation of Orbit 149 RBV Video and That Recorded During BIT Board 22 Vdc Tap Short Simulation

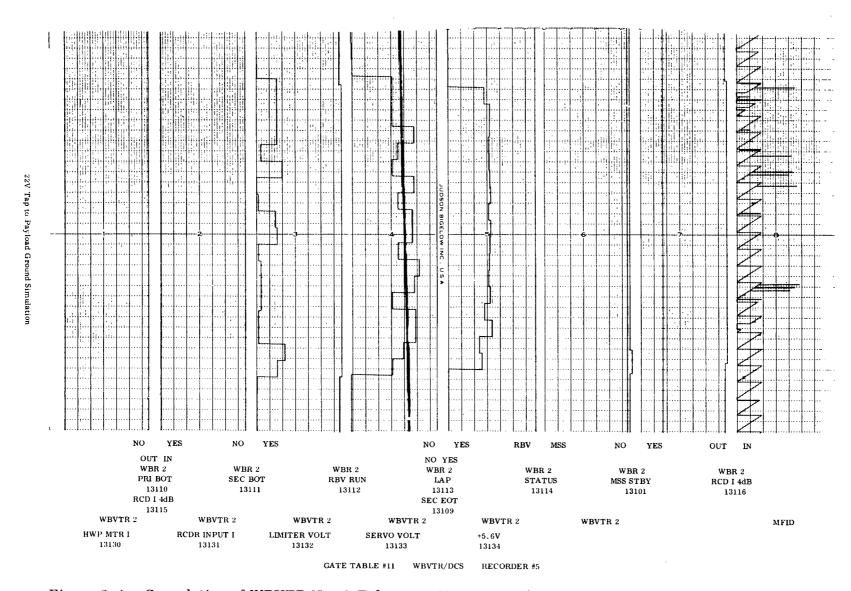


Figure 3-4. Correlation of WBVTR No. 2 Telemetry Signatures Obtained During the Orbit 149 Anomaly and During the 22 Vdc Tap BIT Board Short Simulation (Sheet 1 of 6)

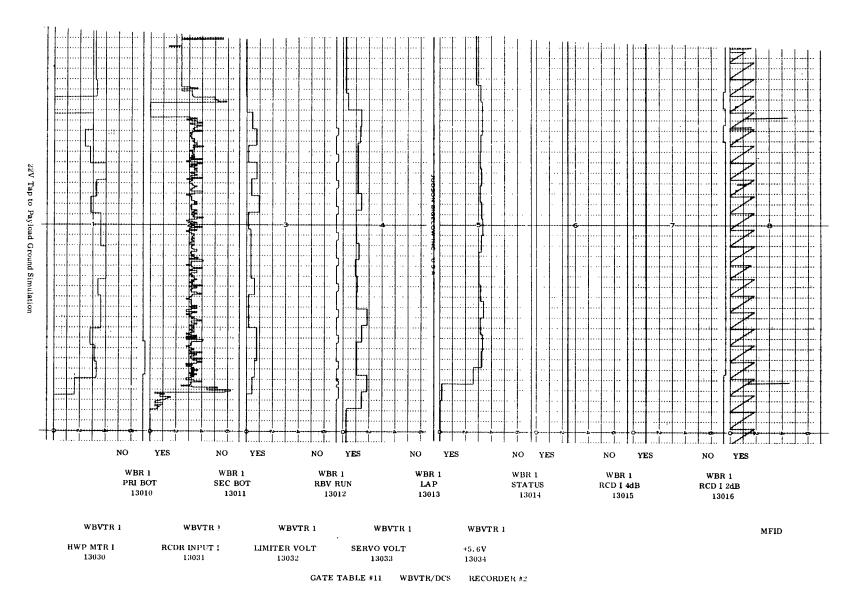


Figure 3-4. Correlation of WBVTR No. 1 Telemetry Signatures Obtained During the Orbit 149 Anomaly and During the 22 Vdc Tap BIT Board Short Simulation (Sheet 2 of 6)

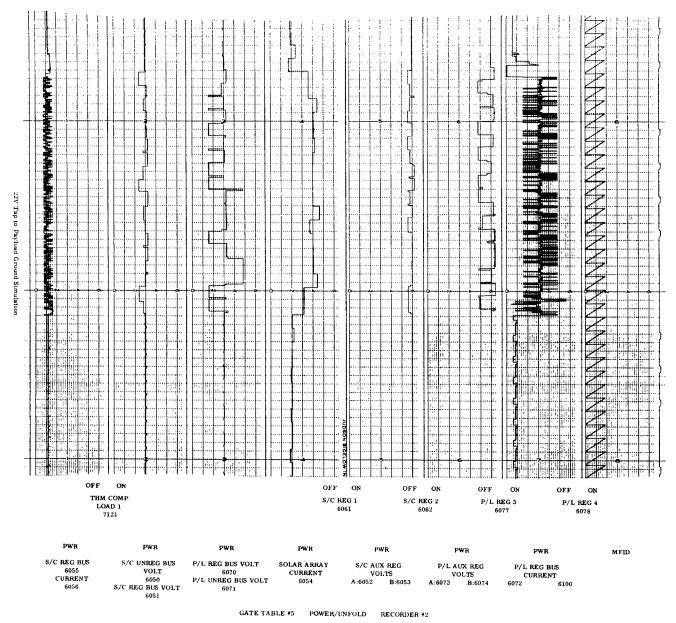


Figure 3-4. Correlation of Power Telemetry Signatures Obtained During the Orbit 149 Anomaly and During 22 Vdc Tap BIT Board Short Simulation (Sheet 3 of 6)

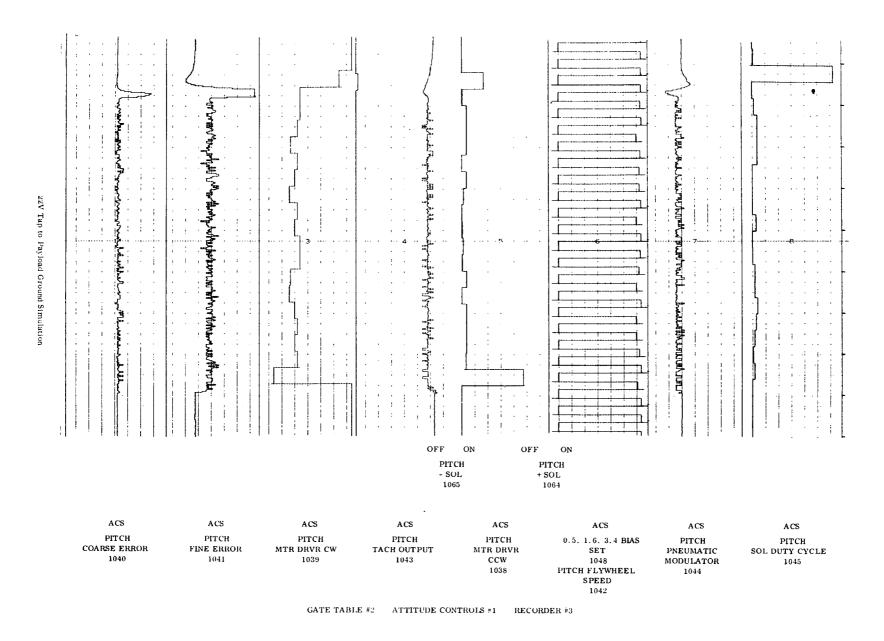


Figure 3-4. Correlation of ACS Telemetry Signatures Obtained During the Orbit 149 Anomaly and During the 22 Vdc Tap BIT Board Short Simulation (Sheet 4 of 6)

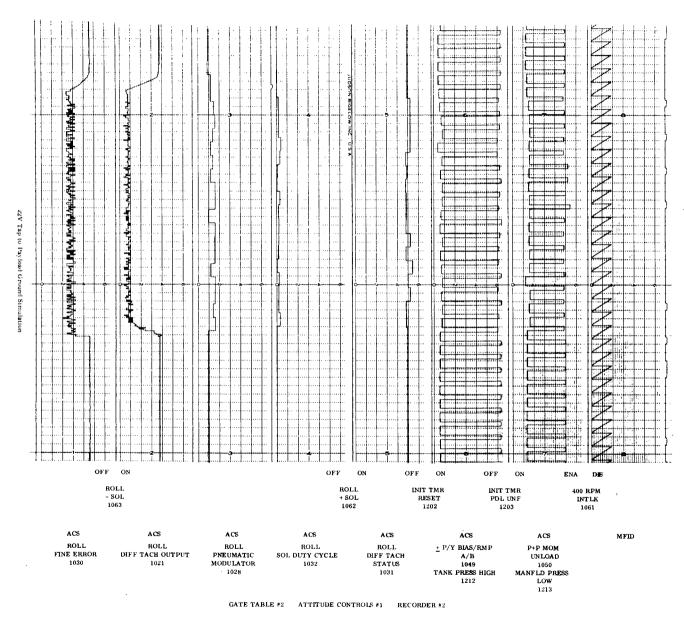


Figure 3-4. Correlation of ACS Telemetry Signatures Obtained During the Orbit 149 Anomaly and During the 22 Vdc Tap BIT Board Short Simulation (Sheet 5 of 6)

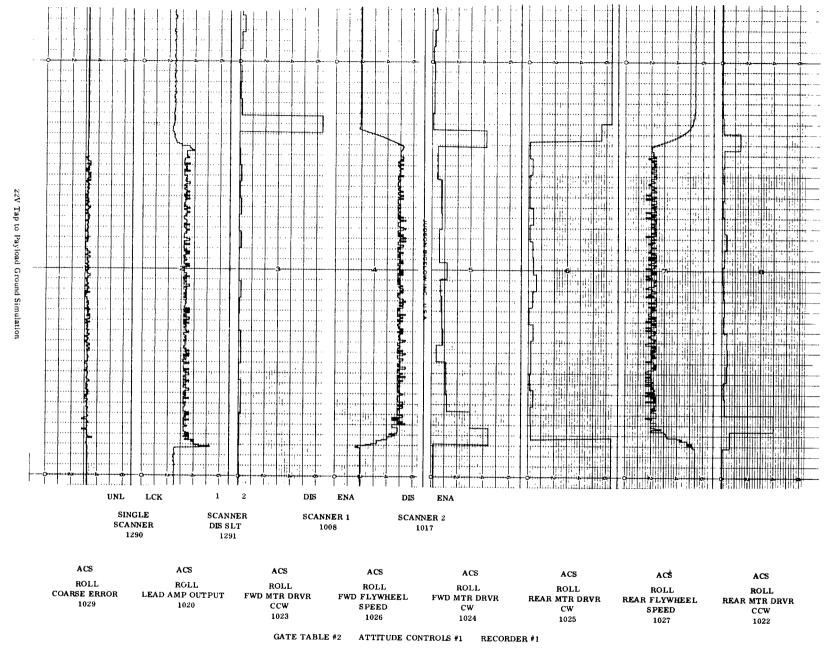
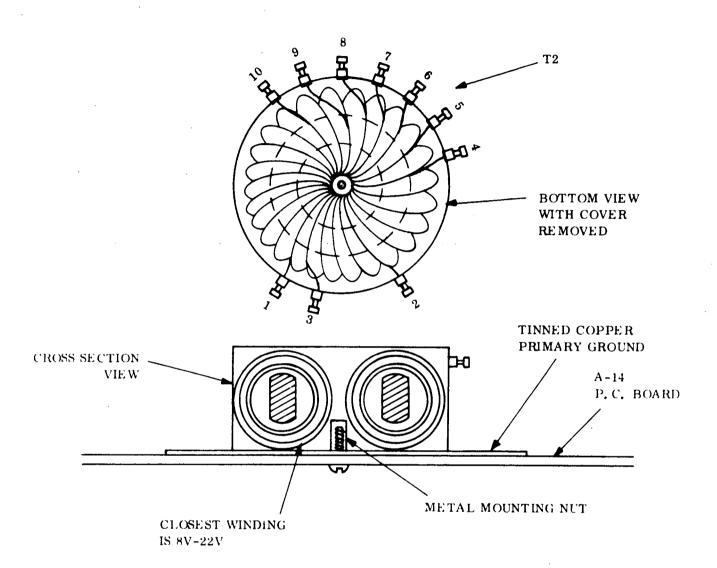


Figure 3-4. Correlation of ACS Telemetry Signatures Obtained During the Orbit 149 Anomaly and During the 22 Vdc Tap BIT Board Short Simulation (Sheet 6 of 6)



FAILURE MODE:

- 1. MOUNTING NUT SHORTS TO WINDING
- 2. MOUNTING NUT SHORTS TO TINNED COPPER GROUND PLANE

Figure 3-5. Sketch Showing Manner by Which the T-2 Transformer of WBVTR No. 2 Became Shorted

ERTS 1 SPACECRAFT RBV ANOMALY BENCH TEST REPORT

TABLE OF CONTENTS

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3	SHORT SIMULATION	3-1
4	REACTIVATION SIMULATION	4-1

INTRODUCTION

The investigation of the ERTS 1 orbit 196 anomaly associated with the RBV Turn On was based on spacecraft telemetry data analysis and BIT component testing and system level testing.

The BIT Test Program consisted of a series of relay tests which have been covered under a separate report and the following system level tests covered in this report.

- 1. RBV Current Transient Test
- 2. Payload Bus Short Circuit Simulation
- 3. RBV Reactivation Simulation

The RBV current transient test was conducted using the feasibility model RBV system, which is composed of a CCC, one camera electronics and one camera sensor in conjunction with the basic S/C equipment on the BIT Board. The purpose was to determine the changes in RBV Turn On transient from nominal with the CCC input choke shorted.

The Payload Bus Short Circuit Simulation was performed using the BIT S/C power supply/PSM, harness, etc., plus the feasibility model RBV. Short circuits were momentarily placed between RBV On power and various returns in order to reproduce the telemetry symptoms obtained from flight data.

The RBV Reactivation Simulation was performed using the BIT S/C power supply and two Leach Relays which were turned on into a short circuit with the Payload Battery tap lines open. This was done several times to determine if the Leach relays could withstand a turn on into a short circuit (worst case turn on) and still function properly. The battery tap lines were kept open to limit the current to approximately 25 amps.

The results of these tests indicated the following.

- 1. The RBV Turn On transient with CCC input choke shorted was not large enough to account for the current drawn in flight.
- 2. The RBV On power shorted to chassis (only) caused similar telemetry symptoms as seen in flight data.
- 3. The Leach relays can withstand several turn on's into a short circuit with the battery tap lines open and still function properly. Therefore, if a short circuit exists within the RBV at reactivation, the system can be safely turned off.

RBV CURRENT TRANSIENT

This test was run to determine the change in the current pulse waveform at the PSM relay that occurs when the input choke of the RBV CCC is shorted.

Figure 2-1 shows the circuit on the BIT Board used in measuring the turn-on transient.

Current measurements were made of the total RBV current at P5P03-9 through 17 with an ac probe, HP Model 1110A, and amplifier, HP Model 1111A. The RBV used was the feasibility model which has only a CCC and one camera electronics and camera sensor.

Figure 2-2 shows both the transient for RBV turn-on with the CCC input choke functional and with the CCC input choke shorted.

The magnitude of the initial spike was 26.5a in the normal case and 30a in the shorted case (a 17% increase). The duration of the spike increased to 270 microsec.

The effect on the payload regulated bus voltage is effectively the same in magnitude with the time to recover equal to 50 msec for the normal case and 55 msec for the shorted case.

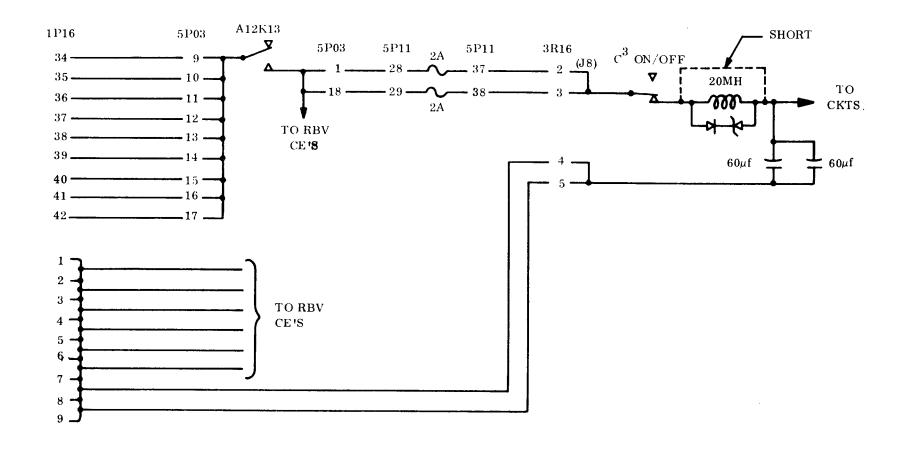
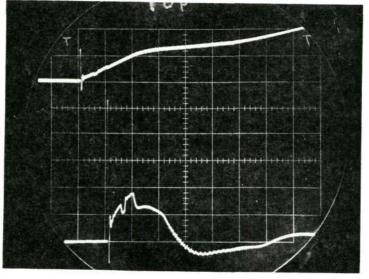
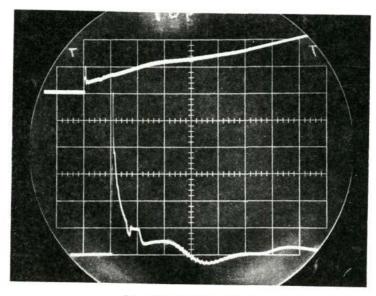


Figure 2-1. BIT Board Setup Used to Measure the RBV Turn-on Transient





a) Choke Normal



b) Choke Shorted

Upper - Payload Reg Bus Voltage - 2.5 V/CM

Lower - RBV Current - 5A/CM (AC Coupled Probe)

Hor - 0.5 MSEC/CM (Lower Trace Offset 1 CM to the Right)

Figure 2-2. Photographs Showing RBV Turn-on Transients

SHORT SIMULATION

A symptom of the RBV turnon anomaly was that Telemetry referenced to the Spacecraft bus return showed a momentary shift toward zero. Simulations on the BIT system were made to duplicate the shift and to generate a calibration by which the current pulse during the anomaly could be measured.

Interrelation of the power grounding system is shown in Figure 3-1.

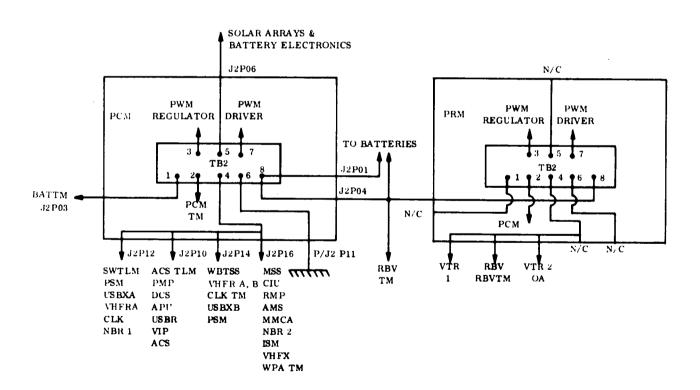
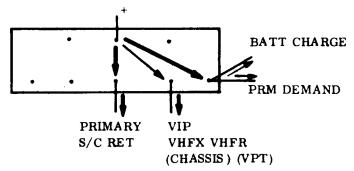
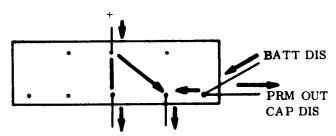


Figure 3-1. Power Return Configuration

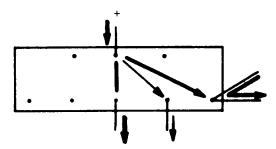
Normal current flows in the board are shown below:



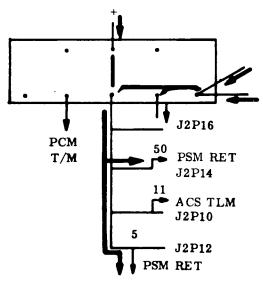
Current during short of PRM output to chassis is shown below:



Current during short of PRM output to PRM return is shown below:



Current during short of PRM output to PSM relay return is shown below:



In BIT tests the output of the RBV subsystem power relay was connected through a knife switch to ground. A one-milliohm shunt was installed in the RBV lines to the PSM. The switch was closed with RBV OFF, and was opened immediately after the RBV ON command. An oscilloscope was connected across the shunt, and photographs were made of the current pulse and bus voltage. The short was made to chassis, PSM Relay Return to the PSM, and PRM (see Figures 3-2, 3-3, and 3-4). The spikes on the current trace are believed to be oscillation of the under voltage, current limit, and duty cycle circuits. ACS telemetry showed no effect from shorts to PRM return. Shorts to PSM relay return caused an increase (more negative) in telemetry of about 0.3 V. Shorts to chassis caused a decrease (toward zero) in telemetry of about 0.4 V, as was observed in orbit.

The VHF receiver has power return shorted to chassis at the secondary of its dc/dc converter. The VHF transmitter shorts power return, relay return (PSM - driven relays), and modulation input return (VIP power return) to chassis at its input. These provide stray paths between PCM ground and unipoint whose current sharing and effects allow measurement of the RBV turn on transient.

BIT shorts to chassis did not simulate the flight anomaly because of significantly different wire gauges and lengths. The primary "stray" path was through the VHF transmitter to P/J2P16 (see Figure 3-5) while the path in the spacecraft was through the VHF Receiver to P/J2P12&14. The primary fact of this test was that there was no significant difference between PCM telemetries grounded at TB2 and ACS telemetries grounded at P/J2P10. This showed there was little difference in line drops from P/J2P16 and TB2 and from P/J2P11 and TB2 (normal unipoint return).

BIT shorts were also made to PSM relay returns, which connect to P/J2P12&14, same as the VHF Receiver. These caused a shift of -3m V/Amp in ACS telemetry, but none in PCM telemetry.

In the spacecraft, a straight-line fit on the ACS telemetry (shifted during the transient) gives a value of about +0.5 V shift at the time the reg bus current indicated a shift of about +0.625 V.

This gives 0.125 V difference at 3mV/amp for 42 amperes. The resistance of chassis to PCM through the VHF Receiver is about $15\text{m}\Omega$, and the total PCM/Chassis resistance is between 3 and $5\text{m}\Omega$. This would cause between 1/3 and 1/5 of the current to go through the receiver, so the total would be between 126 and 210 amps. As a double check, 210 amps through $3\text{ m}\Omega$ or 126 amps through $5\text{m}\Omega$ would give 630 mV, which match the regulator bus shift.

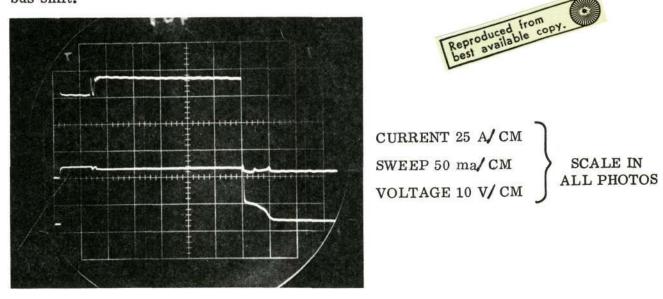


Figure 3-2. Short to Chassis

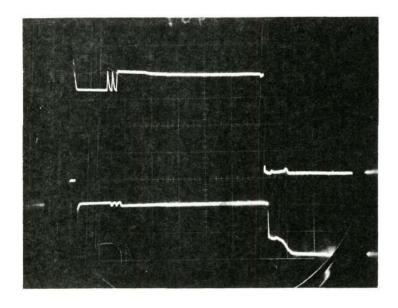


Figure 3-3. Short to RSM Relay Return



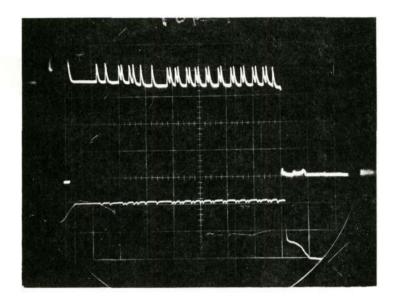


Figure 3-4. Short to Payload Return

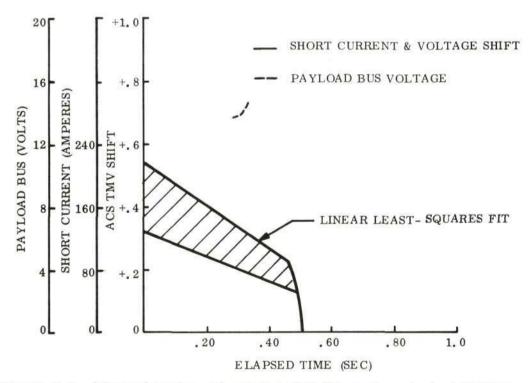


Figure 3-5. ACS Telemetry, Current and Voltage Transient at RBV Turn-on

REACTIVATION SIMULATION

4.1 GENERAL

A series of tests involving PSM BR-20 relays, RBV-Leach relays and the S/C power supply were conducted at GE. The Leach relays and the S/C power supply were utilized in a test simulating the reactivation of the RBV. The purpose of the test was to determine if the Leach relays could withstand several operations of closing the S/C power supply into a short circuit with the battery taps open (see Figure 4-1). This would simulate a worst case reactivation if a short circuit existed within the RBV system. Two Leach relays were tested separately in the circuit with each contact being subjected to 10 closures into a short circuit. With the battery taps open the current was limited to approximately 20 amps supplied by the PRM. The photograph shown in Figure 4-2 represents a typical current draw through the contacts.

4.2 RESULTS AND CONCLUSIONS

Both relays operated normally throughout the test. At the conclusion of the test the relays were submitted to failure analysis and all contacts were examined with the following results.

- 1. L1 Contacts bright and clear no degradation (see Figure 4-3).
- 2. L2 Small central spot of descoloration on all eight contacts. Evidence of localized surface material transfer no welding (see Figure 4-4).

From the test with Relay L-2 (used contacts), it was concluded that if a short circuit exists internal to the RBV at the instant of reactivation (with battery taps open), the Leach relay will not be welded or permanently disabled and the RBV may be turned off.

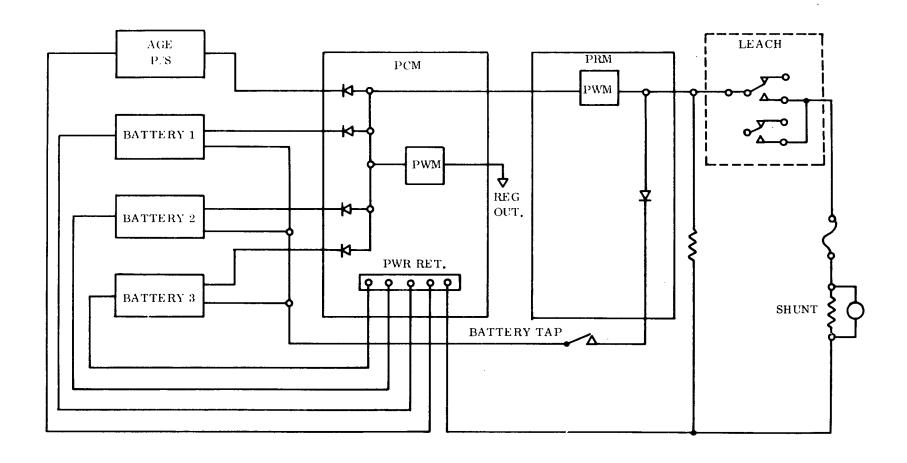


Figure 4-1. Reactivation Simulation Test Schematic

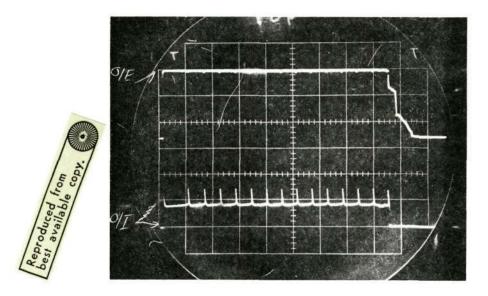


Figure 4-2. Photograph Showing Typical Current Drawn Through Contacts

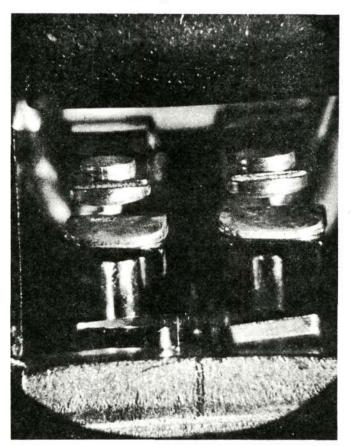


Figure 4-3. Relay L1 - Used Contacts

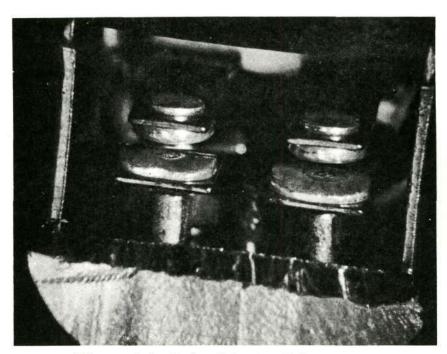


Figure 4-4. Relay L2 - Used Contacts





PHILADELPHIA

REV. LTR. SEQUENCE NO. PROGRAM CLASS, LTR. OPERATION 759 U 1J83 NE PIR NO

PROGRAM IN	FORMATION REQUEST / RELI	EASE *use "c" for cla	*USE "C" FOR CLASSIFIED AND "U" FOR UNCLASSIFIED					
	J. Becek NE Subsystem Engineer	TO P. Jone NE Elec	es c. System Engineer					
DATE SENT	DATE INFO. REQUIRED	PROJECT AND REQ. NO.	REFERENCE DIR. NO.					
5/28/70		Nimbus E						
SUBJECT								
COMMA	ND CLOCK COMMAND EXECUT	ION COUNTER UPDATING						
INFORMATION	REQUESTED/RELEASED							

Introduction

During the course of Nimbus D integration and test, a number of command executions failed to occur. Eleven of these were considered to be related to the command subsystem. In three of these instances the command execution counter did not update, so the problem was considered to be related to the transmission link. In the remainder of the command failures, the counter did update (5 times) or its status was indeterminate (3 times). The problem was not considered serious due to its infrequent occurrence and the reason for the updates without command executions was never satisfactorily established.

Conclusions and Recommendations

A number of reasons for the counter updates were postulated, but were not able to be backed up by evidence:

- 1) Failure for a relay to pull in
- Harness intermittant 2)
- Matrix driver failure 3)
- Short driving pulse 4)
- Improperly coded command 5)
- Improperly decoded command
- 7). Erroneous counter update.

The first four reasons were not very likely due to the random nature of the failures and the ability to successfully retransmit the same command immediately after the failure. The fifth reason implies computer program error since transmission bit errors are not likely to pass the command clock's error criteria; and a program error would be expected to show up more frequently. This left the last two reasons as the most likely possibilities. An investigation by Calcomp revealed that a timing race was present between the incoming command data and the internal command clock timing which could result in the same command being executed twice with the loss of a second realtime This is not considered a serious problem in either the Nimbus IV command clock or in future units since all command executions are verifiable by Digital B telemetry or status changes and a missed command can easily be re-transmitted. Therefore, no design changes are recommended.

	PAGE NO. A RETENTION REQUIREMENTS				
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Discussion

The command execution counter in the command clock is comprised of six flip-flops which are triggered by the trailing edge of the monostable multivibrator pulse which drives the matrix driver amplifiers. Therefore, an update of the counter indicates that a command (not necessarily the correct one) was decoded and the matrix driver amplifiers were triggered by the monostable. It does not determine whether or not a command pulse actually left the command clock.

There is a 100 kHz master clock signal in the command clock which is used for internal timing. This signal is derived from the 3.2 MHz master oscillator and is asynchronous with any incoming command data. It is used to establish a "T-counter" which consists of a series of 10-usec pulses counted from 1 to 50. When a realtime external command is received and decoded, the fiftieth (last) strobe pulse is OR'd with the T2 pulse to activate a gate (L-gate). The L-gate sets a shift control flip-flop in the comdec and matrix decoder which permits the shifting of the nine bits of command data from the comdec to a command register in the matrix decoder. shifting takes place at a 100 kHz rate on bit times T3 through T11, when the shift control flip-flops are reset to permit no more data to shift. The L-gate also fires the monostable which turns on the MA and MB drivers selected by the data in the matrix decoder command register and creates a matrix busy term which feeds back and inhibits the L-gate and clear the comdec. The monostable pulse is nominally 40 msec wide and the drivers are gated on by the Tll term, indicating the proper data has been shifted into the command register. The trailing edge of the monostable is used to update the command execution counter.

Since the incoming data strobe and the T-counter are asynchronous, it is possible for the L-gate pulse width to vary from 0 to 10 usec. If portions of the gate derived from the 128 bps data strobe became true just as the T2 portion was preparing to go false, a very narrow pulse would result. This pulse could fire the monostable but not set the flip-flops, which require a finite time at their inputs. This would result in execution and counting of the previous command which still occupies the matrix decoder command register.

Calcomp demonstrated the above in a laboratory test using a breadboard matrix and a controlled L-gate. This test showed that pulses less than 50 nanoseconds wide would fire the monostable but not set the shift control flip-flops. The problem could be prevented by synchronizing the T2 term to the L-gate or by creating the matrix busy feedback term with the monostable firing and the setting of the flip-flops. Either approach would involve a design change and is not considered necessary since the problem affects only realtime commands which are monitored.

The above satisfactorily explains the problems observed during Nimbus D I&T, but leaves some questions unanswered. Since the maximum L-gate pulse width is 10 usec (governed by the T2 term) and the minimum pulse width to set the flip-flops is 0.05 usec, it appears that in a large sample, 1 out of every 200 commands should be counted but not executed. Test data showed evidence of 1 in 10,000 (estimated total). (Note: It can be assumed that the ratio was somewhat higher than this since many commands are sent to ensure a status which already exists and their non-execution would not have been observable). Also, the above timing problem could result in the first command of a transmitted sequence being missed and the last command of the preceding transmission (which is still in the command register) being executed. If the erroneously executed command was one that changes a normally automatic S/S status, an undesired response could result. This was never observed during test. It appears that there is still a missing variable which lowers the probability of this occurrence. It is believed that further investigation by Calcomp is warrented.

APPENDIX C ERTS-1 DCS PLATFORM LISTS

GPTIGNAL FORM NO. 10 MAY 1955 EDITION GSA FPMIR (4) CFR) 101-11.8

UNITED STATES GOVERNMENT

Memorandum

TO

Distribution

DATE: December 20, 1972

FROM

J. Williamson - 430

SUBJECT:

DCS PLATFORM LISTS

REFERENCE:

Memo from ERTS DCS Engineer (Painter) to ERTS GDHS (Holmes), "Platform Activations", 15 December 1972.

The attached lists reflect the latest DCS Platform information which has been supplied to the GDHS (Reference).

Corrections or additions should be given to J. Padden, X2745.

James M. Williamson

Ássistant Operations Director

ERTS Project

CC: L. Gonzales

R. Holmes

T. Winchester (4)

(2)

E. Painter

J. Boeckel

E. Szajna

E. Crump

G. Ensor

A. Finelly

R. Stonesifer

L. Smith



--ERTS DCS PLATFORMS --SORTED BY USER ID

USER	PRO	PLAT	FORM	LAT	LONG	L&C	STUDY	VALID	USER	AFFILIATION
	REQ-	0 CT	DEC							F10-70 CARBONIA CONTROL OF 18 PROPERTY 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1
D005				41-45N	71-27h	RI	HYDR	8-31-72		
0005		6012	10					11-27-72		
	RLH	6021-		44=52N	·69=51#-	MAIN		8-31-72		
DOOS	RLH	6042	34					11-27-72		
_ • • -	RLH	_	57-				HYDR	8-31-72		-
		6101	65	.			HYDR	7-23-72		
0005		6136		43=48N	70=47W			11-07-72		
D005		6127	87	41=46N	72-40W		HYDR	8-31-72		
<u> - 5005</u>				42-34N	71=47W	MASS		11-07-72		
D005		6147	103				HYDR	7-23-72		
- 000S		6170	120	45-14N	·68 -3 9*	MAIN		11-07-72		
D005		6171	121					11-27-72		
- 0002		6201	129					11-07-72		
0005		6236	134	43=45W	71-41W			11-07-72		
0005			135	42-24N	71-13×	MASS		7-23-72		
D005		6216	142					11-27-72		
0005		6220	144				HYDR	7-23-72		-
0005		6233	155					11-07-72		
0005	RLA	6242	162		7			11-27-72		
D005		6246	166	42-15N	71-00 W	MASS		8=31-72		
0005-		6254 ·	172	47-15N	68=35w	MATRI		11-27-72 8-31-72		
D005		6271	155	47-154	00-33W	HATIA		11-07-72		
0002		6272 6273	185					11-07-72		
D005	KLH KLH	6304	187 196	44-04N	70-42"	MATRI		11-27-72		
0002	KLH	6325	213	44-04:1	10-154	LINITIA		11-27-72		
0002	RLH	6335	221					11-07-72		
0002	KLH	6345	229					11-27-72		_
0005	KLH	6335	237	42=06N	72=38w	N: V	HYDR	8-31-72		
0002		6336	238	+2=15N	71=15W		HYDR	8-31-72		_
5002	ive n		230	46-10.4	\ T-I 2 4	11422	ri j Dis	6-31-72	COUPER	ARITE ENGINEES
DQ11	LH	6374	60				HYDR	10-24-72	KEE	USN BCEANGRAPH
	···LH	- 6153	107	- Maria - T. F. a Cont 10 Street, and Cont.			HYDR	10-24-72	KEE	USN SCEANGRAPH
D011	LH	6336	222					10-24-72		USN OCEANGRAPH
1015	LH		4			MISS	HYDR	8-31-72	PREBLE	USGS+MISS
1015	Lн	6313	11			MISS	HYDR	12-15-72	PREBLE	USGS-MISS
1015	LН		15							USGS=MISS
		6J24								USGS#MISS
1015	LH	6025	21					11-27-72		
1015	LH		· 35							USSS-MISS
1015	LH	6051	41					11-27-72		
1015	LH	6036	46							USGS-MISS
1015	LH		ნე							LSGS=MISS
		6ú75								USGS-MISS
1015	LH	6137	71			MISS	HYDR	a=31-72	PREBLE	USGS-MISS

I015	LH	6110	72 -		MISS	HYDR	11-27-72	PREBLE	USGS-MISS
1015		6122	82				11-27-72		USGS-MISS
		6136	94_				8=31=72		USGS-MISS
1015		6143	99				11-27-72		USGS=MISS
					11133	HIVOR	11-6/4/6	PREDLE	
1015				The state of the s					USGS-MISS
1015		6156	118				9-22-72		LSGS-MISS
-10 15	} ≠	6232	130		-MISS	HYDR	11-27-72	PREBLE	LSGS=MISS
1015	LH	6234	132		MISS	HYDR	11-27-72	PREBLE	USGS-MISS
- 1015		6212-	-138		-HISS	HYDR	11-27-72	PREBLE	USGS-MISS
1015	LH	6230	152				11-27-72		USGS-MISS
				The ARREST CARRY CO.	MISS	HVDR	11-27-72	PRESIE	USGS-MISS
1015		6245	165				8-31-72		USGS-MISS
									USGS-MISS
1015		6257	175	•			11-27-72		USGS=MISS
		6253-							USGS-MISS
1015		6266	182		MISS	HYDR	11=27-72	PREDLE	USGS-MISS
I015	· LH	6301	- 193		MISS	HYDR	11-27-72	PRESLE	USGS-MISS
1015	LH	6303	195				11-27-72		USGS-MISS
I015			_	THE PERSON AND RESIDENCE AND ADDRESS OF MALES AND THE					USGS-MISS
1015		6327	215				8-31-72		USGS=MISS
				The second secon					USGS-MISS
1015		6347	231				11-27-72		USGS-MISS
1015		6351	533		-MISS	HYDR	11-27-72	PREBLE	USGS-MISS
1053	L H -	6020 ·	16 -	40=30N 121=15W	CALF	GEBL	8-31-72	FRIEDMAN	N USGS=WASH=DC
1023	LH	6134	68	40-30N 121-20W					N USGS-WASH-DC
NO24	ŔLн	6014	12			HYDR	12=15=72	KRIEGER	NASA-WALLOPS
NO24		6025	- 18			HYDR			
-					administration of agreement of				NASA-WALLEPS
N024		6323	19						NASA-WALLOPS
N024		6035	26			HYDR			NASA-WALLEPS
N024		6035	29			HYDR			NASA-WALLOPS
N024		60 5 0 -		er erte i dessi endoset sta ma denominari denominari espera espera		HYDR	11-03-72	KRIEGER	NASA-WALLOPS
N024	KLH	6052	42			HYDR	12-15-72	KRIEGER	NASA-WALLEPS
N024	RLH .	6,72	58			HYDR			NASA=WALLOPS
N024		6133	91			HYDR			NASA-WALLEPS
N024		- 6226	150						NASA-WALLEPS
•			_				-	_	
1024		6300	212	e de la companya del companya de la companya del companya de la co		חוות	11-09-70	KRIEGER	NASA-WALLOPS
14024	~ (A) (1)	4327		The second of th			11-00-72	KRIEGER	NASA-WALLERS
N024		6333	219			MIUK	11=05=/2	KAIFOEK	NASA-AALLOPS
		633 0	232			HYDR	12-15-72	KRIEGER	NASA=WALLEPS
NQ24		6350	240					KRIEGER	NASA-WALLEPS
N024	RLH	6375	253			HYDR	12-15-72	KRIEGER	NASA-WALLERS
N024	RLH	6431	257	<u>.</u>		HYDR	7-23-72	KRIEGER	NASA-WALLEPS
					- 140 - 140 -			-	· · · - • • · ·
1066	-LH	6006	6			HYDR	8-31-72	SCHUMAN	USGS-PHUENIX
- 1066		6016	14			HYDR	7-23-72		USSS-PHEENIX
1066		6151	105			HYDD	2-21-72		USGS-P-DENIX
1000	i ii	6160	117	24-222		コンクロ	0-03 70		
1000	11 11	6473 6473	127			11 UK	J=45=/4		USSS-PHENIX
1000	⊢ 7	6777	16/			TIUK	0-31-/2		USGS-PHEENIX
1066		0445 -	149			HYDK	3-55-15		USGS-PHOENIX
1066	LH	6251	177	34-36N 111-51W	ARIZ	HYUR	8-31-72	SCHUMAN	USGS-PHUENIX
·									
1000	LH	6007	7			HMET	9-22-72	HOFFER	COLORADO UNIV
1000	LH	6054	44			HMET	9-22-72		COLORADO UNIV
	_ `	- ' '	• •						COMPLIANCE DIATA
-402h-	[6155	109	en e	етна		10-24-72	CHEET	BATTELLE LABS
	-				5.110		-U-ET#/E	JACEI	BALLETTE TABS

-1030	~ LH ~		39			ARIZ	-			KSON ARIZ UNIV
103D	LH	6167				ARIZ				KSON ARIZ UNIV
1030 -		6351	-241			-ARIZ		-10-24-72	HENDRIC	KSON ARIZ UNIV
104D	LH	6140	. 96	-44-16N	103-47W	SDAK	AGFR	7-23-72	HELLER	USDA-CALIF
104D	LH	6175	125		103-47W			7-23-72		USDA-CALIF
104D			207		103-47W			7-23-72		USDA-CALIF
1010	B 11		_0,	, , , , , , , , , , , , , , , , , , , ,	100 1111		701	, 250,2	HEFELN	OSUA-CALIF
- 1050 -	1	606 0	+8				HVAD	-10-24-72	LIEN:DV	A 1 A 11N1 9 N/
									_	ALA UNIV
105D	Ļ	6061	49					10-24-72		ALA UNIV
	·	6105						10-24-72		ALA UNIV
1050	L	6120	80					10-24-72		ALA UNIV
105D	L	6156	110				HYDR	10-24-72	HENRY	ALA UNIV
1050	L	6154	116				HYDR	10-24-72	HENRY	ALA UNIV
-105D	L	6224	1.48				HYDR	10-24-72	HENRY .	ALA UNIV
1050	L	6255	181					10-24-72		ALA UNIV
- 105D	ī	6353	211					10-24-72		ALA UNIV
105D	_	6346	235					10-24-72	-	ALA UNIV
- 105D	Ī,	6357	239					10-24-72		
1050	-	0337	233	BA11 12700 000 00			חוטא	10-24-72	MENKI	ALA UNIV
4060		7704	074	39-80N	7/ 5/0	0000	TEAT	7-00 70	041711	
-1060 -				38-59N						NASA-SSFC
106D	LB	7737	967	38-59N	76=51 w	GSFC	TEST	7-23-72	SMITH	NASA=GSFC
• • • • • • • • • • • • • • • • • • • •	<u></u>									
	RLH	6030	24	41-02N	75-01 w	PENN				USGS-HARISEG
	KLH	6046	38			•	HYDR		-	USGS-HARISBG
1340	KLH	6157	55				HYDR			USGS-HARISBG
1340	RLH	6114	76				HYDR	8-31-72	PAULSON	USSS-HARISES
1340	RLH	6115	77	39-56N	75-11w	PENN	HYDR	8-31-72	PAULSEN	USGS=HARISEG
· 1340	RLH	6116	78	41=16N	74-47~	PENN	HYDR			USGS-HARISES
1340		6124	84	39-30N	75-34w					USGS-HARISBB
	RLH	6215	141		, 5 5					USGS-HARISBG
	KLH	6223	147	41-30N	75-35m	PENN				USGS-HARIS3G
1345		- 6227	151	72 00/1	/ 5 · 5 • K	. 614.4	-HYDR			USGS-HARISSG
1340		6275								
			189			•	HYDR			USGS-HARISBS
1340		6277	191							US35-HARIS63
1340		6306	198	40-41N	75 - 12*	PENN				USGS-HARISBG
1340		6312	505							USGS=HARIS53
1340		6322	210				HYDR	10-24-72	PAULSON	USGS-HARISBG
1340-		6331	217 -	40-42N	- 75-11w	PENN				USGS-HARIS3G
I340 (KLH	6332	218	39-41N	75=31 N	PENN	HYDR	8-31-72	PAULSON	USGS-HARISEG
I340	KLH	6341	225				HYDR	8-31-72	PAULSAN	USGS-HARIS83
1340	RLH	6343	227	40-04N	74-51 N	PENN	HYÜR	8-31-72	PAULSEN	LS3S-HARIS36
1340		6344	825	39-50N	75-22N	PENN	HYDR	8-31-72	PAULSAN	USGS-HARISES
7000	21	6357								USGS-HARISSG
-1340-	*! +	-6374			-		-110K		-	USGS-HARISEG
1340	() = ()	03/1	673				אטזה	0-31-15	PAULSON	0202#HWK1203
N347	L	6344	36				とくり 口	2-21 70	202	A A G A _ M G C
N347							HYDR	8-31-72		NASA-MSC
		6345	37				HYDR	8-31-72		NASA-MSC
		6377	63				HYDR	7-23-72		NASA-MSC
N347	<u> </u>	6112	74				HYDR	8-31-72		NASA-MSC
-N347								7=23-72		NASA=MSC
		6132	106				HYDR	8-31-72		NASA-MSC
- N347 -	. <u>L</u>	6211	137				HYDR	8-31-72	ERB	NASA-MSC
	L	6234	156				HYDR	8-31-72		NASA-MSC
N347	L	6235	157				HYDR			NASA-MSC
N347	L	6244	164				HYDR	8-31-72		NASA-MSC
									- '*	
F360 A	₹L9	6102	66				HMET	8-31-72	CAMPRELL	-9NTARIO
							(() ()	0.314/5		- JNIARIU

F360	RLB	6126	86	50=38N 1	17-03W	BC	HMET	8-31-72	CAMPBELL	-ONTARIO
F360	RLS	6137	95	30 3311 3			HMET		CAMPBELL	
		-6150		59-23N-1	08-53W-	SACK		-8-31-72		
F360	RLA	6232	154	J- 45.4 1	.03.35%	UASK	HMET		CAMPBELL	
		—626 0		61-52N-1	21-21-	Niw T	_		CAMPBELL	
	RLB			. 61-254.1	CIASIM	1414 .				
		6353	235	24-0431 4	40-65-3	5.0	HMET		CAMPBELL	
—F360			236		18-05W	BC			CAMPBELL	
F360	KLO	6356	246				HMET	8-31-72	CAMPBELL	-9NTARIO
				_				-	communication of the second contraction of the second contract con	AND SUPERIOR OF SUPERIOR STATE OF THE STATE
F368	RL	6270	184	46-52N	71-39W	QUEB	HMET	8-31-72	PERRIER	RESBURCES = QUE
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1378	L	6144	100							USGS-LOUISANA
1378	·· ··· <u>L.</u>	6237	159				-HYDR	11-08-72	CANERON	USGS-LOUISANA
				•						
-1380		6 063-	5 1 -	42-40N	70-54W-	MASS		-11-27-72	KNBX	USGS-BUSTON
			_	-						
I-381	L	6037	31				HYDR	10-24-72	RARNES	USGS-NASHVILE
1381		6203	131					10-24-72		USGS-NASHVILE
.001		0233	101				HIUN	10-24-72	DANNES	02020 142011 155
1382		(26)	4 (: -	to a first think of more own own own when a mean				10.0/. 30		U500 00508N
1305	L	6254	180					10-24-72	KAPUISKA	USGS-BREGON
***		(00-							~ . =	
1384	LH	6005	5				GEOL	8-31-72		USGS-CALIF
I-384		6J11 -	9	· · · · · · · · · · · · · · · · · · ·				9-22-72		USGS-CALIF
I384	LH	6334	28				GEOL	9=22-72		USGS-CALIF
I384	L ₩	- 6036 ·	3O	1 10 10 10 10 10 10 10 10 10 10 10 10 10			GEOL	10-24-72	EATON	LSGS-CALIF
I384	LH	6343	35				GEUL	8-31-72	EATON	USGS-CALIF
I384	L H	6057	47				SEGL	8 = 31 = 72	EATEN	USGS-CALIF
1384	LH	6056	54				GEOL	7-23-72		USGS-CALIF
1384			67-		**************************************			8+31-72		USGS-CALIF
1384	LH	6117	79				GEOL	10-24-72		USGS-CALIF
1384		6132.						10-24-72		USGS + CALIF
1384	LH	6154	108				GEOL	9-22-72		USGS-CALIF
1384							GEUL.			USGS-CALIF
1364	LH	6163	115				GESL	9-62-72		
1384		6176	126							USGS-CALIF
							_	8-31-72		USGS-CALIF
I384	LH	6213	139				GEUL	8-31-72		USGS-CALIF
1384		6245	160				· ·	10-24-72	I I .	USGS-CALIF
1384		6247					GEUL	9-22-72		USGS-CALIF
<u>-</u> 384-	L 	6262	-178-				GEBL	9-22-72	EATUN	USGS-CALIF
1384	LH	6274	158				GEEL	10-24-72	EATON	USGS-CALIF
I384	·· LH	6276 -	190				GEUL	9-22-72	EATON	USGS-CALIF
I384	LH	6311	201				GEBL	10=24=72	EATON	LSGS-CALIF
1384	LH	6315	205-			44	GEBL	8=31=72	FATEN	USGS-CALIF
1384	LH	6320	208				GEUL	8-31-72	EATEN	USGS-CALIF
1384		6334	. 220-	e er de diene nammen de produktein eller (A. N. Nap.), das 12 augste	FF Westerland Mary Inches with product		3FBL	9=22-72	FATEN	USGS-CALIF
										USGS-CALIF
1364		- 6 - 6 -	245				GEAL	2-21 72	EATEN	
1364		6375	243				3561	8-31-72	EATON	USGS-CALIF
1304	<u></u> ⊑ ⊓	6370	250				CEUL	10-51-72		USGS-CALIF
1.384	F. H		550 ·				GEUL	10=24=72	EAIDN	USGS-CALIF
•			- · -				. 15.5 =	4.4		
13 90		640 2-	- 258				HYDR	10-24-72	BEAMER	USGS+HARIS8G
						_				
1414	KLH	6031	25			FLA -	HYDR	7-23-72	HIGER	USGS=MIAMI
I414	RLH	6533	27			FLA	HYDR	8-31-72	HIGER	USGS=MIAMI
· I+14	RLH	6005	+5		. "	FLA	HYDR	12-15-72	HIGER	USGS-MIAMI
1414	RLH	6070	56			FLA	HYDR	8-31-72	HIGĒR	USGS-MIAMI
I-414	KLH-	6121	6 1· ·			FLA	HYUR	12-15-72	HIĞER	USGS-MIAMI
1414	RLH	6141	97			FLA	HYDR	6-31-72	hluER	USGS-MIAMI
			•				-	· -		= + - + + + + + + + + + + + + + + + + +

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		6210								
F501	RL	6555	146	·		HMET	8-31-72	ZUBRYCKY	FISH-OTTAWA	4
F 5 08	- RLO	6135	93+3-	17N -79-08W	BNT	-HMET-	8=31=72	MACPHAIL	IN-WATER-ON	11
F503	RL	6330 -	216			HMET	8-31-72	VOCKEROTE	TING-SEMTA	
P550 P550		7000 7001		05N 75-23W 05N 75-23W			7-23-72 7-23-72		GE-VF GE-VF	
P568 P568	L	6373 6373	59 251		VIRG -VIRG				TITRE CORP-V	
U661 U661		6131 6310	89 200		KANS KANS				KSU-KANSAS KSU-KANSAS	
ST6	P 0									
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GSFC=430 12=20=72

ERTS DCS PLATFORMS SORTED BY DCP ID

				S	BRTED BY	DCP	10			the state of
PLAT OCT	FORM	USER	PRO REG	LAT	LONG	LBC	STUDY	VALID	USER	AFFILIATION
6000	0	•		and the second						
6001	1									
6002	į							and the second s		AND SHOW THE RESIDENCE OF SHIP AND ADDRESS OF
6003	3									
6004	4	1016	LH			MISS	HYDR	8-31-72	PREBLE	USGS-MISS
6005	5	1384	LH			,,,,,,	GEBL	8=31=72		USGS-CALIF
6006	ó	1366	LH				HYDR		SCHUMAN	USGS-PHSENIX
6007	7	1000	LH				HMET	9-22-72		COLORADO UNIV
6010	á	2002	RLH	41=45N	71=27W	RI	HYDR	8-31-72		ARMY ENG-MASS
6011	9	1364	LH	4110.11	11.51.	,	GEBL	9-22-72		USGS-CALIF
6012	10	2002	RLH					11-27-72		ARMY ENG MASS
6013	11	1015	LH			MISS		12-15-72		USGS-MISS
6014	12	N024	RLH			11430		12-15-72		
6015	13	11024	10=11				777 6213	100/6		***************************************
6015	14	1366	LH				HYDR	7-23-72	SCHUMAN	USGS=PHBENIX
6017	15	1315	LH			MICS	HYDR	8-31-72		USGS-MISS
6020	16	1353	LH	40-30N	121-154					N USGS-WASH-DC
6021	17	0005	RLH	44-52N	09#51W	MAIN		8-31-72		ARMY ENG-MASS
9055	18	N324	RLH	7: 56.11	05 51		HYDR		KRIEGER	
6023	19	N324	RLH					11-08-72		NASA-WALLEPS
6024	50	1015	LH			MISS		11-27-72		LSGS-MISS
6025	51	1015	LH					11-27-72		USGS-MISS
6026	55	1012	Cr,				,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			0040 4100
6027										
6030	23	1345	RLH	41-02N	75=01W	DENIN	HYDR	7-23-72	PAULSON	USGS-HARISBG
6031	24 25	1414	RLH	41-0514	12-71W	FLA	HYDR	7-23-72		USGS+MIAMI
	2¢	N324	RLH		ı	, mv	HYDR		KRIEGER	NASA-WALLEPS
6032 6033	27	I414	RLH			FLA	HYDR	8-31-72		USGS=MIAMI
6034	25	1384	LH			r LA	GEUL	9-22-72		USGS-CALIF
6035	29	N024	RLH					12-15-72		NASA= NALLOPS
6036	30	1384	LH				GEGL	10-24-72		USGS-CALIF
	31	1361	L					10=24=72		USGS-NASHVILE
6037	35	1315	ΓH			MICS		11-27-72		USGS-MISS
6040	33	1912	<u> </u>			11133	11101	11-2/4/2	, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	0300-1123
6041			2, 4	•			HVND	14-27-72	CARDED	ARMY ENG MASS
6042	34	7305	RLH					8=31=72		USGS=CALIF
6043	35	1384	LH					8-31-72		NASA-MSC
6044	36	N347	L					8-31-72		NASA-MSC
6045	37	N347								USGS-HARISBG
6046	3 o	1345	RLH			A 2 7 7				CSGN ARIZ UNIV
6047	39	1030	LH Blil			ARIZ				NASA-WALLEPS
6050	4 O	N324	RLH			MICC				NASA-WALLERS USGS-MISS
6051	41	1015	LH			U122				
6052	42	N024	RLH				HTUK	15-12-15	KKIEUEK	NASA-WALLEPS
6053	43	400=	1 1 1				Line Promite	0-00 70	HAPPE	COLONIA IN TO
6054	44	1000	LH			FLA		9=22=72 12=15=72		COLORADO UNIV USGS-MIAMI
6055	45	1414	RLH			FLA	MIUN	75-10=/5	H136K	09334 JI W.J.I

6056 6057	46 47	I015 I384	LH LH			MISS	GEBL	8-31-72	EATUN	USGS-MISS USGS-CALIF
6060	48	1050	. L				HYDR			ALA UNIV
6061	49	1050	L				HYDR			ALA UNIV
6062	50	1015	ĻH	. 0 . 6 6 51	.	MISS	HYDR			USGS-MISS
6063	51	1380	L	42-40N	70-54W	MASS		11-27-72	KNOX	USGS#B8ST8N
6064	52				*		-			
6065	5 3	_								
6066	54	1384	LH				-GEOL	7-23-72		USGS-CALIF
6067	55	1340	RLH				HYDR			USGS-HARISBG
6070	56	1414	RLH			FLA	HYDR	8-31-72	HIGER	USGS-MIAM!
6071	57	SOCO	RLH				HYDR	8-31-72	COUPER	ARMY ENG-MASS
6072	58	N324	RLH				HYDR	8-31-72	KRIEGER	NASA-WALLOPS
6073	59	P568	L			VIRG		10-24-72	GREELEY	
6074	60	311 كان	LH				HYDR			SN GCEANGRAPH
6075	61	IJĨŜ	LH			MISS		11-27-72		USGS-MISS
6076	62								.	
6077	63	N347	L				HYDR	7-23-72	ERA	NASA-MSC
6100	64		- .						2 .10	MAN PAGE
6101	65	DOOZ	RLH				HYDR	7-23-72	CASPER	ARMY ENG-MASS
6102	66	F360	RLB				HMET		CAMPBELL	
6103	67	1384	LH				GEBL	8-31-72		USGS-CALIF
6104	68	1023	Ľн	40-30N	121-20W	CALF				N USGS-WASH-DC
6105	69	1050	L			• · · • · ·	HYDR	10-24-72		ALA UNIV
6106	70	2000	RLH	43=48N	70=47W	NH	HYDR	11-07-72		ARMY-ENG-MASS
6107	71	1015	LH	70 (0.1	75.471	MISS	HYDR	8-31-72		USGS-MISS
6110	72	1015	LH					11-27-72		USGS-4155
6111	73	• • • • •	— 1,			11133	MIUN	11-5/4/5	PAREELE	0202-4122
6112	74	N347	L				HYDR	0-04 70	E D C	1.1C1 VCC
6113	75	11347	_				חזטת	8=31=72	ERB	NASA-MSC
6114	75 76	1340	RLH				HYDR	0-24 72	DAIH CON	1:000 HAD 1000
6115	77	1340	RLH	39-58N	75-44	DENIN		8-31-72		USGS-HARISBG
6116	78	I345	RLH		75-11W		HYDR			USGS-HARISEG
6117	79	1384		41-16N	74-47W	PENN	HYDR			USGS-HARISEG
6120	80 80	1350	ĻH				GEGL	10-24-72		USGS-CALIF
	-		L		•	. .	HYDR	10-24-72		ALA UNIV
6121 6122	81 82	1414 1015	RLH LH			FLA	HYDR	12-15-72	HIGER	USGS-MIAMI
6123	83	1019	∟ ⊓			W122	אטזה	11-27-72	PREBLE	USGS-MISS
6124	84	1340	RLH	39+30N	75-04	DENIN.	. IVA B	7 22 72	5 4 11 66	
6125	85	N347		33#3UN	75=34×	PENN				LSGS-HARISBG
6126	85		F	27.0 3 5 N	447 00	2.0	HYDR			NASA-MSC
6127	87	F360	RLO		117-03W		HMET		CAMPBELL	
6130	88 88	SOCU	КLН	41-46N	72-40W	CANN	HYDR	8=31=72	COOPER	ARMY ENG-MASS
6131	89		1 14							
6132	90	US61 1384	LH			KANS	0001		-	KSU-KANSAS
6133			LH Dist	•				10-24-72		USGS-CALIF
	91	N324	RLH				HYDR	12-15-72	KRIEGER	NASA-WALLOPS
6134 6135	93 93	E=^~	ω:	. 3 - 4 3 -	70 - 2	e 		.		
		F502	RLU	43-17N	79-08W		HMET			. IN WATER-BUT
6136	9+ 95	1015	LH			MISS	HYDR	_		USGS-MISS
6137	95 97	F360	RLB				HMET			
5140	96	1040	Lm	44-16N	103-474			7-23-72		USDA-CALIF
6141	97	I414	RLH			FLA	HYDR	3-31-72		LSGS-MIAMI
6142	98	٥٥٥٥	RLH	42-34N	71-47W			11-07-72		ARMY ENG-MASS
6143	99	1015	LH			MISS		11-27-72	PREBLE	USGS-MISS
6144	100	1378	L				HYDR	11-08-72		USGS-LOUISANA
6145	101								-	
6146	102									
6147	103	2000	RLH				HYDR	7-23-72	COSPER	ARMY ENG-MASS
C . 0								· • • • • • • • • • • • • • • • • • • •		, ((); , ,)U m(//UU

6150 6151 6152	104 105 106	F360 I366 N347	RL0 LH	59-23N	108=53W	SASK	HYDR	8-31-72		USGS-PHBENIX:
6153	107	0011	.LH	and the second s	****		HYDR	8-31-72 10-24-72		NASA#MSC Sn bceangraph
6154	108	I384	LH				GEUL			USGS-CALIF
6155	109	1020	L		-	9118	GEUL	10-24-72		BATTELLE LABS
6156	113	1350	Ĺ				HYDR	10-24-72		ALA UNIV
6157	111	1015	Lн			MISS		11-27-72		USGS-MISS
6160	112				to a secondary a constant of the second					
6161	113									
6162	114	1384	LH				GEBL	7-23-72	EATON	USGS-CALIF
6163	115	1384	LH				GEUL			USGS-CALIF
6164	116	1950	L				HYDR	10=24-72		ALA UNIV
6165	117	1066	LH	•			HYDR		SCHUMAN	
6166	110	1015	LH			MISS	HYDR			USGS-MISS
6167	119	1030	LH			ARIZ	_			KSON ARIZ UNIV
6170	120	0002	RLH	45-14N	68=39w	MAIN		11-07-72		ARMY ENG MASS
6171	121	DOOS	RLH				HYDR	11-27-72	COGPER	ARMY ENG 4ASS
6172	122									
6173	123									
6174	124	10:0			400-67	C 5 A 1/4	4000	7-00 70	1351 L ED	1.004.04.15
6175 6176	125 126	104D 1384	LH LH	44-101/	103=47W	SUAK	GEBL			USDA=CALIF USGS=CALIF
6177	127	1366	LH				HYDR		SCHUMAN	
6200	128	1000	∟ ⊓				HIDN	0-31-72	SCHOLAN	DOGGENIX
6201	129	DOOZ	RLH			•	HYDR	11-07-72	CASPER	ARMY ENG-MASS
6202	130	1015	LH			MISS		11-27-72		USGS-MISS
6203	131	1381	L			.,,		10-24-72		USGS-NASHVILE
6204	132	1015	LH			MISS		11-27-72		USGS#MISS
6205	133									
6206	134	SCCU	RLH	43-45W	71-41 w	NH		11-07-72		ARMY-ENG-MASS
6207	135	20CÚ	RLH	42-24N	71-13W	MASS		7-23-72		ARMY ENG-MASS
6210	136	F461	RLU				HMET	8-31-72		FISH=STTAWA
6211	137	14347	L				HYDR	8=31-72		NASA-MSC
6212	136	1015	LH			MISS		11-27-72		USGS-MISS
6213	139	1384	LH			.	GEÓL	8=31=72		USGS-CALIF
6214	140	1414	RLH			FLA		12-15-72		USGS-MIAMI
6215	141 142	1340 0002	RLH							USGS-HARISEG
6216 6217	143	چ ن ن ن	ŘLH				חנטת	11-5/4/5	COUPER	ARMY ENG MASS
6550	144	SOCU	RLH				HYDR	7=23=72	COOPER	ARMY ENS+MASS
6221	145	N324	RLH							NASA=WALLOPS
6222	146	F501	RL				HMET	8-31-72	ZUBRYCKY	/ FISH=UTTAWA
6223	147	1340	RLH	41-30N	75-05W	PENN	HYDR	8-31-72	PAULSON	USGS-HARISBG
6224	148	1050	L					10-24-72		
6225	149	1066	LH				HYDR	9-22-72	SCHUMAN	LSGS-PHUENIX
6226	150	M324	RLH							NASA-WALLOPS
6227	151	1340	RLH							USGS-HARISBG
6230	152	1015	LH			MISS	HYDR	11=27=72	PREBLE	USGS-MISS
6231	153	r 🤜 -	231				. 1845 =	0 54 5-		
6232	154	F360	RLU					8-31-72		
6233	155	0002	RLH					11-07-72		ARMY ENG-MASS
6234	156 157	N347	L				HYDR	8-31-72		NASA-MSC
6235	157 158	N347 I414	L			E 1 A		8=31=72		NASA-MSC
6236 6237	150	1414 1378	RLH L			FLA		8-31-72		USGS=MIAMI USGS=LYUISANA
6240	160	13/8	LH					10-24-72		USGS=LYUISANA USGS=CALIF
6241	161	1015	LH			MISS				USGS-MISS
0 E 4 I		• 4 7 7	- 1							0349-11139

4000	4 . 0		CM							
6242	162	2002	RLH			•	HYDR	11-27-72	COOPER	ARMY ENG MASS
6243 6244	163	N347					UVAB	9-34 70		1.454
	164 165		<u> </u>			HIOO	HYDR			NASA-MSC
6245 6246	166	1015 2002	LH KLH	42=15N	74-00-0		HYDR			USGS-MISS
6247	167	1384	LH	45-1914	71=00W	MASS	GEBL			ARMY ENG-MASS
6250	168	1414	RLH			FLA	HYDR			USGS-CALIF
6251	169	1015	LH		· · · · · · · · ·		HYDR	-		USGS-MIAMI
6252	170	1414	RLH					8-31-72 12-15-72		USGS-MISS
6253	171	1414	NED	,,		- PLA	HIUK	15-12-15	HIGER	USGS-MIAMI
6254	172	DODE	RLH				HYDR	11-27-72	CARPED	ARMY ENG MASS
6255	173		.,_,,				,,,,,,,,,	11,-2/4/2	COUPER	ARIT ENG MASS
6256	174	1414	RLH			FLA	HYDR	8=31=72	HIMED	USGS-MIAMI
6257	175	1015	LH			MISS		11-27-72		USGS=MISS
6260	176	F365	RLU	61-52N	121-21W			8-31-72		L =5NTARI8
6261	177	1366	LH		111-51w					USGS-PHBENIX
6262	178	1384	LH	3	***************************************	N.1.2.	GEOL			USGS-CALIF
6263	179	1015	LH			MICC		11-27-72		USGS-MISS
6264	180	1382	L.			114.50	1:10:1			A USGS-GREGEN
6265	181	1050	Ĺ				HYDR	10-24-72		ALA UNIV
6266	182	1015	LH			MISS		11-27-72		USGS-MISS
6267	183		_			,			1 1 to 60 to 50	0040-1103
6270	184	F368	RL	46=52N	71=39w	QUEB	HMF T	8-31-72	PERRIER	RESOURCES-QUE
6271	185	DOOZ	RLH	47-15N	68-35W	MAIN	HYDR			ARMY ENG+MASS
6272	186	SOCO	RLH					11-07-72		ARMY ENG MASS
6273	187	DODE	RLH					11-07-72		ARMY ENG-MASS
6274	186	1364	ĽН					10-24-72		USGS-CALIF
6275	189	1345	RLH					10-24-72		USGS-HARISES
6276	190	1384	LH				GEEL	9-22-72		USGS-CALIF
6277	191	1340	RLH					10-24-72		
6300	192									
6301	193	1015	LH			MISS	HYDR	11-27-72	PREBLE	USGS-MISS
6302	194									,
6303	195	1015	LH			MISS	HYDR	11-27-72	PREBLE	USGS-MISS
6304	196	0002	RLH	44-04N	70-12W	MAIN	HYDR	11-27-72		ARMY-ENG-MASS
6305	197	M324	RLm				HYDR	8-31-72		NASA-WALLEPS
6306	198	1340	RLH	40-41N	75-12m					USGS-HARISBG
6307	199	1715	LH				HYDR	12-15-72		USGS-MISS
6310	200	U561	LH		\$40.5°	KANS		10-24-72	KANEMASL	J KSU-KANSAS
6311	201	1384	LH					10-24-72		USGS-CALIF
6312	505	1340	RLH			_				USGS-HARISBG
6313	203	1414	RLH			FLA	HYDR	12-15-72	HIGER	USGS-MIAMI
6314 6315	204 205	120.	1 4.				05.51		m + m /	
		1384	LH				GEBL	8-31-72	EATON	USGS-CALIF
6316	206	1 2	1 1 .		400 : =	4 1.50			<u>.</u>	
6317	207	1340	Lh	44=16N	103-47h	SDAK		7-23-72		USDA-CALIF
6320 6321	208 208	1384 1414	LH			. .		8-31-72		LSGS=CALIF
6322	215	1340	RLH			FLA		8-31-72		USGS-MIAMI
6323	211	13#0 1350	RLH L							USGS-HARISEG
6324	212	N324	RLH			•		10-24-72		ALA UNIV
6325	213	2005	RLH							NASA-WALLEPS
6326	214	0002	NEM				HTUK	11-27-72	COUPER	ARMY ENG MASS
6327	215	1315	LH			MICO	JVOD	0-04 30	D D C = 1 =	
633)	216	F503	RL			MISS		8-31-72		
6331	217	1340	RLH	40-42N	75-440	DD KINE				H ATM95-BNT
6332	215	1345	RLH	39-41N		DEL C	7 A V D	0-31-/2	PAUL SEN	USGS-HARISBG USGS-HARISBG
6333	219	NO24	RLH	32 - 41W	12-21M	LEVA				
	- • •	- 					חוטא	11-00-15	アメイロロデス	NASA-WALLEPS

6334	250	1384	LH				GEOL	9-22-72	EATON	USGS-CALIF
6335	221	2000	RLH				HYDR	11-07-72	COUPER	ARMY ENG-MASS
6336	555	0011	LH							SN OCEANGRAPH
6337	553	1015	LH			MISS	HYDR	11-27-72	PREBLE	USGS-MISS
6340	224			,						
6341	552	1340	RLH				HYDR			USGS-HARISBG
6342	556	1384	LH		_		GEOL			USGS-CALIF
6343	227	1340	RLH	40=04N						USGS-HARISBG
6344	258	1340	KLH	39-50N	75-22N	PENN				USGS-HARISBG
6345	559	2000	RLH					11-27-72		ARMY ENG MASS
6346	230	1050	L					10-24-72		ALA UNIV
6347	231	1015	LH		•	-		11-27-72		USGS-MISS
6350 6351	535	N324	RLH		-	 MICC				NASA-WALLOPS USGS-MISS
6352	533	1015	LH			M122	ATUK	11-27-72		02324 1132
6353	234 235	F365					UMET	8-31-72		
6354	236	F360	RLO RLO	21-01N	118-05W	D C		8=31=72		
6355	237	0302	RLH	42-06N	72=38W		HYDR	8-31-72	CHUPER	ARMY ENG-MASS
6356	238	2005	RLH	42-15N	71=15W		HYDR	8-31-72		ARMY ENG-MASS
6357	239	1350	L	,	, 1 10			10-24-72		ALA UNIV
6360	240	N024	ŔĹĦ	· er						NASA-WALLEPS
6361	241	133D	LH			ARIZ	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,			KSON ARIZ UNIV
6362	242	1414	RLH			FLA	HYDR	12-15-72		USGS=MIAMI
6363	243	1414	KLH			FLA		12-15-72		USGS-MIAMI
6364	244									
6365	245	1384	LH		•		GEGL	8-31-72	EATON	USGS-CALIF
6366	246	F360	RLO				HMET	8-31-72	CAMPBELL	-SNTARIO
6367	247	1340	RLH				HYDR	8=31=72	PAULSON	USGS-HARISSG
6370	246	1384	LH				GEOL	8=31=72		USGS-CALIF
6371	249	1340	RLH				HYDR			USGS-HARISBG
6372	250	1384	ĽН				GEGL	10-24-72		USGS-CALIF
6373	251	P368	L			VIRG		10-24-72	GREELEY	MITPE CORP-VA
6374	252	١.٥٥.	C3				HMDD	40 45 30	or for the end.	
6375	253	M324	RLH				HYDK	12-15-72	KRIEGER	NASA=WALLOPS
6376	254									
6377 6400	255 256									
6401	257	N024	RLH				HYDR	7=23-72	ZRIFGER	NASA-WALLEPS
6402	258	1395	L							USGS=HARISEG
6403	259		-				.,, .			OUGO MAN.
6404	260									
6405	261									
6406	262									
6407	263									
7000	512	P555	Lö	40-05N	75-23W	PENN	TEST	7-23-72	W88D	GE-VF
7001	513	მანე		40-05N				7-23-72		GE-VF
7701	961	1960		38-59N				7-23-72		NASA-GSFC
7707	967	1060	LS	38-59N	76-51 W	GSFC	TEST	7-23-72	SMITH	NASA-GSFC

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6334 6335	220	1384	LH RLH		•			11-07-72	COUPER	USGS-CALIF ARMY ENG-MASS
6336 6337 6340	222 223 224	0011 1015	LH			MISS		10-24-72 11-27-72		SN BCEANGRAPH USGS-MISS
6341 6342 6343	225 226 227	1345 1384 1340	RLH LH RLH	#0-24N	74=51W	DENIN	HYDR	8-31-72	EATON	USGS-HARISBG USGS-CALIF USGS-HARISBG
6344 6345	558 558	1340	KLH RLH	39-50N	75-22N		HYDR HYDR	8-31-72 11-27-72	PAULSON COUPER	USGS-HARISBG ARMY ENG MASS
6346 6347 6350	230 231 232	1050 1015 N024	L LH RLH	•		MISS	HYDR	10-24-72 11-27-72 12-15-72	PREBLE	ALA UNIV USGS=MISS NASA=WALLOPS
6351 6352 6353	233 234 235	1015 F360	LH RLÖ		er e er a nam same e en	MISS	HYDR	11-27-72	PREBLE CAMPBELI	USGS-MISS
6354 6355	236 237	F360 0002	RLG RLH	42-06N	118=05W 72=38W	NY	HMET HYDR	8=31=72 8=31=72	CAMPBEL!	-9NTARIO ARMY ENG-MASS
6356 6357 6360	238 239 240	1002 1050 N024	KLH L KLH	45-12N	71=15w		HYUR	8-31-72 10-24-72 12-15-72	HENRY KRIEGER	ARMY ENG-MASS ALA UNIV NASA-WALLOPS
6361 6362 6363	241 242 243	1030 1414 1414	LH RLH RLH			ARIZ Fla Fla		10=24+72 12=15=72 12=15=72	HIGER	KSON ARIZ UNIV USGS=MIAMI USGS=MIAMI
6364 6365 6366	244 245 246	1384 F360	LH RL6				GEBL HMET	8-31-72		USGS-CALIF
6367 637ე	247 246	1345 1384	RLH LH				HYDR GEOL	8=31=72 8=31=72	PAULSON EATON	USGS-HARISAG USGS-CALIF
6371 6372 6373	249 250 251	1345 1384 Pä68	RLH LH L			VIRG	HYDR GE6L	10-24-72	EATON	USGS-HARISBG USGS-CALIF MITRE CURP-VA
6374 6375 6376	252 253 254	N024	RLH				HYDR	12-15-72	KRILGER	NASA-WALLOPS
6377 6400 6401	255 256 257	N)24	RLH				HVDB	7=23-72	∠ p ieneo	NASA-WALLBPS
6402 6403 6404 6405	258 259 260 261	1395	L							USGS-HARISEG
6406 6407 7000 7001	262 263 512 513	P553 P353	Ľβ	40=05N				7-23-72		GE=VF
7701 7707	961 967	1960 1960	Γġ	40-05N 38-59N 38-59N	76-51 W	GSFC	TEST	7=23=72 7=23=72 7=23=72	SMITH	GE=VF NASA=GSFC NASA=GSFC

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ERTS DCS PLATFORMS SORTED BY USER AFFILIATION

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- USER ID	PROD REG	PLAT UCT	FORM DEC	LAT	LONG	Lec	STUDY	VALTD	USER	AFFILIATION	
104D	LH	6140	96	44=16N	103-47W	SDAK	AGFR	7-23-72	HELLER	USDA-CALIF	
1040	LH	6175	125	44-16N	103-47W	SDAK	AGFR	7-23-72		USDA-CALIF	
104D	LH	6317	207	44-16N	103-47%	SDAK	AGER	7-23-72	HELLER	USDA-CALIF	
0005	RLH	6010	8	41-45N	71-27N	RI	HYDR	8-31-72		ARMY ENG-MASS	
D002		6012	10					11-27-72		ARMY ENG MASS	
D005	RLH	6521	17	44-52N	69-51W	MAIN	HYER	ä=31-72		ARMY ENG-MASS	
0002	RLH	6342	34					11-27-72		ARMY ENG MASS	
0005	KLH	657 <u>1</u>	57				HYDR	8-31-72		ARMY ENG-MASS	
0005	RLH	6101	65				HYDR	7-23-72		ARMY ENG-MASS	
0005	RLH	6106	75	43=46N	70=47×			11-07-72		ARMY-ENG-MASS	
0005	ALH	6127	67	41=46N	72-404		HYDR	8-31-72 11-07-72		ARMY ENG-MASS ARMY ENG-MASS	
0005	KLH	6142	98	42-34N	71-474	MASS		7-23-72		ARMY ENG-MASS	
2005	RLH	6147	103	= 4 // 8/	68-39W	MATN	HYDR	11-07-72		ARMY ENG MASS	
0005	RLH	6170	120	45-14N	00-324	HAIN	HYDR			ARMY ENG MASS	
0005	RLH	6171	121 129				HYDR			ARMY ENG-MASS	
0002	RLH	6201	134	43=45w	71=41 w	K:l⊒i		11-07-72		ARMY-ENG-MASS	
D005	KLH KLH	6236 6237	135	42-24N	71=13w		HYDR	7-23-72		ARMY ENG-MASS	
0002	RLH	6216	142		71-131	IIAGO		11-27-72		ARMY ENG MASS	
0002	RLH	6220	144				HYDR	7-23-72		ARMY ENG-MASS	
5005	RLH	6233	155				HYDR			ARMY ENG-MASS	
2002	RLH	6242	162					11-27-72	COUPER	ARMY ENG MASS	
D005	KLH	6246	166	42-15N	71-00W	MASS	HYUR	8-31-72		ARMY ENG-MASS	,
0005	KLH	6254	172	_			HYDR	11-27-72	CHUPER	ARMY ENG MASS	
Doos	KLH	6271	105	47-15N	68-35W	MAIN		ò=31=72		ARMY ENG-MASS	
2002	スレ ュ	6272	106					11-07-72		ARMY ENG MASS	
2002	KLH	6273	167					11-07-72		ARMY ENG-MASS	
0005	スレエ	63)4	196	44=04N	70-124	MAIN		11-27-72		ARMY-ENG-MASS	
U 002		6325	213					11-27-72		ARMY ENG MASS	
0002		6335	221					11-07-72			
Doos		6345	229	0.0(1	70.05			11=27-72			
0005		6335	237		72=38W			8=31=72			
0005	KLH	6336	238	42-15W	/1-10W	HASS	HIUK	0.31.4/5	COUPER	ARMY ENGTHAGS	
0011	LH	6,74	6ე					10-24-72		ISN OCEANGRAPH	
0011	LH	6153	107					10-24-72		ISN GCEANGRAPH	
D011	LH	6336	555				HYDK	10=24=72	KEE (JSN BCEANGRAPH	
N024	al a	6014	12				HYÜR	12-15-72	KRILGER	RASA-WALLOPS	
NO24		6022 0014	18					-		RASA-WALLEPS	
NUCH	13 = 17	2022	7.0								

N024	ם ופ	6023	19							11-08.73	KOTECED	. 464 411.50
N024	RLH	6032	26						HYDR	11-00-72	KRIEGER	NASA-WALLOPS Nasa-Wallops
N024	RLH	6035	29							1 12-15-72	VAIE GEV	NASA-WALLEPS
NO24	RLH	6050	45						HYDR	11-08-72	KDIEGER	NASA-WALLOPS
N024	RLH	6052	42							12-15-72	KBIEGER	NASA-WALLOPS
NO24	RLH	6072	58						HYDR			_
NO24	RLH	6133	91						HYDR			
NO24	RLH	6221	145				•		HYDR			
NO24	RLH	6226	150								KRIEGER	NASA-WALLEPS
N024	RLH	63)5	197						HYDR	6-12-12-72	KRIEGER	NASA-WALLEPS
NO24	RLH	6324	212								KRIEGER	
NO24	RLH	6333							- MYDK	11-08-72	KRIEGER	NASA-WALLEPS
			219							11-08-72		
N024	RLH	633 0	535						HYDR			
N024	RLH	635g	240						HYDR			
N024	RLH	6375	253		•			******		12-15-72		
N024	RLH	6431	257		-				HYDR	7-23-72	KRIEGER	NASA=WALLOPS
N347	L	6044	36						HYDR		ERB	NASA-MSC
N347	L	6045	37						HYDR	8-31-72	ERB	NASA=MSC
N347	L	6377	63						HYDR			NASA-MSC
N347	L	6112	74						HYDR			NASA-MSC
N347	L	6125	85						HYDR			NASA-MSC
N347	L	6132	106			•			HYDR			NASA-MSC
N347	L	6211	137						HYDR			NASA-MSC
N347	L	6234	156						HYUR			NASA-MSC
N347	Ī	6235	157						HYDR			NASA=MSC
N347	Ĺ	6244	164						HYDR			
		- La	104				•		אטוא	8-31-15	END	NASA-MSC
1015	LH	6334	4						HYDR			USGS-MISS
1015	LH	6013	11					MISS		12-15-72		US35-4135
1015	LH	6017	15						HYDR			USGS=MISS
1015	LH	6524	20					MISS		11-27-72		USGS=MISS
1015	Ŀн	6025	21						HYDR			USGS=MISS
1015	LН	6040	32					MISS	HYDR	11-27-72	PREELE	USGS-MISS
1015	ĻН	6031	41					MISS	HYDR	11-27-72	PREBLE	USGS-MISS
1015	LH	6,56	46					MISS	HYDR	9-22-72	PREBLE	USGS-MISS
1015	LН	6052	50					MISS	HYDR	11-27-72	PREBLE	USGS=MISS
1015	LH	6075	61							11-27-72	-	USGS=4135
1015	LH	6137	71						HYDR		PREBLE	USGS-MISS
1015	LH	6110	72					MISS	HYDR	11-27-72		USGS-MISS
1015	LH	6122	62							11-27-72		USGS-MISS
1015	LH	6136	94							8=31=72		US3S-415S
1015	LH	6143	99							11-27-72		USGS-MISS
1015	LH	6157	111							11-27-72		USSS-MISS
1015	LH	6156	118							9-22-72		US3S=MISS
1015	LH	6232	130							11-27-72		US\$5-4188
1015	LH	6234	132							11-27-72		USGS-4155
1015	LH	6212	158							11-27-72		US3S-4155
1015	Ľн	6230	152							11-27-72		US35-4135
1015	LH	6241	161							11-27-72		US35-7155 US35-7155
1015	LН	6245	165					MICC	HADB	8=31-72		US35=MISS US35=MISS
1015	LH	6251	169						HYDR			USGS=MISS
1015	LH	6257	175	4								
1015	LH	6253	179	•	•					11-27-72		USGS-MISS
1015	LH	6256	102							11-27-72		LSGS-MISS
1015	LH	6301	193							11-27-72		USGS-MISS
1015	LH	6303								11-27-72		US35-4188
1015	LH		195							11-27-72		LSGS-MISS
.010	□ □	6337	199					MISS	HYDR	12-15-72	PREBLE	USGS-MISS

* ^		1		24-			H160	HVAD	0-01 73	nacate	USGS-MISS
10		LH	6327	215			MISS				
10		LH	6337	223					11-27-72		USGS-MISS
IO	15	LH	6347	231	and the supplemental and the second and		MISS	HYDR	11-27-72	PREBLE	USGS-MISS
10		LH	6351	233					11-27-72		USGS-MISS
- 0	•		0001					111011			
10	22	1	(035		# O - 3 o M	404 - 450	C 41 E	CESI		EDIEDMAN	N USGS-WASH-DC
10		LH	6020	16	40=30N	121-15W	CALF	GEGL			
10	23	LH	6104	68	40-30N	121=20W	CALF	GEBL	8-31-72	FRIEDMAN	N USGS-WASH-DC
-10	66	LH	6006	. 6				HYDR	8-31-72	SCHUMAN	USGS-PHBENIX
Io		LH						HYDR			USGS-DHBENIX
			6016	14							USGS-PHOENIX
ΙQ		LH	6151	105				HYDR			
Ιo	66	LH	6155	117				HYDR	9-22-72	SCHUMAN	USGS-PHBENIX
Io	66	LH	6177	127		to see a consider a		HYDR	8-31-72	SCHUMAN	USGS-PHBENIX
10		LH	6225	149				HYDR	9-22-72	SCHUMAN	USGS=PHBENIX
- 10		LH	6261	177	34-38N	444-546	A C 1 7				USGS-PH8ENIX
10	00	- 11	0231	1//	3443614	111-51"	NN12	THUN	0.21415	GGRIGHT	0000 117021121
• -		5 1					~~			D. 4.1.11. C.O.3	1 000 11 010
	_	RLH	6030	24	41-02N	75=01 W	PENN				USGS-HARISBG
13	40	RLH	6546	38				HYDR	8-31-72		USGS-HARISEG
13	40	RLH	6057	55			•	HYDR	8=31=72	PAULSEN	USGS-HARISÒG
	4a	RLH	6114	76				HYDR		PALL SAN	USGS-HARISBG
_	_				39-58N	75 - 11×	DELA				USGS-HARISSG
13	_	RLH	6115	77	-						
13		KLH	6116	78	41=16N	74-47					USGS-HARISBG
13	40	RLH	6124	ŏ4	39-3UN	75-34W	PENN				USGS-HARISSS
13	4 0	RLH	6215	141				HYDR	10-24-72	PAULSON	USGS-HARISBG
13		RLH	6223	147	41-00N	75-35 M	PENIN				USGS-HARISBG
	_			_	41-0011	75-5511	7 601414	HYDR			USGS-HARISBG
	40	RLH	6227	151							
13		RLH	6275	109	•	•		HYDR			USGS-HARISEG
13	40	RLH	6277	191				HYDR			USGS-HARISBG
13	40	RLH	6306	198	40-41N	75-12×	PENN	HYDR	8-31-72	PAULSON	USGS=HARIS8G
13		RLH	6312	202				HYDR	10-24-72	PAULSON	USGS-HARISEG
13		ŔĿН	6322	210				HYDR	10-24-72	PAULSON	USGS-HARISBG
			6331	217	40=42N	75-11 W	DENIN		8-31-72		USGS-HARISES
13	_	KLH	_	_	•						USGS-HARISEG
13	_	KLH .	6332	218	39-41N	75-31 W	PEININ				
13	4 O	RLH	6341	225				HYUR			USGS-HARISEG
13	40	RLH	6343	227	M+C=0+	74=51 N					USGS-HARISEG
13	40	RLH	6344	228	39-50N	75-22N	PENIN	HYDR	8-31-72	PAULSON	USGS-HARIS53
	40	RLH	6357	247				HYDR	8-31-72	PAULSEN	USGS-HARISEG
_	_		6371								USGS-HARISES
13	70	KLH	03/1	249				HYUN	0-21-15	FACEDUIT	0303-HAN1330
									44	C. UEDAN	
13		L	6144	100							USGS-LOUISANA
13	78	L	6237	159				HYDR	11=08=72	CAMERSN	USGS-LUJISANA
13	80	L	6053	51	42-40N	70-54W	MASS		11-27-72	KN8X	USGS-BUSTON
• •	0	_	-0	- 4		, 5					
	_			٥.				11455	10-04 70	SADNES	11000 NA 01141 F
13		L	6037	31			•				USGS-NASHVILE
13	81	L	6203	131	•			HYDR	10-24-72	BARNES	USGS-NASHVILE
	-										
13	c 2	L	6£54	150					10-24-72	KAPUTSKA	USGS-UREGON
• •	0.	-	•=-	-00							
• •			/ c a =	_				0501	0-04 70	CATER	1 C C C A 1 T T
13		ĻΗ	6005	5					8+31-72		USSS-CALSF
13		LH	6011	9					9-22-72		USGS-CALIF
13	84	LH	6034	28					9-22-72		USGS=CALIF
13		LH	6036	30				GEBL	10-24-72	EATON	USGS-CALIF
13		LH	6043	35					8-31-72		US3S-CALIF
13		LH	6 ₀ 57	47					8-31-72		USGS-CALIF
13		LH	6,56	54					7-23-72		LSGS-CALIF
13	64	LH	6103	67				ü E Ö L	_		USGS-CALIF
13	ö 4	LH	6117	79				GEOL	10-24-72	EATON	USGS-CALIF

13844 1384 13884 1		6132 6154 6162 6163 6176 6217 6217 6217 6215 6315 6331 6334 6342	90 108 114 115 129 160 178 190 105 100 100 100 100 100 100 100 100 10				GEOLL GEOLL GEOLL GEOLL GEOLL GEOLL GEOLL	10-24-72 9-22-72 7-23-72 9-22-72 8-31-72 9-22-72 10-24-72 9-22-72 10-24-72 8-31-72 8-31-72 8-31-72	EATON EATON EATON EATON EATON EATON EATON EATON EATON EATON	USGS-CALAF USGS-CALIF
1384	LH	6355	245				GEOL	8-31-72		USGS-CALIF
I384	LH	637 ე	248				GEOL	8-31-72		USGS-CALIF
1384	LH	6372	250				GEOL	10-24-72	EATUN	USGS=CALIF
1390	L	6432	258			, ,	HYDR	10=24-72	BEAMER	USGS-HARISBG
I414	RLH	6531	25			FLA	HYDR	7-23-72	HIGER	USGS-MIAMI
-	RLH	6033	27			FLA	HYDR	8-31-72		USGS-MIAMI
1414		6035	45			FLA		12-15-72	HIGER	USGS-MIAMI
	RLH	6070	56			FLA	HYDR	8=31-72		USGS-MIAMI
1414	RLH	6121	81			FLA	HYDR	12-15-72		LSGS-MIAMI
1414	RLH	6141	97			FLA	HYDR	8=31=72		USGS-MIAMI
I414	KLH	6214	140			FLA	HYDR	12-15-72		LSGS=MIAMI
I414	RLH	6236	158			FLA	HYDR	8-31-72		USGS-MIAMI
I414	RLH	6250	168			FLA	HYDR	8-31-72		USGS-MIAMI
I414 I414	RLH RLH	6238 6236	170 174			FLA	HYDR	12-15-72		USGS-MIAMI
I414		6313	203	•		FLA	HYDR	8-31-72		USGS-MIAMI
1414	RLH	6321	203			FLA	HYDR	12-15-72 8-31-72		USSS=MIAMI USSS=MIAMI
I414	RLH	6352	242			FLA	HYDR	12-15-72		USGS=MIAMI USGS=MIAMI
I414	スレイ	6353	243			FLA	HYDR	12-15-72		USGS=MIAMI
4114	11-11		243			FLA	HIUN	15-12-15	HIGER	0202+WI WWI
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* (JNIVER	SITIES								
*			#							
		*****	***							
USER	PROD REU	PLAT	DEC DEC	LAT	LƏNG	LOC	STUDY	V VALTD	USER	AFFILIATION
1050	L	605ე	48				HYDR	10-24-72	HENRY	ALA UNIV
1050	L	6551	49					10-24-72		ALA UNIV
1050	L	6105	69					10-24-72		ALA UNIV
1050	L	6120	60					10-24-72		ALA UNIV
1050	L	6156	115					10-24-72		ALA UNIV
1050	L	6154	116					10-24-72		ALA UNIV
105D	L	6224	148					10-24-72		ALA UNIV
1050	Ļ	6255	181					10-24-72		ALA UNIV
1050	L	6353	211					10=24=72		ALA UNIV
1050	L	6346	230				HYER	10-24-72	HENRY	ALA UNIV
1050	L	6357	239				HYUR	10-24-72	HENRY	ALA UNIV

103D 103D	LH LH	6047 6167	39 119			ARIZ ARIZ				KSON ARIZ UNIV	
1030	LH	6351	241			ARIZ				KSON ARIZ UNIV	
100D 100D	ŁH LH	6007 6054	7				HMET HMET	9-22-72 9-22-72		COLORADO UNIV	
U661 U661	LH LH	6131 6310	89 200			KANS		10-24-72 10-24-72		U KSU-KANSAS U KSU-KANSAS	

#										engen over en	
*	FOREI	GN *							contract of the second		
***	*****	*****							•		
ID	PROD Reg	PLAT UCT	F8RM DEC	LAT	LONG	LOC	STUDY	VALID	USER	AFFILIATION	
F360		6102	66				HMET	8-31-72	CAMPBEL	L -BNTARIB	
F360		6126	86	50-38N	117-03W	ЭC	HMET		CAMPBELL		
F360 F360		6137 6150	95 1 0 #	59-304	430=#3	CACK	HMET		CAMPBELL		
F360		6535 6130	104 154	53#E3N	108-53W	SASK	HMET		CAMPBELL		
F360		6250	176	61-52N	121-21 W	NWT	HMET		CAMPBELL		
F360		6333	235		1-1 -1	. , , , ,	HMET		CAMPBELL		
F360	RLB	6354	236	51-01N	118-05W	BC	HMET	8-31-72	CAMPBELL		
F360	RLb	6356	246				HMET	8-31-72	CAMPBELL	-ONTARIO	
F368	RL.	6270	184	46=52N	71-39W	GUEB	HMET	8=31=72	PERRIER	RESOURCES-QUE	
F461	RLB	6210	136				HMET	8-31-72	KRUUS	FISH-BTTAWA	
F501	RL	6222	146				HMET	8-31-72	ZUBRYCK	Y FISH-STTAMA	
F502	RLB	6135	93	43-17N	79-08w	BNT	HMET	8-31-72	MACPHAIL	IN WATER-ONT	
F503	RL	6330	216		•		HMET	8-31-72	VƏCKERDI	TH ATMOS-ONT	
****	****	****									
* * F	PRIVATE	*									
*	NATOL	<u>.</u> #									
USER ID	PROD KEG	PLAT		LAT	Leng	LUC	STUDY	VALID	USER	AFFILIATION	
106D 106D	La	7701 7707	961 967	38=59N 38=59N				7-23-72 7-23-72		NASA-GSFC NASA-GSFC	
P550 P550	La	7000 7001	512 5 ₁ 3	40=05N 40=05N				7-23-72 7-23-72		GE-VF GE-VF	
P568 P568	L	6073 6373	59 251			VIRG VIRG	;	10-24-72 10-24-72	GREELEY GREELEY	MITRE CORP-VA	

ST8P 3

APPENDIX D

ERTS-1 FLIGHT HARDWARE OPERATING TIME SUMMARY

* Extracted from consolidated configured articles list, issued July 7, 1972. **Extracted from quality assurance LOS books.

Subsystem	Module	S/ N*	Test Hours**
G	Cleak	FT-1	1895
Command	Clock VHF Receiver	02	2536
	CIU	6549450	2523
	Cit		
VIP	Digit Mux	0004	2439
	Reprogrammer	0004	2439
	Analog Mux	0003	2504
	Memory Sequencer	0004	2557
	Memory A/B	0005/0007	2567
D	S/C Domilator	007	2549
Power	S/ C Regulator	008	2542
	P/L Regulator	65 49313	2526
	Aux Load Cont		297
	Aux Load Panel 1	6549311 6549288	297
	Aux Load Panel 1	37	2418
	Battery 1	38	2818
	Battery 2		
	Battery 3	41	2407
	Battery 4	35	2405
	Battery 5	34	2419
	Battery 6	39	2385
	Battery 7	36	2418
	Battery 8	33	2418
	ISM	EAB-FT-1	2535
	PSM	6549500	2459
RBV	RBV Elect 1	007	230
	RBV Elect 2	005	221
	RBV Elect 3	006	217
	RBV Camera 1	007	230
	RBV Camera 2	005	221
	RBV Camera 3	006	217
	CCC	004	306
		6549512	206
	Mag. MOM Comp	6549512	200
MSS	MSS Scanner System	1	270
	MSS Multiplexer	2	270
	MSS Scanner	1	270
		Donata	940
WBVTR	WBVTR Elect 1	Proto	268
	WBVTR 1 (T/T)	Proto	268
	WBVTR 1 (R/P)	Proto	126
en e	WBVTR Elect 2	FT-3	88 90
	WBVTR 2 (T/T)	FT-3	
	WBVTR 2 (R/P)	FT-3	45
OA	OA	FT-1	
	SOL 1	Fir	ings - 54
	SOL 2		52
	SOL 3		50
ADVI	APU	6549503	1861
APU	APO	004000	
Narrowband Telemetry	Beacon Transmitter	0003	2250
	NBTR 2	EAB-FT-1	1437
	NBTR 1	EAB-FT-2	1370
	USBE	EAB-FT-2	177
	PMP	FT-1	2354
	mr. a	05.40045	000
Thermal	TM Conv Mod 3	6549315	2365
	TM Conv Mod 1	5962964	2359
	TM Conv Mod 2	5962965	2358
Unfold	Unfold Timer	5962963	12
DCS	DCS A	FT-4	370
	DCS B	FT-5	256
WBTSS	WBPA 1	QM-1	468
	WBPA 2		474
	WBPS	6549509	597
	WBFM	6549506	586
	WB Output Filter 1	3	168
	WB Output Filter 2	6	178
4.00		7777 00	1000
ACS	Right SAD	FT-03	1800
	Left SAD	FT-02	1035
	Yaw Rate Gyro	FT-2	327
	RMP "A"	FT-02	725
	RMP "B"	FT-03	743
	Logic Box	FT-1	2500
	Scanner No. 1	FT-2	2500
	Scanner No. 2	FT-6	1344
	Timer	005	2315
	Pitch Flywheel	706 003	1773
	Yaw Flywheel	908 005	2315
MMCA	MMCA	FT-1	15
AMS	AMS	FT-1	1094

Table 1. ERTS-1 Flight Hardware Operating Time Summary as of 23 July 1972